

# 100 IDEAS FOR DESIGN

No. 3

**ELECTRONIC  
DESIGN**

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## Foreword

This is the third volume in the series, "100 Ideas for Design." As in the previous volumes, we have selected 100 of the best items that appeared during the past year in the "Ideas for Design" section of ELECTRONIC DESIGN. These have been grouped by category for easy reference.

The continued popularity of the "Ideas for Design" section is very gratifying, although not surprising. After all, the electronic design engineer is an originator as well as a user of ideas. The almost 1,000 ideas we have published since we started the section some eight years ago have been useful and -- we feel -- have given rise to many new ideas as well.

The volume starts with the \$1,000 award-winning "Idea of the Year." Details of the award competition appear on the inside back cover. Why not submit your idea? You might be the winner next year.

Incidentally, Volumes I and II are in their third printing and are available as outlined on the inside back cover.

**Edward E. Grazda**  
Editor

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# Idea of the Year

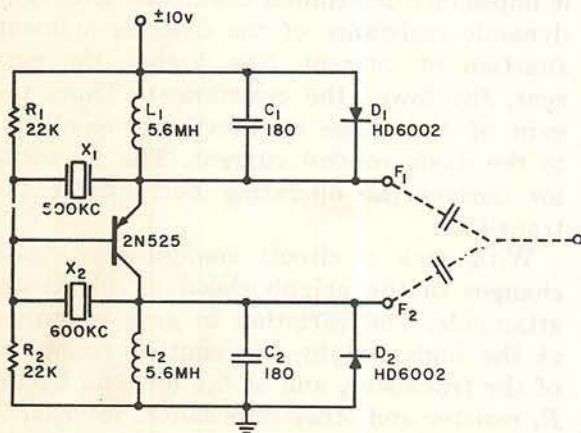


*ELECTRONIC DESIGN'S 1962 Idea of the Year Award of \$1,000 was presented to John M. Tewksbury, principal engineer, Bendix Radio Div., The Bendix Corp., Avionics Products, Baltimore, Md.*

*His idea, reproduced here, was selected by the editors of ELECTRONIC DESIGN as the most useful and interesting of those published in the Ideas for Design section of the magazine during the year.*

## Bilateral Crystal Oscillator Has Two-Frequency Output

The bilateral characteristics of the transistor come into play in this two-frequency crystal oscillator. Either of the two frequencies may be selected by applying plus-or-minus voltage to the supply terminal.



Either of two oscillator frequencies can be obtained by reversing polarity of supply voltage.

When plus voltage is applied, the current flows through  $D_1$  to the emitter of the transistor. Tuned circuit  $L_2C_2$  and crystal unit  $X_2$  then become active and an output is derived from  $F_2$ . The  $L_1C_1$  network is shorted out by diode  $D_1$  and crystal  $X_1$  is connected between base and emitter where there is no gain to promote oscillation in this unit.

With minus voltage applied to the supply terminal, the transistor operates in the "inverted" mode. Effectively, the collector becomes the emitter and vice versa. In this case, oscillations are generated by  $L_1C_1$  and crystal unit  $X_1$ . Output voltage will be delivered at output terminal  $F_1$ .

If desired, two additional capacitors (shown by dashed lines) may be added to provide a single output terminal.

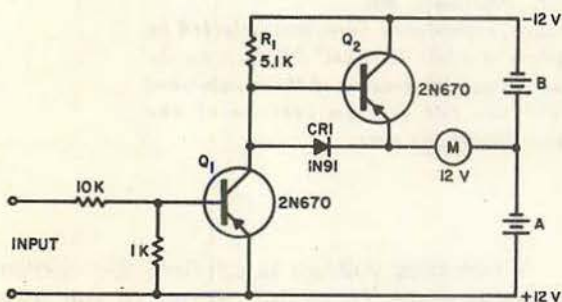
Diodes  $D_1$  and  $D_2$  limit the output to 0.7-v rms. Since the transistor is operating in an oscillator circuit the beta of the inverted mode need only be sufficient to produce oscillation. Therefore, it is not necessary to use selected bilateral transistors in this application. This circuit can be used to select frequencies from a remote point by electrical means. Since it uses a single transistor, there is a saving in components.

# AMPLIFIERS

## DC-Servo Amplifier Has Single-Ended Drive

In driving a small dc motor in a servo loop it is sometimes desirable to have a single-ended input. Here is an amplifier that affords high voltage gain and high input impedance.

When the input voltage (or current) is sufficient to cause  $Q_1$  to conduct, it first cuts off  $Q_2$  and then conducts through  $CR_1$ . The motor thus is connected to supply A, causing rotation in one direction. When the input is



Input-signal level biases  $Q_1$  or  $Q_2$  on to connect required battery polarity to motor.

reduced,  $R_1$  will bias  $Q_2$  on and the current through the motor is then in the opposite direction, through supply B. Voltage amplification is provided by  $Q_1$ , and  $Q_2$  is an emitter follower that makes possible equal drive torque in each direction. This circuit has been successfully used to provide follow-up in a low-voltage power supply to reduce series regulator dissipation.

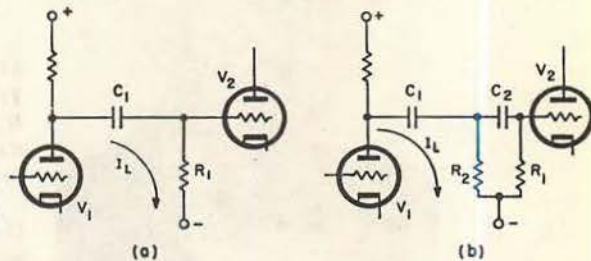
Richard L. Shaum, staff associate, Sandia Corp., Albuquerque, N. M.

## Double Coupling Capacitors Avoid Leakage Current

Here's an amplifier coupling scheme that can be quite valuable, particularly when the coupling is over several thousand volts as in cathode ray tubes.

In the commonly used arrangement, Fig. 1a, the leakage current of capacitor  $C_1$  flows through resistor  $R_1$ . This can cause an appreciable shift in the bias on the following stage  $V_2$ .

But, when  $C_2$  and  $R_2$  are added, as in Fig. 1b, the leakage current of  $C_1$  is largely blocked by  $C_2$ . Instead of flowing through  $R_1$ , the leakage flows through  $R_2$  and the bias on  $V_2$  is not shifted.



Extra coupling capacitor  $C_2$  in (b) blocks leakage current of  $C_1$  from affecting bias of following stage  $V_2$ .

E. R. Roeschlein, electronic engineer, U. S. Naval Avionics Facility, Indianapolis, Ind.

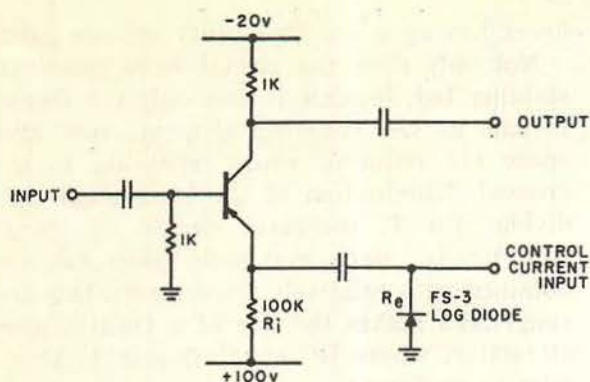
## Variable-Gain Amplifier Has 40-Db Range

Gain of the circuit to be described is controlled by the current flowing through a log diode. The diode is the dynamic emitter resistance ( $R_e$ ) and its dynamic impedance determines the circuit gain. The dynamic resistance of the diode is a linear function of current (the higher the current, the lower the resistance). Thus, the gain of the stage is directly proportional to the diode control current. The  $R_1$  resistor derives the operating current for the transistor.

With such a circuit configuration, gain changes in the neighborhood of 40 db are attainable. The variation in gain is limited at the high end by the emitter resistance of the transistor, and at the low end by the  $R_1$  resistor and other impedances internal to the transistor.

Such a circuit is limited to small signal operation due to the nonlinear diode characteristic.





Current through log diode controls gain of amplifier stage.

Log diodes can also be placed across the collector resistor and base resistor to affect gain. It is anticipated that the gain of a single video coupler can be varied more than 70 db with triple diode control.

Robert W. Cope, project engineer, Bendix Radio Div., The Bendix Corp., Baltimore 4, Md.

## Wien-Bridge Amplifier Has Selectivity With Stable Gain

The conventional frequency-selective feedback amplifier having a rejection filter in the feedback loop has the disadvantage that the gain of the amplifier at the center frequency is equal to the forward-path supply voltage, and tube parameters.

The circuit shown in Fig. 1 is an adaptation of the Wien-bridge frequency-rejection network. It is driven by a split-load bridge driver in series with an amplifier. The amplifier is connected between the cathode and grid of the bridge driver. The flow diagram satisfying Fig. 1 is shown in Fig. 2. From this diagram amplifier gain at center frequency can be obtained by  $R_2/(R_1 + R_2)$ . Gain at frequencies far from the center frequency will be:

$$\frac{R_2}{R_1 + R_2} \frac{1}{1 - A \frac{R_1}{R_1 + R_2}} \quad \text{or} \quad \frac{R_2}{R_1(1 - A) + R_2}$$

where  $A$  is the gain of  $V_2$ . Simultaneous change of  $C$  or  $R$  will provide a change of center frequency by  $1/2\pi RC$ .

A simple, inexpensive Wien-bridge frequency-selective amplifier using a triode-pentode tube is shown in Fig. 3. To avoid unbalance of the bridge, a variable resistor is

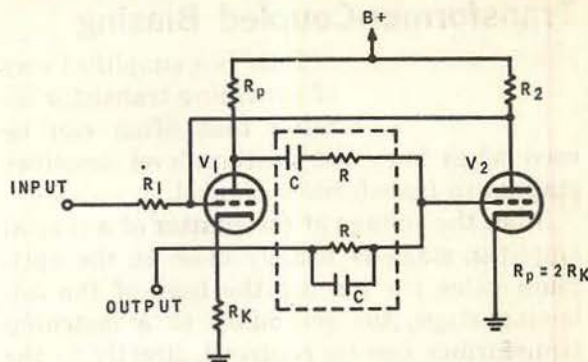


Fig. 1. Basic Wien-bridge frequency-selective amplifier.

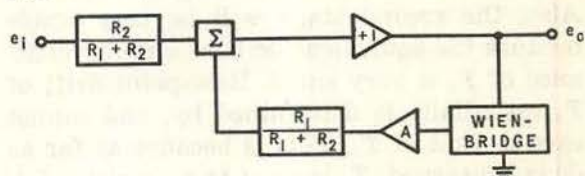


Fig. 2. Gain at center frequency can be obtained from flow diagram.

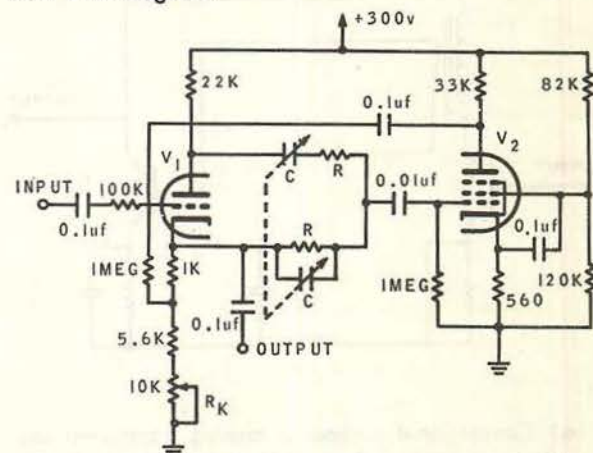


Fig. 3. Frequency-selective amplifier uses 6EA8 triode-pentode. Cathode potentiometer is used for balancing. used as  $R_k$ . For the adjustment, the feedback loop between the plate of  $V_2$  and the grid of  $V_1$  is opened at a convenient point. The  $R$  or  $C$  and the pot  $R_k$  should be adjusted to the null by applying a desired frequency signal at the input. A CRO or VTVM at the plate of  $V_2$  is used as a detector.

The test result indicated that the gain stability of the amplifier at the center frequency is very good despite large changes in the power supply voltage as well as change of tubes. The frequency-selective amplifier described can be operated up to about 500 kc.

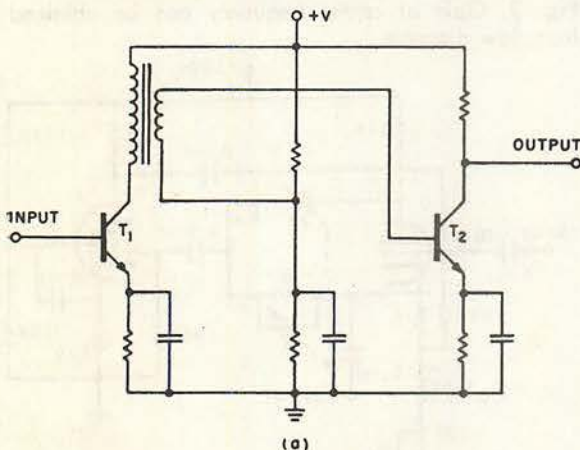
K. H. Liu, engineer, Industrial Nucleonics Corp., Columbus 2, Ohio.

## AMPLIFIERS

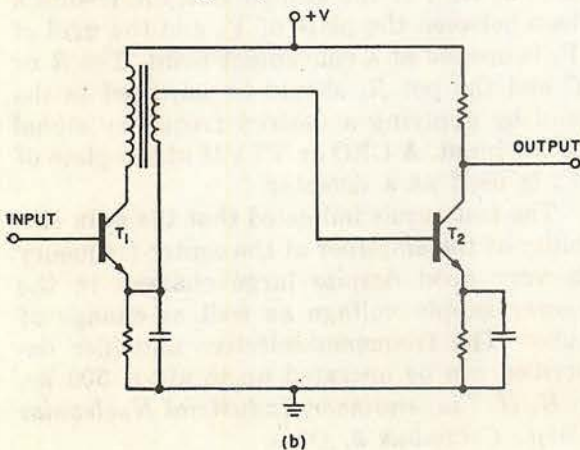
### Short-Cut Connection Simplifies Transformer-Coupled Biasing

Here is a simplified way of providing transistor biasing that often can be used when low- and medium-level amplifier stages are transformer-coupled.

Since the voltage at the emitter of a typical amplifier stage is usually close to the optimum value for biasing the base of the following stage, the secondary of a matching transformer can be returned directly to the emitter, (b). As long as the emitter of  $T_1$  is bypassed there will be no signal feedback. Also, the second stage will be very stable because the equivalent dc base circuit resistance of  $T_2$  is very small. Base-point drift of  $T_2$  essentially is determined by, and cannot exceed, that of  $T_1$ . This is because as far as dc is concerned,  $T_1$  is used as an emitter fol-



(a) Conventional method of biasing transformer-coupled stage applied dc bias to second stage through dropping resistors and secondary winding. (b) Simplified connection places bias on stage  $T_2$  directly from the emitter of stage  $T_1$ .



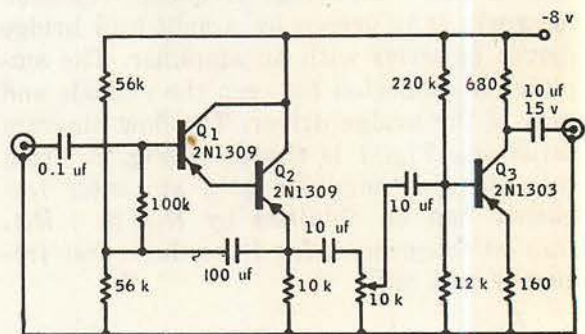
lower having a less-than-unity voltage gain.

Not only does the circuit have excellent stability but, because it uses only the transformer as the coupling element, cost and space are reduced, while reliability is increased. Elimination of the biasing voltage divider for  $T_2$  increases circuit efficiency. And finally, since maximum gain can be obtained with relatively fewer parts, this arrangement makes the use of a transformer attractive, where RC coupling might otherwise be preferred.

Maxwell Strange, electronic engineer, Goddard Space Flight Center, Greenbelt, Md.

### Low-Level Preamplifier Has High Impedance Input

A low-cost preamplifier for oscilloscopes and meters can be a real time saver in the lab. The unit employs the Darlington circuit to obtain a high input impedance. The ac input impedance is approximately equal to  $\beta^2$  times the emitter resistance of  $Q_2$ . The actual measured impedance was in excess of 2.2 megohms. With the input shorted, the noise level is down -78 db as read at the output with a VTVM. Using low-value resistors in the base of  $Q_1$  to establish the operating point provides good dc stability from 25 C to 60 C. Linearity is within 1.5 per cent from 100  $\mu$ v to 1 mv in-



Darlington low-level preamplifier has 1.5 per cent linearity with input of 100  $\mu$ v to 1 mv.

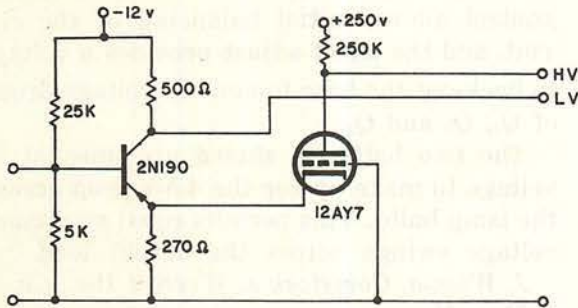
put. Frequency response is  $\pm 2$  db from 100 cps to 350 kc. The circuit shown can be readily adapted to other applications.

Edward W. Smith, Senior Engineering Technician, Texas Instruments Inc., Houston, Tex.

## Hybrid DC Amplifier Replaces Output Transformer

In a low frequency hybrid amplifier it appeared that an output transformer would have to be used to secure a higher no-load output voltage than was available at the collector of the output transistor. Because very low frequencies were involved, a transformer would have been large and expensive.

It was found simpler and better to use a grounded grid vacuum tube output stage. This gave direct coupling and unusually simple circuitry for the additional stage of amplification.



**Grounded grid vacuum** tube output stage in low frequency hybrid amplifier takes the place of bulky, expensive output transformer.

*Laurence G. Cowles, Electronic Design Engineer, The Superior Oil Co., Bellaire, Tex.*

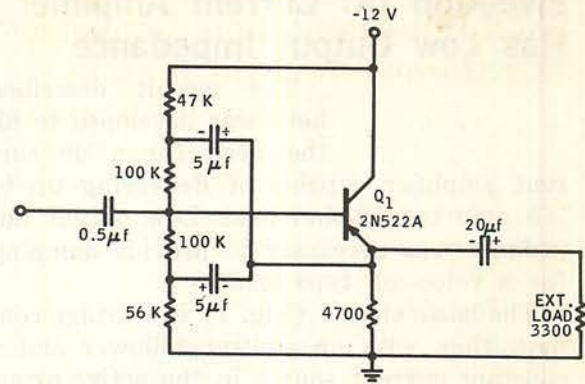
## Amplifier Design Provides 20-Megohm Input

A high-impedance transistor amplifier was needed in a metering circuit. Impedances approaching those of vtvm amplifiers were desirable to keep circuit loading to a minimum. An output voltage of 1-v rms across a 3300-ohm load and a frequency response from 10 cps to 200 kc was necessary. Figures 1, 2 and 3 show the evolution of an amplifier that more than met the requirements.

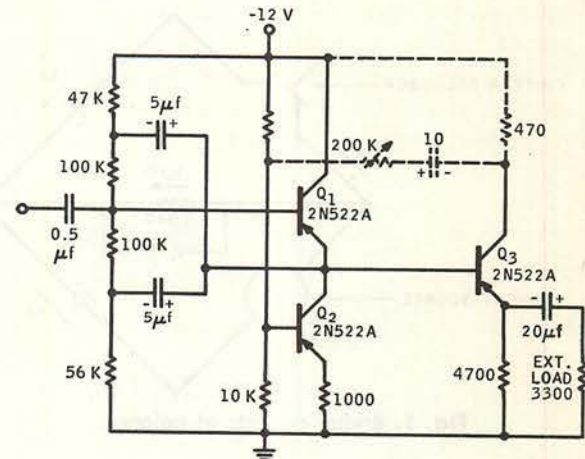
In Fig. 1, bootstrapping was used on a basic emitter-follower circuit to eliminate the shunting effect of the base-bias resistors. Using a transistor with a current gain of

approximately 100, the input impedance was measured at 200 K with a 3300-ohm load.

A significant increase in input impedance



**Fig. 1.** Basic amplifier uses bootstrap capacitors to eliminate shunting effect of base bias resistors.



**Fig. 2.** Transistor in emitter leg of  $Q_1$  and positive feedback (dashed lines) increase input impedance.

was obtained by replacing the emitter resistor of  $Q_1$  with the collector resistance of a grounded-base transistor  $Q_2$ , as shown in Fig. 2. To keep the loading as light as possible on the emitter of  $Q_1$ , an emitter follower  $Q_3$  was used to couple the load. An impedance of slightly over 1 megohm was measured at the input with the load connected.

Input impedance can be greatly increased by the addition of the components shown in the dashed lines. This, of course, is positive feedback and if overdone will result in oscillation. However, if the feedback adjustment is set with care, the input impedance can be raised as high as 20 megohms before instability occurs.

*Gordon D. Svendsen, engineer, Ampex Corp., Redwood City, Calif.*

## AMPLIFIERS

### Five-Amp DC Current Amplifier Has Low Output Impedance

The circuit described here was developed to fill the need for a dc current amplifier capable of delivering up to  $\pm 5$  amp to a 2-ohm load. Low output impedance was necessary to provide damping for a voice-coil type load.

The basic circuit (Fig. 1) is a bridge configuration, with an emitter follower and a constant current source in the active arms. The current source arm of the bridge provides lower average dissipation than a

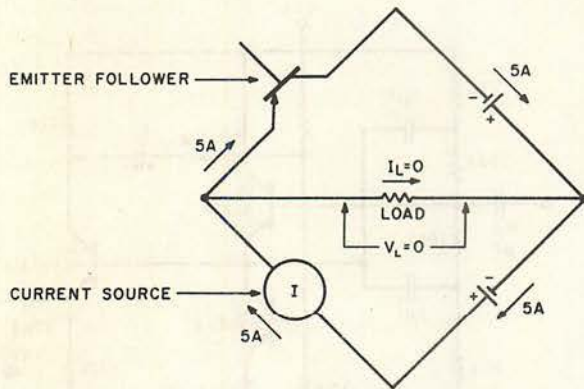


Fig. 1. Bridge currents at balance.

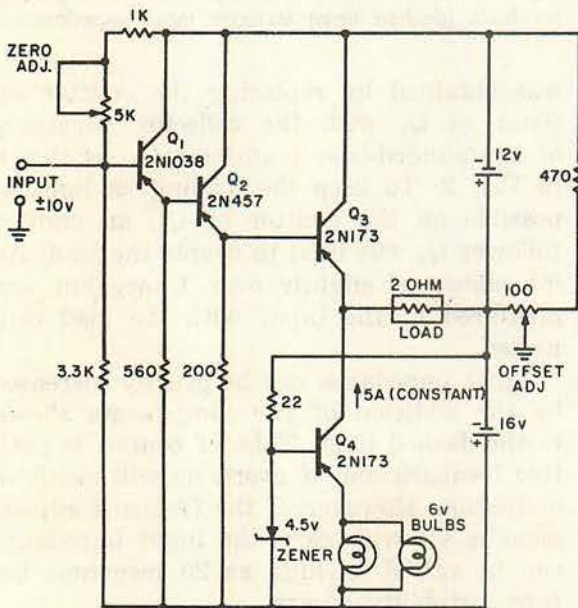


Fig. 2. Current amplifier was designed to drive 2-ohm voice-coil type load with maximum damping.

straight resistive arm. This source is composed of transistor  $Q_4$ , whose base is held at a fixed potential by a Zener diode. Emitter current from  $Q_4$  flows through a resistive load composed of several paralleled 6-v bulbs. The number of bulbs used determines the amount of current required to raise the emitter of  $Q_4$  to a stable point near the base voltage. Straight resistors could be used instead of the bulbs, but the positive temperature coefficient of the bulbs provides additional current regulation.

The remainder of the circuit consists of three compound emitter followers,  $Q_1$ ,  $Q_2$  and  $Q_3$ . These provide large current gain and moderate input impedance. A zero adjust control allows initial balancing of the circuit, and the offset adjust provides a voltage to buck-out the base-to-emitter voltage drops of  $Q_1$ ,  $Q_2$  and  $Q_3$ .

The two batteries shown are unequal in voltage to make up for the 4.5-v drop across the lamp bulbs. This permits equal maximum voltage swings across the output load.

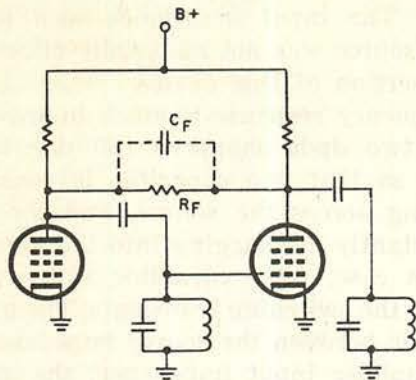
*J. Wisnia, Comstock & Wescott Inc., Cambridge, Mass.*

### Bridged-T Feedback Yields "Maximally Flat" Response

The "maximally flat" response characteristic obtainable with staggered amplifier pairs can be synthesized by using plate-to-grid degenerative feedback in "feedback pairs." This eliminates the problem of staggering the individual responses. The circuit arrangements of (a) and (b) are most commonly used. Either circuit can be made essentially equivalent to the other by using  $\pi$  to  $T$  transformation equations.

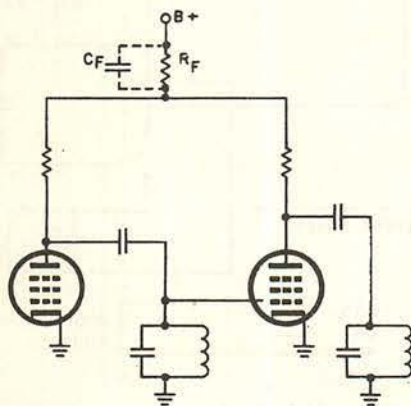
In practice, it has been found that the inherent shunt capacitance across  $R_f$ —the feedback element in each of the circuits—affects the response by providing either too much or too little feedback at the high frequency end of the band. Thus, the response of the circuit of (a) tends to have a negative slope, while the response of the circuit of (b) tends toward a positive slope.

By combining both feedback configura-



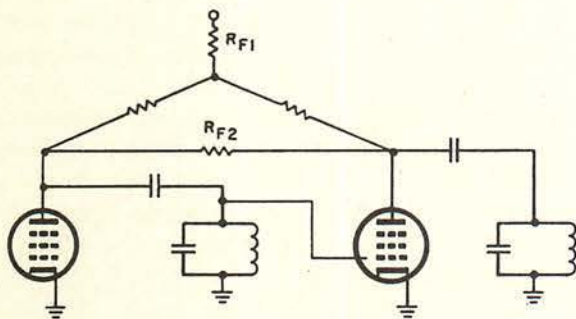
"π"  
RESPONSE CHARACTERISTIC

(a)



"T"  
RESPONSE CHARACTERISTIC

(b)



"BRIDGED T"  
RESPONSE CHARACTERISTIC

(c)

By combining the amplifier-pair π and T coupling configurations of (a) and (b), left, p. 46, the effects of shunt capacity tend to cancel and the response of (c), above, is "maximally flat."

tions in one "bridged-T" network, (c), the effects of shunt capacity across the feedback elements tend to cancel. If the resistors are chosen correctly so that the total feedback remains the same as for either circuit alone, the response will be "maximally flat" as in a corresponding staggered pair.

Ernest I. Fox, engineer, Raytheon Co., Sudbury, Mass.

## Audio Frequency Amplifier Responds over 10-Cps Bandwidth

Many applications require a band-pass amplifier in the audio-frequency range. The circuit shown in Fig. 1 is intended for such an application.

Transistors  $Q_1$  and  $Q_2$  are connected in the compound (or Darlington) connection. The output current is the sum of the collector currents of the two transistors. By using a bridged-T network in the negative-voltage feedback loop between collector and base of  $Q_2$ , the required bandwidth can be ascertained. It is known that the null frequency

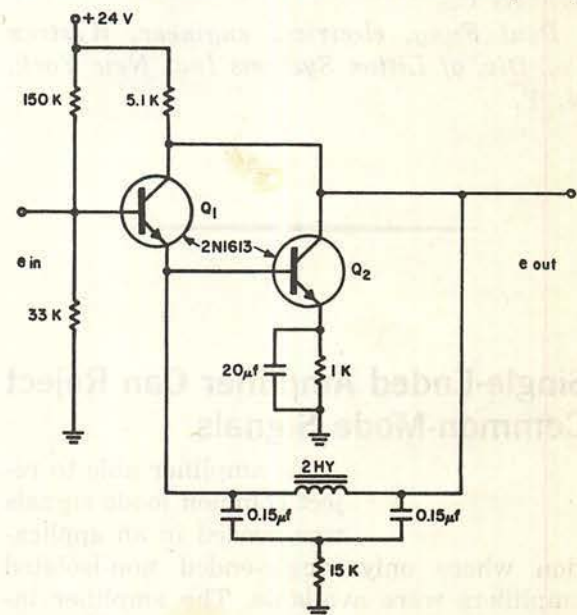


Fig. 1. Darlington circuit combined with bridged-T has 10-cps bandwidth at 400 cps.

$\omega_0$  of the bridged-T network is:

$$\omega_0 = \frac{2RC}{Q}, \omega_0 = \sqrt{\frac{2}{LC}}$$

The fundamental relationship between the

## AMPLIFIERS

gain  $A$  of the amplifier with a feedback coefficient of  $\beta$  is

$$A = \frac{\alpha}{1 - \alpha\beta}$$

Consequently feedback occurs at all frequencies except at  $\omega_0$  where  $\beta=0$ . Thus the circuit has a gain of  $\alpha$  at  $\omega_0$ .

The input impedance of the amplifier is very high, for a frequency of 400 cps and a

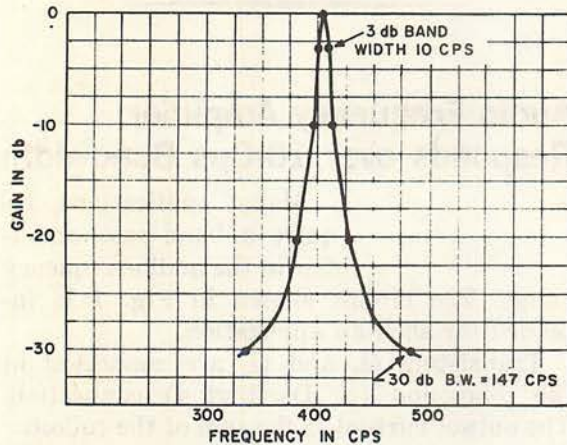


Fig. 2. Characteristic curve for band-pass amplifier has 10-cps bandwidth at 3-db point.

bandwidth of 10 cps. The amplification is over 30 db over a temperature range of  $-20$  to  $+85$  C.

*Paul Fung, electrical engineer, Westrex Co., Div. of Litton Systems Inc., New York, N. Y.*

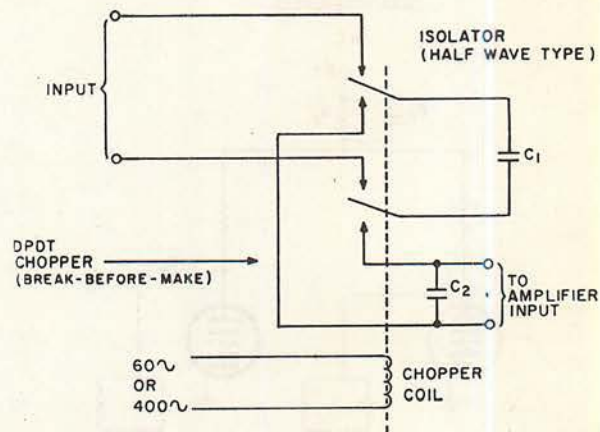
## Single-Ended Amplifier Can Reject Common-Mode Signals

An amplifier able to reject common mode signals was needed in an application where only single-ended non-isolated amplifiers were available. The amplifier input was to be fed by grounded thermocouples.

Using a dpdt chopper and two capacitors the circuit shown in the figure was designed to provide the common mode rejection. Also, it was able to isolate completely the thermocouple from the amplifier.

Capacitor  $C_1$  charges up across the signal source, and discharges into the amplifier. Capacitor  $C_2$  provides the desired filtering. The input impedance seen by the signal source was not materially affected by the insertion of this device.

Frequency response is much improved by using two dpdt choppers 180 deg out of phase, so that one capacitor is constantly charging across the source, and the other is constantly discharging into the amplifier. In this case, filter capacitor  $C_2$  serves to remove the switching transients. The greater the ratio between the source impedance and the amplifier input impedance, the greater will be the frequency response capability of the unit.

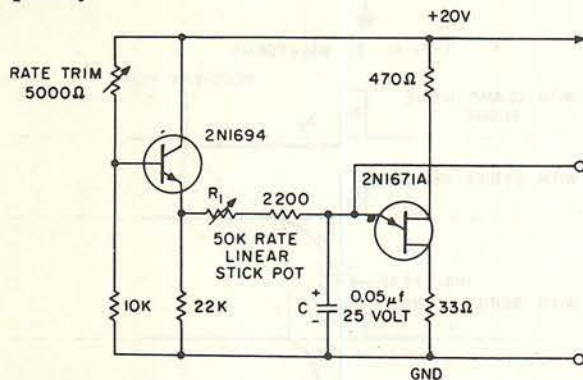


Combination of dpdt choppers and two capacitors allows single-ended input amplifier to reject common-mode signals.

*Joseph V. Patterson, senior engineer, The Martin Co., Denver, Colo.*

## Unijunction Oscillator Has Frequency Trim Control

The unijunction relaxation oscillator, because of its frequency stability and wide frequency range (variable with a single potentiometer), invites uses where pot shaft position accurately describes a given frequency.



**Low-interaction** trim control for frequency of unijunction relaxation oscillator uses common-collector variable regulator for timing-circuit voltage supply.

In practice, however, variation of unijunction intrinsic stand-off ratio and timing-capacitor variations can destroy the pot shaft/frequency characteristic if simple series resistance trim is employed in the timing network. Further the variation in Thevenin equivalent resistance of a variable divider may be intolerable if divider current must be held to a low value.

The circuit described provides a very low interaction trim control for frequency by employing a common-collector variable regulator in the timing-circuit voltage supply.

The source impedance is low and relatively constant over a wide range with little additional current drain.

Production tolerances of aluminum electrolytic timing capacitors can be absorbed by this circuit, and the least expensive unijunction transistors can be employed.

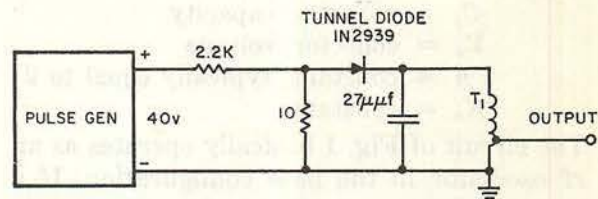
The 5000-ohm rate trim potentiometer provides frequency set that is independent of the main timing potentiometer  $R_1$ . The center frequency is approximately 1000 cps.  $R_1$  provides at least a decade variation in frequency and the trim control provides at least one octave variation.

*John H. Phelps, manager application engineering, General Electric Co., Semiconductor Products Dept., Syracuse, N. Y.*

## Gated Tunnel-Diode Oscillator

A pulsed 30-mc oscillator was needed to test radar IF strips. Our commercial signal generator had excessive 30-mc signal feedthrough when the pulse was off. Starting phase of the 30-mc signal varied from pulse to pulse. In addition turnoff time was unsatisfactory in the commercial unit.

The test requirements were met by using the output of a fast-rise pulse generator to power a simple tunnel-diode oscillator. The results were excellent. Approximately 100 mv peak-to-peak were delivered to a 100-ohm load. Changing the pulse amplitude accomplished electronic tuning, varying the frequency from about 28 mc to 35 mc cycles. There is no feedthrough problem since the oscillator is completely off in the absence of a pulse. The oscillator is coherent in that it always starts with the same phase when pulsed.



**Radar IF test oscillator** provides 100 mv into 100-ohm load.

This device readily may be converted to a sweep-frequency oscillator. Tilt on the input gating pulse will produce fm within the output wave packet. Pulse-to-pulse fm may be achieved by amplitude-modulating the input gating-pulse train.

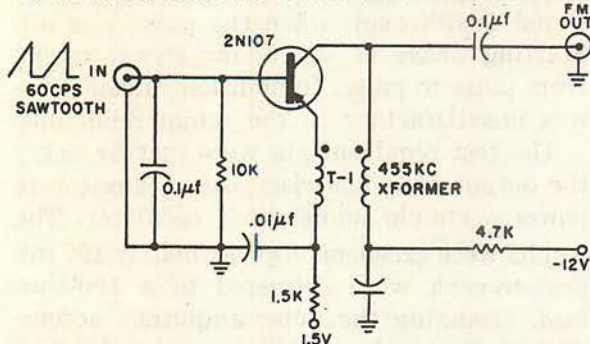
If frequency modulation or electronic tuning is not required, a crystal-controlled tunnel-diode oscillator is desirable, since frequency calibration is inherent in crystal choice.

*Paul E. Harris, research associate, Syracuse University Research Corp, Syracuse, N. Y.*

### Sweep-Frequency Oscillator Operates on Collector Capacity

Low frequency if amplifier design often calls for a sweep oscillator whose frequency can be changed electronically. When the ratio of frequency deviation to center frequency is small, the circuit shown can be used to achieve surprising linearity.

The circuit's mode of operation depends upon the inherent collector capacitance,  $C_c$ , of the transistor. This collector capacitance is variable and is a function of the collector



**Operation** of electronically-swept oscillator depends upon the inherent collector capacitance,  $C_c$ , of the transistor.

voltage,  $V_c$ . The analytic relationship can be expressed as:

$$C_c = \frac{K_o}{(V_c)^{1/n}} \quad (1)$$

where:

- $C_c$  = collector capacity
- $V_c$  = collector voltage
- $n$  = constant, typically equal to 2
- $K_o$  = constant

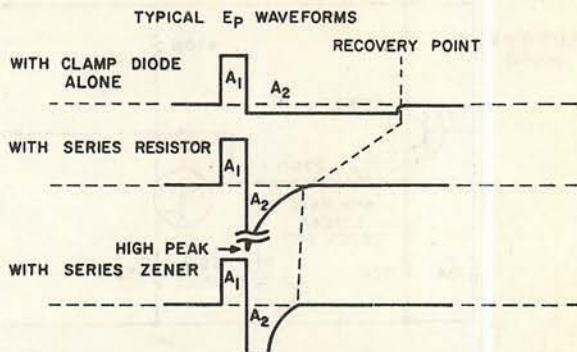
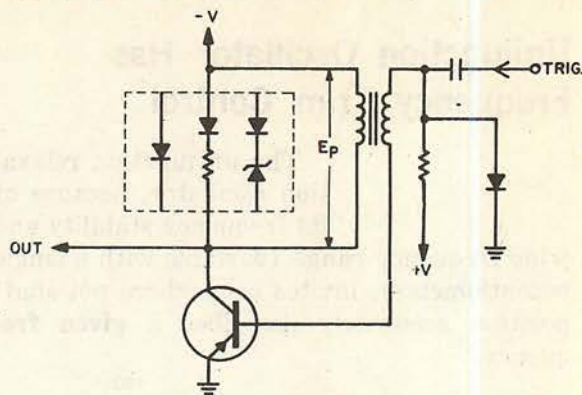
The circuit of Fig. 1 basically operates as an rf oscillator in the base configuration. If a low-frequency sweep, that is, 60 cps sawtooth, is applied to the base, the collector capacitance changes according to Eq. 1 and the desired frequency change is obtained.

*Joseph R. Kotlarski, member of technical staff, Hughes Aircraft Co., Culver City, Calif.*

### Clamp Circuit Improves Blocking Oscillator Duty Cycle

Blocking oscillators find limited application because conventional circuits are unable to achieve a duty cycle much greater than 0.2.

This limitation is introduced by the standard procedure of putting a clamping diode across the transformer primary to protect



**Series Zener diode** shortens recovery time of blocking oscillator without endangering transistor.

After each pulse, the energy stored in the transformer field must be discharged before the oscillator can fire again. The transformer attempts to do this by the well known fly-back pulse.

The clamping diode prevents the fly-back pulse from building up to a significant voltage level, and appears as a very small resistance to the pulse. This lengthens the  $L/R$  time constant of the discharge path.

The duty cycle may be improved by increasing the equivalent resistance of the discharge path to allow faster discharge of the stored energy. A resistor in series with the clamping diode will help considerably, but is somewhat unpredictable. A better solution is to use a Zener diode in series with the clamp diode.

This allows the fly-back pulse to build up to a significant voltage and presents the equivalent of a larger path resistance while still precisely controlling the fly-back amplitude to protect the transistor. In any case, the transistor has to withstand a higher peak voltage, but this is normally no problem.

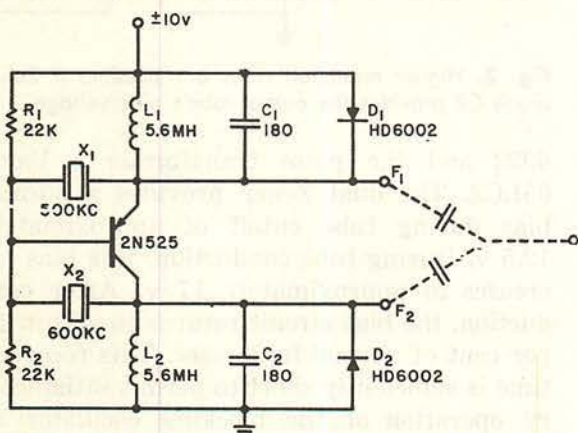
*Roy P. Foerster, group engineer, Martin Co., Baltimore, Md.*



## Bilateral Crystal Oscillator Has Two-Frequency Output

The bilateral characteristics of the transistor come into play in this two-frequency crystal oscillator. Either of the two frequencies may be selected by applying plus-or-minus voltage to the supply terminal.

When plus voltage is applied, the current flows through  $D_1$  to the emitter of the transistor. Tuned circuit  $L_2C_2$  and crystal unit  $X_2$  then become active and an output is derived from  $F_2$ . The  $L_1C_1$  network is shorted out by diode  $D_1$  and crystal  $X_1$  is connected between base and emitter where there is no gain to promote oscillation in this unit.



Either of two oscillator frequencies can be obtained by reversing polarity of supply voltage.

With minus voltage applied to the supply terminal, the transistor operates in the "inverted" mode. Effectively, the collector becomes the emitter and vice versa. In this case, oscillations are generated by  $L_1C_1$  and crystal unit  $X_1$ . Output voltage will be delivered at output terminal  $F_1$ .

If desired, two additional capacitors (shown by dashed lines) may be added to provide a single output terminal.

Diodes  $D_1$  and  $D_2$  limit the output to 0.7-v rms. Since the transistor is operating in an oscillator circuit the beta of the inverted mode need only be sufficient to produce oscillation. Therefore, it is not necessary to use selected bilateral transistors in this application. This circuit can be used to select frequencies from a remote point by electrical means. Since it uses a single transistor, there is a saving in components.

*John M. Tewksbury, principal engineer, Avionics Products, Bendix Corp., Towson, Me.*

## Diode-Resistor Pair Improves One-Shot Multi Fall Time

In a collector-coupled one-shot multivibrator, Fig. 1, the trailing edge of one of the pulses always has a poorer fall time than the other. This easily can be overcome by adding a resistor and a diode as shown in Fig. 2.

In Fig. 1 when the trailing edge of a pulse occurs, the collector of  $Q_1$  cannot rise to  $E$  immediately because  $C$  has to be charged. The result is a slow trailing edge, which depends on  $R_c$  and  $C$ .

If the circuit is designed as shown in Fig. 2 diode  $D$  will be reversed biased when the trailing edge occurs. The voltage at the collector of  $Q_1$  will now rise to  $ER/(R_c + R)$ . This voltage practically will be  $E$  if  $R$  is chosen much larger than  $R_c$ . It can be seen that the fall time now is independent of  $C$ . As a result, both trailing edges will have the same fall time.

The diode  $D$  has been added to short out the resistor  $R$  from the time the one-shot is triggered until the trailing edge occurs. The operation during this period is that of a conventional one-shot.

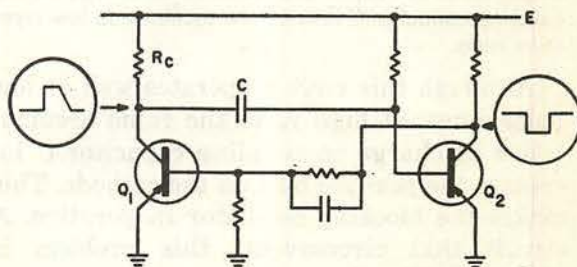


Fig. 1. In conventional one-shot, one of the pulses always has a poorer trailing edge than the other.

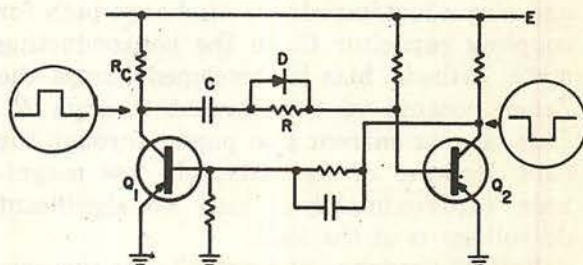
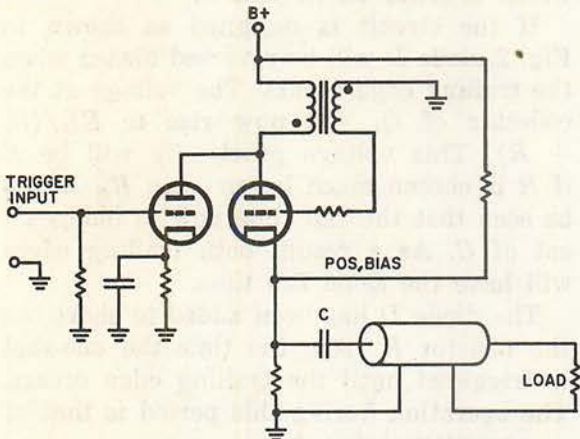


Fig. 2. Both pulses can be squared-up by adding a resistor and diode to the collector with the poorer pulse.

*Erik Rosenbaum, engineer associate, The Bendix Corp., Baltimore, Md.*

## Zener-Biased BO Has High Repetition Rate

The usual method of self-biasing the output tube of a monostable blocking oscillator is to apply a positive voltage to its cathode. But if the output pulse is to be taken from this cathode, it usually is desirable to block this dc bias from the load by a suitable coupling capacitor, as shown in Fig. 1.



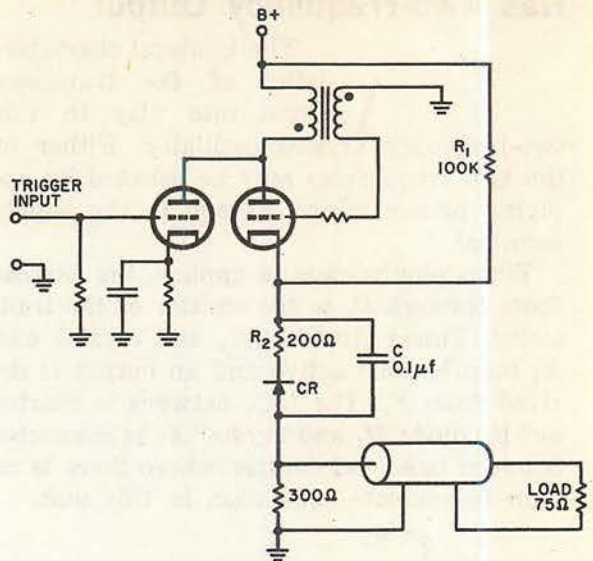
**Fig. 1.** Usual method of self-biasing a blocking oscillator applies a positive voltage to the cathode of its output tube. But rapid accumulation of charge on the coupling capacitor *C* restricts the oscillator to low repetition rates.

Although this circuit operates well at low pulse rates, at high rates the rapid accumulation of charge on coupling capacitor *C* increases the positive bias on the cathode. This makes the blocking oscillator inoperative. A circuit that circumvents this problem is shown in Fig. 2.

In this circuit, the Zener diode, *CR*, provides the bias voltage for the output tube and also a low-impedance discharge path for coupling capacitor *C*. In the nonconducting state, cathode bias is developed across the Zener because of the current through *R*<sub>1</sub>. This biasing current also passes through the load. Because of its extremely low magnitude (approximately 2 ma) no significant dc voltage is at the load.

Both the average and peak Zener currents must, of course, be limited to the maximum ratings of the particular diode used. Average Zener current is equal to the average load current. Maximum Zener current is limited by resistor *R*<sub>2</sub>, which usually has a value in the order of a few hundred ohms.

In the circuit of Fig. 2, the Zener is actually two 1N429 Zeners in series. The tube is a



**Fig. 2.** Higher repetition rates are possible if Zener diode *CR* provides the output tube's bias voltage.

6922 and the pulse transformer a Valor 05LC2. The dual Zener provides a normal bias during tube cutoff of approximately 12.5 v. During tube conduction, this bias increases to approximately 17 v. After conduction, the bias circuit returns to within 10 per cent of normal in 25  $\mu$ sec. This recovery time is sufficiently short to permit satisfactory operation of the blocking oscillator at pulse repetition rates up to 50 kc.

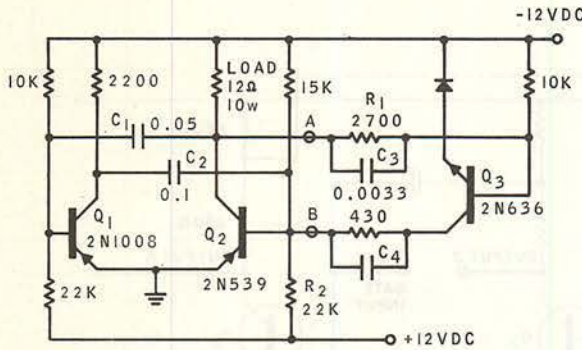
*Edward E. Godin, Sandia Corp., Sandia Base, Albuquerque, N. M.*

## Regenerative Stage Enhances Flip-Flop Power Output

An inherent deficiency of the astable flip-flop as a source of ac is its load limitations. As the collector load is increased, a point is reached where the available base current is inadequate to drive the transistor into saturation. The circuit shown here makes use of a regenerative amplifier stage to supply this needed base drive.

The circuitry to the left of *A-B* is a typical astable flip-flop, except that the 12-ohm load would prohibit proper operation. As *Q*<sub>1</sub> starts turning off, the charge on *C*<sub>2</sub> goes negative causing *Q*<sub>2</sub> to start turning on. As

the collector of  $Q_2$  goes positive (toward ground)  $Q_3$  is forced to turn on, thus supplying another 25 ma (approximately) of base current to  $Q_2$ . The peak power delivered to the 12-ohm load will be nearly 10 w, the average power will be 3 w for a 50 per cent duty cycle (square wave output). The current delivered to the load when  $Q_2$  is in saturation is 1 amp. Capacitors  $C_3$  and  $C_1$  increase the output rise time.



**Regenerative amplifier** boosts flip-flop output to supply 10 w to 12-ohm load.

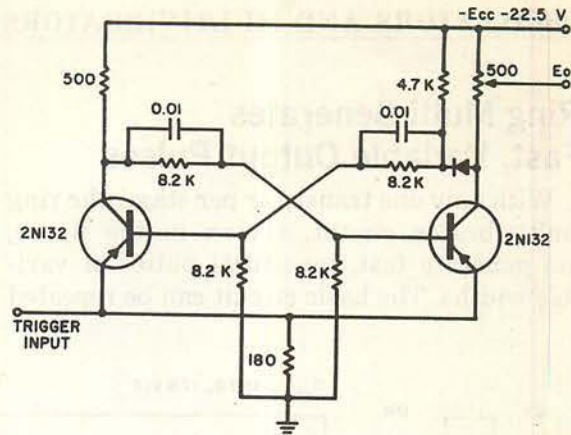
This basic idea easily can be extended to the stable and monostable flip-flops as well. The astable circuit as shown can be used as a dc-to-ac or dc-to-dc converter, by replacing the load resistor with a transformer primary, or as an oven control circuit, by using a heater element as a load and putting a thermistor in series with  $R_2$  to vary the duty cycle with temperature. The monostable could be used to drive high-current relays, or to switch a larger number of logic stages.

*Robert A. Durand, electrical engineer, Bendix Systems Div., The Bendix Corp., Ann Arbor, Mich.*

## Obtaining Zero Reference For Flip-Flop Square-Wave Output

A transistor flip-flop driven by a blocking oscillator produces excellent symmetrical square waves, but lacks a zero voltage reference. For certain test procedures, such as testing the response time of a potentiometric recorder, a square wave with negligible zero offset is convenient.

As shown in the diagram, this is easily accomplished by obtaining the base bias for one transistor through a separate resistor, isolating the resultant voltage drop by means



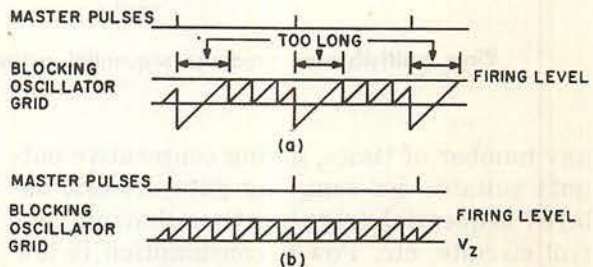
**Zero reference** in flip-flop is obtained by isolating base bias of one transistor through diode.

of a diode. The remaining zero offset is only that due to the  $I_{co}$  of the cut-off transistor—usually at least two orders of magnitude lower than the normal base-biasing current residual in the collector load resistor.

*Roy A. McCarthy, engineering designer, Beckman Instruments, Fullerton, Calif.*

## Zener Diode Helps Set Blocking Oscillator Synchronizing

When a free-running blocking oscillator is to generate timing pulses, but must be started by a master pulse, the master pulse itself can cause the blocking oscillator to give incorrect timing of the first interval. However, if a Zener diode is placed across the blocking oscillator capacitor, the capacitor is always driven down to the Zener voltage and the timing will not be disturbed.



**Pulse intervals** of blocking oscillator output are made equal by adding Zener diode across circuit capacitor. (a) Circuit without Zener; (b) circuit with Zener.

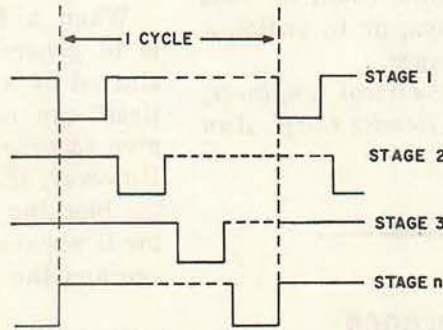
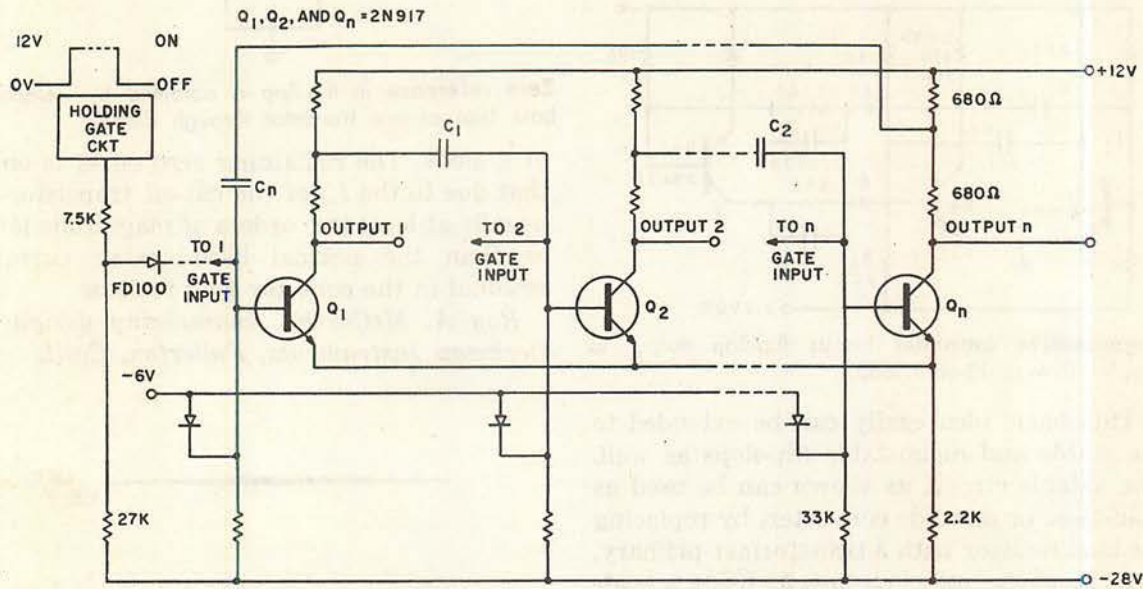
*E. R. Roeschlein, electronic engineer, U. S. Naval Avionics Facility, Indianapolis, Ind.*

### Ring Multi Generates Fast, Variable Output Pulses

With only one transistor per stage, the ring multivibrator circuit, shown in the figure, can generate fast, sequential pulses of variable widths. The basic circuit can be repeated

secutive outputs, without any noticeable affect on the collectors. Fast transistors in the circuit can yield speeds of less than 100 nsec.

Circuit operation is as follows: As each transistor finishes its conducting period and returns to the 12-v level, its collector produces a positive transient. This positive swing, coupled to the following base, turns on the next stage. The sequence can be made



Ring multivibrator produces sequential output pulses whose widths are independently variable.

any number of times, giving consecutive outputs suitable for sampling gate drivers, delayed sequential triggers, time-sharing control circuits, etc. Power consumption is low because only one stage conducts at a time.

Each stage is basically a constant-current, nonsaturating circuit providing negative output pulses. The RC combination in the transistor base determines pulse width. Pulse width may vary as much as 3 to 1 for con-

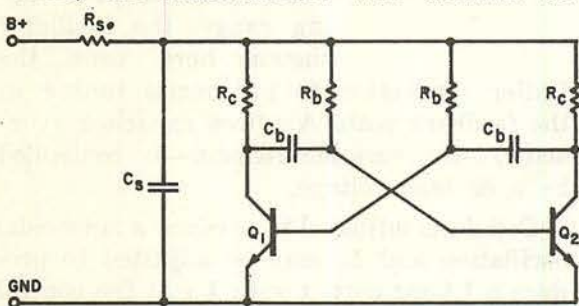
repetitive by coupling the last stage back to the first. Various load conditions can be accommodated by adjusting the emitter and collector resistors. By keeping the gated transistor on, the individual holding gates can stop the cycle without prematurely interrupting the sequence.

*John A. MacIntosh, Application Engineer, Fairchild Semiconductor Corporation, Mountain View, Calif.*

## Voltage Control Starts Free-Running Multivibrator

The circuit shown in the illustration provides a simple method of starting a free-running multivibrator. If the multivibrator is used where its output cannot be shorted, it can stall only at the moment power is applied. Both transistors then may saturate.

At low  $E_s$ ,  $I_b$  is reduced more than  $I_c$  because  $V_{BE}$  becomes significant. In addition,  $h_{FE}$  is low at low currents. If  $E_s$  rises slowly when power is first applied, neither transistor can saturate for a while. Meanwhile, the multivibrator will oscillate be-



**Slow voltage rise** assures nonsaturation of transistors in free-running multivibrator.

cause of positive feedback around the loop. Once oscillating,  $E_s$  can rise to normal operating level. A large decoupling capacitor,  $C_s$ , will cause  $E_s$  to rise slowly. Since good equipment design requires a liberal use of decouplers, there is no penalty for additional components.

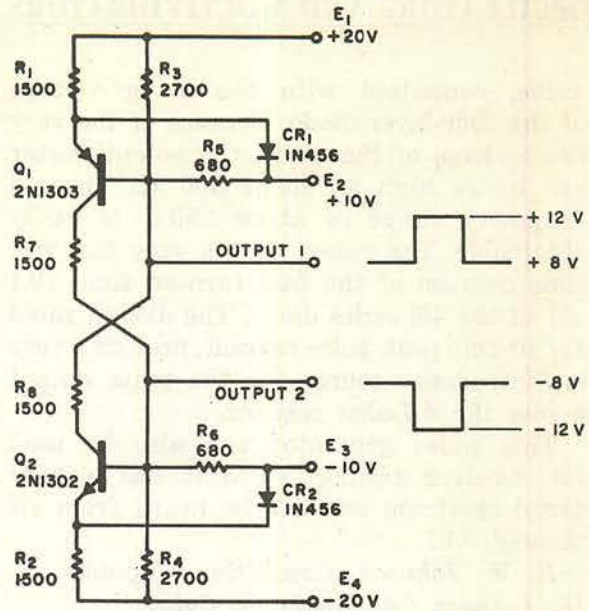
The value of  $R_c$  depends upon load and optimum operating point for the transistors. Ratio  $R_c/R_b$  should be less than  $h_{FE}$  min, and  $R_b R_c$  should be approximately  $f$ .  $R_s C_s$  should be greater than  $10R_b R_c$ .

*Cameron Burley, research engineer, Lockheed Missile and Space Co., Sunnyvale, Calif.*

## Current-Mode Flip-Flop Has Dual Voltage Outputs

The main advantage of the vertical current-mode flip-flop shown is that two outputs can be obtained at widely separated voltage levels.

In essence, the vertical current-mode flip-flop is one half of a symmetrical current-mode flip-flop.<sup>1</sup> The transistors operate out



**Positive and negative voltage levels** are available at dual-mode flip-flop output.

of saturation, and are either both on or both off. Resistors  $R_7$  and  $R_8$  serve to reduce the power dissipation in the transistors. They are unnecessary if power is not a problem.

Means for triggering are not shown since there are many possibilities, and the choice depends on the particular application.

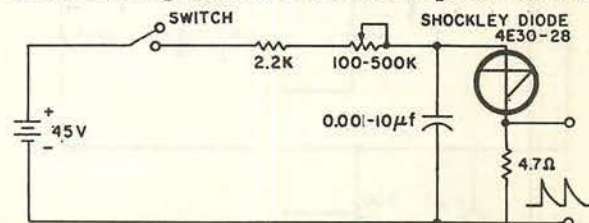
*Richard W. Hofheimer, project manager, Non-Linear Systems, Inc., Del Mar, Calif.*

### Reference

1. Richard W. Hofheimer, "Symmetrical Current-Mode Flip-Flop," *Electrical Design News*, June, 1961.

## Shockley Diode Modernizes Neon-Tube Oscillator

An easily-assembled source of pulses sometimes is needed when available test equipment is being used. The circuit on p 207 shows



**Easily-assembled** pulse source is built around Shockley four-layer diode.

a simple, but by-no-means new circuit that we found useful in such cases. It is a modernized version of the classic neon-tube oscillator, built around a Shockley four-layer diode.

The battery voltage can be any convenient

## OSCILLATORS AND MULTIVIBRATORS

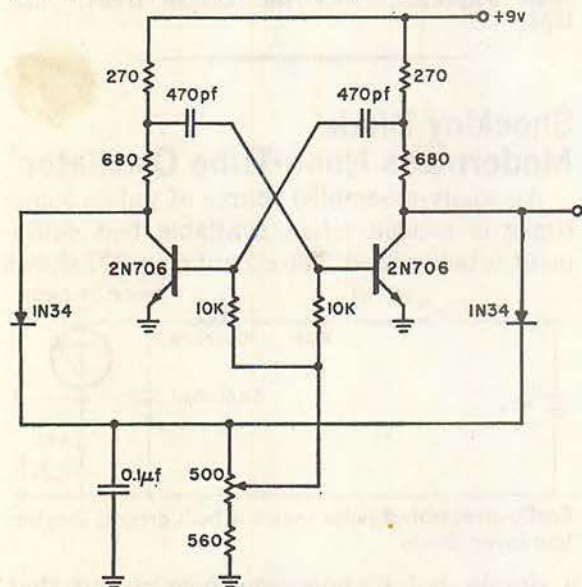
value, consistent with the firing voltage of the four-layer diode. Because of the very low leakage of the diode, the potentiometer can be as high as about 500 K. Thus, a frequency range of about 250:1 is easily obtainable. The pulses have a very fast rise time because of the fast turn-on time (0.1  $\mu$ s) of the 4E series diode. The diodes, rated for 10-amp peak-pulse current, provide a very low-impedance source for the pulse output across the 4.7-ohm resistor.

This pulse generator can also be used for receiver testing, since it has a very broad spectrum and can be heard from vlf through vhf.

R. W. Johnson, Consulting Engineer, R. W. Johnson Co., Anaheim, Calif.

### Tunable Multivibrator Starts Reliably

The circuit shown here is an oscillator tunable from 200 to 300 kc. The most troublesome feature of transistor multivibrators is an occasional failure to start, because both transistors reach saturation simultaneously. Deriving the base supply voltage in the manner shown prevents this and,



Simultaneous saturation of transistors is prevented by obtaining base bias through diode network.

as a small bonus, clips the top portion of the collector waveform, where the voltage would otherwise be rising rather slowly. Tap-

ping the cross-coupling capacitors up on the collector load resistors yields full benefit from the clipping, but is otherwise nonessential. It should be possible to stabilize the frequency against supply voltage change by shunting a Zener diode across the potentiometer circuit, but this was unnecessary in the present application.

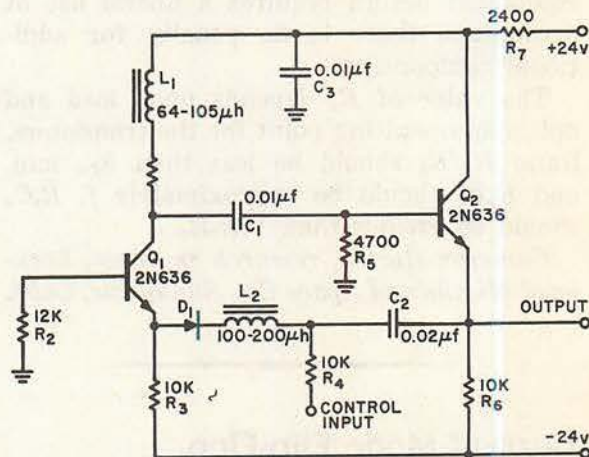
M. W. Egerton, Jr., Towson Laboratories, Inc., Towson, Md.

### Voltage-Controlled Oscillator Exceeds 2-to-1 Frequency Range

To obtain a wide tuning range, the oscillator shown here uses the Butler connection to put series tuning in the feedback path. A silicon capacitor (varactor)—the variable element—is controlled by a dc bias voltage.

Coil  $L_1$  is adjusted to produce a sinusoidal oscillation and  $L_2$  may be adjusted to produce a 1.6-mc output with 4 v at the control input. Under these conditions, the frequency deviation is from 1.1 mc when the control voltage is zero to 2.4 mc with 30 on the control input.

Advantages of this oscillator include a low output impedance and simple adjust-



Using component values shown, output frequency can be varied from 1.1 mc to 2.4 mc.

The control impedance is limited primarily by the required response time. Frequency sweep rates longer than 100  $\mu$ sec could be obtained through a higher value of input resistor.

Charles Turner, electronic engineer, Sanders Associates, Inc., Nashua, N. H.

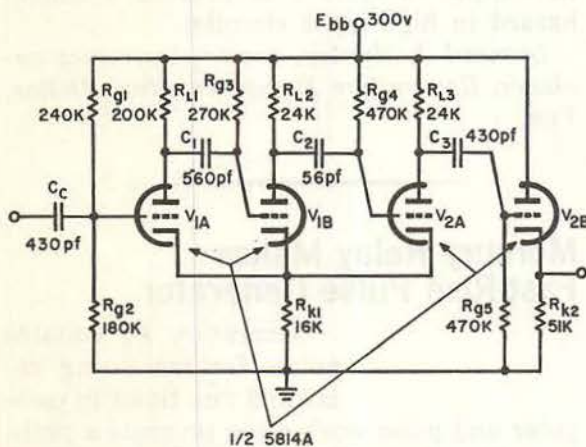
## Delayed-Pulse Generator Uses Fewer Components

It often is necessary to produce a pulse of given width, delayed a specified length of time from a reference pulse. The usual circuitry for doing this requires two one-shot multivibrators followed by an isolation-amplifier output, a total of five stages.

It is possible to build such a two-multivibrator combination using only three stages. The isolation amplifier would require a fourth stage. The circuitry has the form shown in Fig. 1, and the switching sequence

### Switching Sequence

Step	$V_{1A}$	$V_{1B}$	$V_{2A}$
1	OFF	ON	ON
2	ON	OFF	ON
3	ON	ON	OFF
4	OFF	ON	ON



Using component values shown, output of generator will be a 15- $\mu$ sec pulse delayed 8  $\mu$ sec from trigger.

is given in the table.

Stages  $V_{1B}$  and  $V_{2A}$  have identical plate resistors and the current in them is about the same. The value of  $R_{L1}$  is much larger than  $R_{L2}$  and  $R_{L3}$ . The common cathode voltage, then, is determined by the current in tubes  $V_{1B}$  or  $V_{2A}$  or both. The current through the common cathode resistor ( $R_{K1}$ ) during steps 2 and 3 when only  $V_{1A}$  or  $V_{2B}$  is conducting is about two-thirds the current during steps 1 and 4 when both  $V_{1A}$  and  $V_{2B}$  are conducting. Grid voltage of  $V_{1A}$  is held constant at a value that cuts off  $V_{1A}$  when both  $V_{1B}$  and  $V_{2A}$  are conducting, but allows  $V_{1A}$  to conduct when on-

ly  $V_{1B}$  or  $V_{2A}$  alone is conducting. The combination  $R_{g3}C_1$  and  $R_{g4}C_2$  give the desired delay and pulse width.

A positive input pulse will cause stages  $V_{1A}$  and  $V_{1B}$  to switch. The plate of  $V_{1B}$  rising to a more positive voltage only drives  $V_{2A}$  temporarily into harder conducting. With  $V_{1A}$  and  $V_{2A}$  conducting, common cathode voltage is about two-thirds of its initial value. After time-delay capacitor  $C_1$  has discharged to a point where  $V_{1B}$  begins to conduct, the plate voltage of  $V_{1B}$  falls and stages  $V_{1B}$  and  $V_{2A}$  switch.

The common cathode voltage does not change during the latter switch and stage  $V_{1A}$  remains in a conducting state. After pulse-width capacitor  $C_2$  has discharged to a point where  $V_{2A}$  begins to conduct, stages  $V_{1A}$  and  $V_{2A}$  switch and the circuit resumes its initial conductance state. During this last switch there is feedback from  $V_{1A}$  through  $V_{1B}$  which opposes  $V_{2A}$  turning on. This effort can be reduced by making the value of  $R_{g3}$  somewhat smaller than normal.

Stage  $V_{2B}$  is an isolation amplifier. The output will be a pulse of width determined by  $R_{g4}C_2$  and will be delayed in time by an amount determined by  $R_{g3}C_1$ .

*W. L. Lassetter, engineer, Sperry Piedmont Co., Charlottesville Va.*

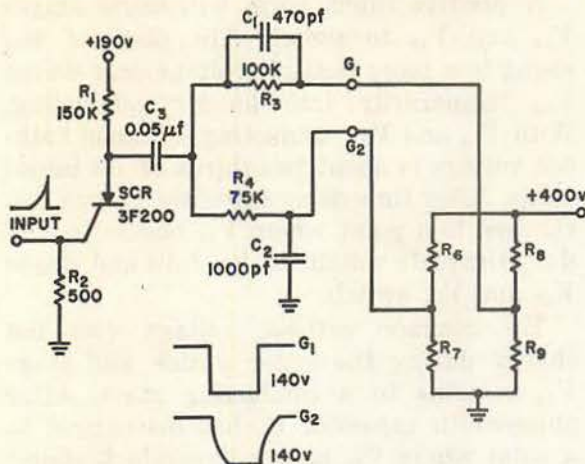
## SCR Drives Cold Cathode Counter Tube

Miniature silicon-controlled rectifiers can be used to produce the high-voltage guide pulses necessary to drive a cold-cathode counter tube. This method simplifies the counter-tube drive circuits and requires less power and space than vacuum-tube drive circuits. The circuit used is shown in Fig. 1.

For reliable operation of the counter tube, a 140-v negative double pulse must be applied to the guides. The pulse widths must be at least 60  $\mu$ sec, however; for lower counting rates (below 50 kc) longer pulse widths can be used.

## COMPUTER AND PULSE CIRCUITS

A positive 3-v pulse applied to the gate turns the SCR on. Resistor  $R_1$  limits the current through the SCR to a value well below the holding current so the SCR regains its open state upon the termination of the



**Fig. 1.** Double pulse for counter-tube drive is obtained from SCR output. Output waveform is as shown. input pulse. The output pulse is applied to the two guides through resistors  $R_3$  and  $R_4$ . Capacitor  $C_2$  and resistor  $R_4$  delay the pulse to guide 2. The guide pulses are as shown. Resistors  $R_6$ ,  $R_7$ ,  $R_8$ , and  $R_9$  supply the guide bias.

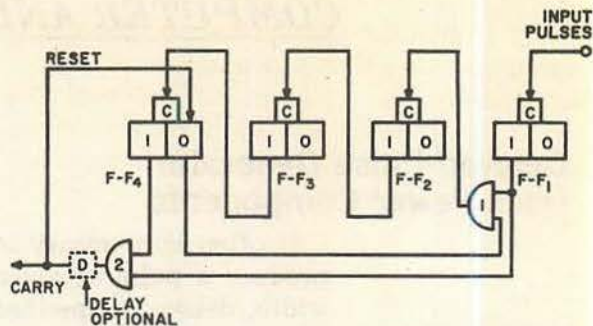
*M. W. Egerton, Jr., engineer, Towson Laboratories, Inc., Towson, Md.*

### Simple Gates Provide Binary Scale-of-Ten Counter

Problems attendant to scale-of-ten counters have been widely discussed and many solutions have been proposed. All of the remedies known to the author have one of the following disadvantages:

(1) The counter is prematurely "forced" to a higher count so that the final state is equivalent to a binary 15. The problem here is that while only 10 states are allowed, the count does not follow the normal binary sequence.

(2) The 11th binary state (1010) is sensed briefly and used to provide a reset to the affected decade as well as a "carry" to the next decade. The problem here is the transient 11th state which may be highly undesirable.



**Steering gates** provide binary output to count of ten. Carry to next flip-flop occurs on 1-to-0 change of state.

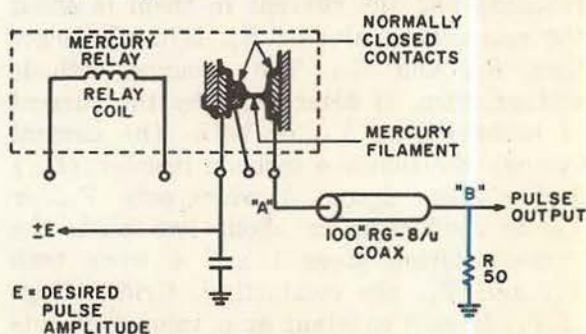
The addition of two simple "steering" gates, as illustrated, solves both problems. Gate 1 allows the binary count to proceed normally to the count of eight at which time flip-flop 4 goes to the "one" state, and Gate 1 is disabled while Gate 2 is enabled. The count of nine occurs normally. When the 10th input pulse occurs, flip-flop 1 returns to the "zero" state causing propagation of a pulse through gate 2, thereby generating both a reset for flip-flop 4 and a carry to the next decade. A delay element may be inserted on the output of Gate 2 to prevent a timing hazard in high-speed circuits.

*Leonard J. Nunley, senior electronics engineer, Recognition Equipment, Inc., Dallas, Tex.*

### Mercury Relay Makes Fast-Rise Pulse Generator

Generation of suitable pulses for measuring delay and rise times in computer and pulse work often presents a problem. The fact that some mercury relays have a "make before break" characteristic, can be used to generate a fast rising pulse with little overshoot or tilt.

The amplitude versatility and choice of



**Fig. 1.** Simple pulse generator uses mercury relay to provide fast rise pulses.



polarity, plus the excellent wave shape, outweigh the fact that the pulse width is determined by the geometry of the relay. In the units tried (Clare HG 1005 and Western Electric 275C), pulse width is about 250  $\mu$ sec. Coil-driving current can be adjust-

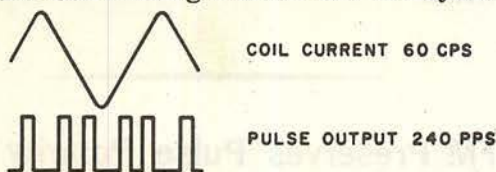


Fig. 2. Pulse output obtained with 60-cps coil current. The "make" pulse width equals the "break" pulse width.

The 50-ohm resistor also may be returned to A voltage if desired to determine the base line of the pulse.

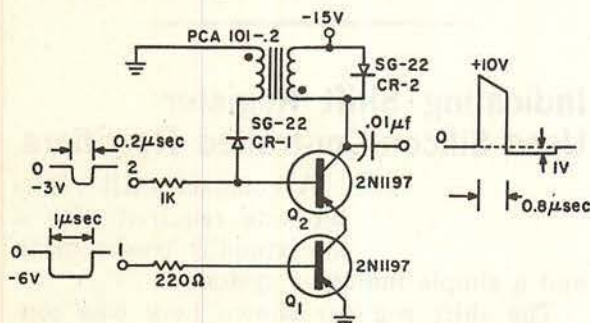
J. R. Bowers, Applied Mathematics Div., Argonne National Laboratory, Argonne, Ill.

### Blocking Oscillator-And Gate Produces Standard Output Pulse

Using only two transistors, the circuit shown checks for pulse coincidence and then produces a standard output pulse. Only when signals are applied simultaneously at both inputs will a pulse appear at the output.

A trigger pulse at input 2 is sufficient to trigger the blocking oscillator circuit. Since  $Q_1$  is not in the regenerative path, the gate at input 1 must be as wide or wider than the blocking oscillator pulse to maintain  $Q_1$  in a conducting state until the BO pulse is terminated.

Diode CR-1 prevents trigger signal feed-through from input 2 into the transformer. The two resistors serve to isolate the circuit from the low-impedance sources.

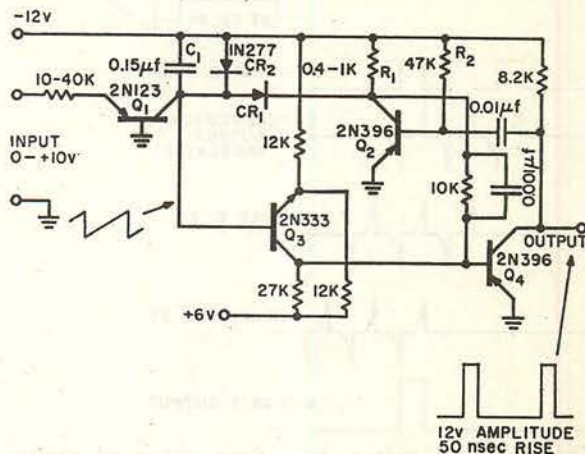


Blocking oscillator-and circuit checks for pulse coincidence, then produces a standard output pulse.

Alfred W. Zinn, project engineer, Farrand Optical Co., New York, N. Y.

### Transistorized Voltage-Frequency Converter Operates Linearly

Developing a servo system using a digital motor, we needed a pulse generator that would produce a pulse rate directly proportional to a varying dc input voltage. Conventional generators would not do because (a) they produced an output even though there was no input and (b) they did not respond linearly to the voltage amplitude over a large enough output frequency range.



Pulse generator produces output pulses proportioned to a varying dc input voltage. With input of 10 v dc output is 300 pps.

With a voltage at the input,  $Q_1$  acts as a constant-current source for  $C_1$ . This produces a linear slope until the base of  $Q_3$  becomes forward-biased. The negative-going collector of  $Q_3$  then starts the single-shot cycle of  $Q_2$  and  $Q_1$ .

Transistor  $Q_2$  is cut off and its collector goes negative. This allows  $C_1$  to discharge through  $R_1$ . When the single-shot has completed its cycle the collector of  $Q_2$  goes to ground and the input current again charges through  $Q_1$ . This restarts the circuit cycle.

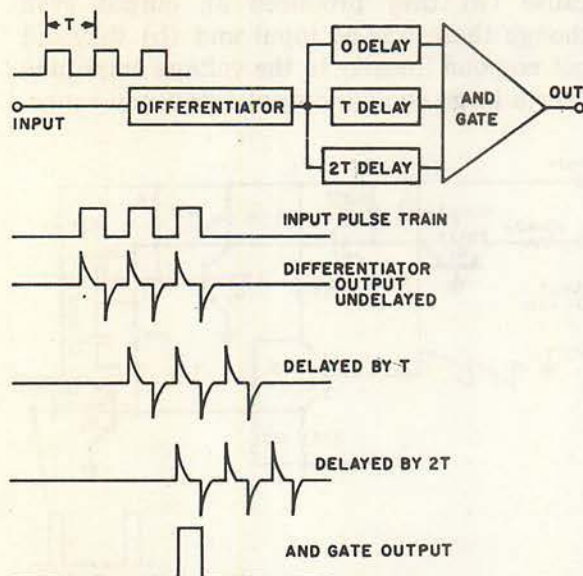
Diode  $CR_2$  passes the leakage currents of  $CR_1$ ,  $Q_1$  and  $Q_3$ . This prevents cycling at low frequencies when there is no input current, and allows the output to reach zero cps.

Modifications can be made to extend the frequency range, alter the input sensitivity and improve the low-end linearity. These steps depend, of course, on how the circuit will be used.

James M. Howe, electronic development, Navy Electronics Laboratory, San Diego, Calif.

## Delay-Line Discriminator Detects Sequences of Pulse

A sequence of equally spaced pulses obscured by random or recurrent signals of period different from the period of



**Sequences of pulses**, here three pulses of proper width and repetition rate, are detected by combination of delay lines and AND gate. Time relation between pulses is also indicated.

the desired pulse sequence, can be detected with the circuit shown in the figure. It extracts the three pulses and generates a trigger when the third pulse is received.

The signal first is differentiated and then fed through parallel delay lines (with delays of  $0$ ,  $T$ , and  $2T$ , respectively) to a 3-input "AND" gate designed to respond to positive signals. A trigger pulse is produced when three positive pulses (the differentiated positive peaks corresponding to the leading edges of the original pulses) are presented to the gate simultaneously. The time relationship between the various signals also is shown in the figure.

The circuit discriminates against both narrow and wide random pulses. Increasing the number of pulses in the sequence and the number of delay lines (with delays of  $0$ ,  $T$ ,  $2T$ , . . .  $nt$ ) reduces the possibility of response to spurious signals to an insignificant level.

Admittedly a single, tapped delay line might be used; however, pulse attenuation and rise time complications might result.

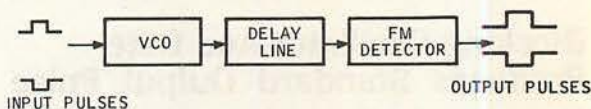
Untapped delay lines are generally easier to obtain, and they allow operation at low impedance levels.

*R. Michel Zilberstein, sr. project engineer, Andersen Laboratories, Inc., West Hartford, Conn.*

## FM Preserves Pulse Polarity In Ultrasonic Delay Lines

When unipolar pulses are used, amplitude modulation can be applied to a delay-line carrier signal with no problem. However, when both positive and negative pulses must be delayed, a different technique is needed, since a dc reference cannot be propagated in this type of delay line.

A simple solution to this problem is to use frequency modulation, as shown in the



**Voltage-controlled** oscillator and fm detector provide polarized outputs from delay line.

figure. A positive pulse will cause the voltage-controlled oscillator frequency to increase while the negative pulse will cause the frequency to decrease. The fm detector then will yield a pulse of polarity dependent on the input pulse polarity.

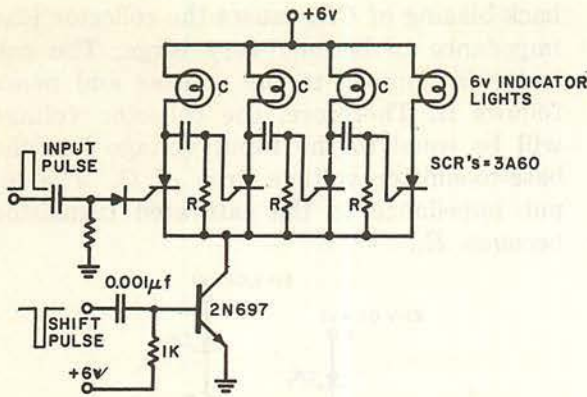
The VCO must have a linear frequency vs voltage characteristic over the dynamic range of interest to preserve accurate pulse amplitude information.

*Robert A. Durand, electrical engineer, The Bendix Corp., Bendix Systems Div., Ann Arbor, Mich.*

## Indicating Shift Register Uses Silicon-Controlled Rectifiers

A compact shift register was required with a low standby power drain and a simple indicator system.

The shift register shown here was constructed using small silicon-controlled rectifiers. Only one SCR per stage of memory is required. Standby power (with register empty) is only a few microwatts per stage. Op-



Use of SCRs provides high speed with little power drain in shift register.

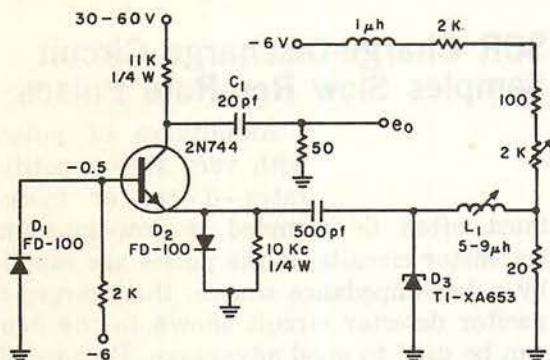
erating speed is high because of the rapid switching of small SCRs. In the four-stage shift register shown, values of  $R$  and  $C$  are determined by input pulse length.

*James M. Loe, circuit design engineer, General Electric Co., Philadelphia 1, Pa.*

## Tunnel Diode Triggers Avalanche Pulse Generator

An ultra-fast pulse generator utilizing the fast rise-time of a tunnel diode to trigger a transistor in the avalanche mode of operation is shown in the diagram.

To get a nanosecond trigger pulse of about 1 v, a TI-XA653 gallium-arsenide tunnel diode was used in a pre-pulse trigger circuit. This is done because the output pulse rise-time, to some degree, is dependent on the trigger rise-time. The fast negative trigger from  $D_3$  is coupled to the emitter of  $T_1$ .



Tunnel-diode pulse generator provides 0.7-nsec rise time.

$T_1$  normally is biased off by the drop across  $D_1$ . This negative trigger pulse is sufficient to drive  $T_1$  into its avalanche breakdown

mode. The output pulse, as a result of this breakdown, has a rise-time of 0.7 nsec, pulse width of 2 nsec. Pulse amplitude is 20 v into a 50-ohm load with a prf from 10Kc to 2 Mc. The pulse width may be varied by a transmission-line pulse-forming network.

The circuit must be layed out with strict attention to rf considerations. It should be packaged in a strip-transmission-line configuration.  $T_1$  is a 2N744, which will exhibit avalanche breakdown tendencies with an  $E_{cc}$  under 24 v when properly biased.

*James R. Williams, design engineer, Sanders Associates, Inc., Inglewood, Calif.*

## Fixed Interval Timer Gates Random Pulse Stream

A simple method was needed to derive a gate signal whose duration equalled that of a complete random stream of pulses, plus a fixed period of time. It is assumed that the time between any two pulses in the stream does not exceed this fixed period. A short-term stability was all that was necessary.

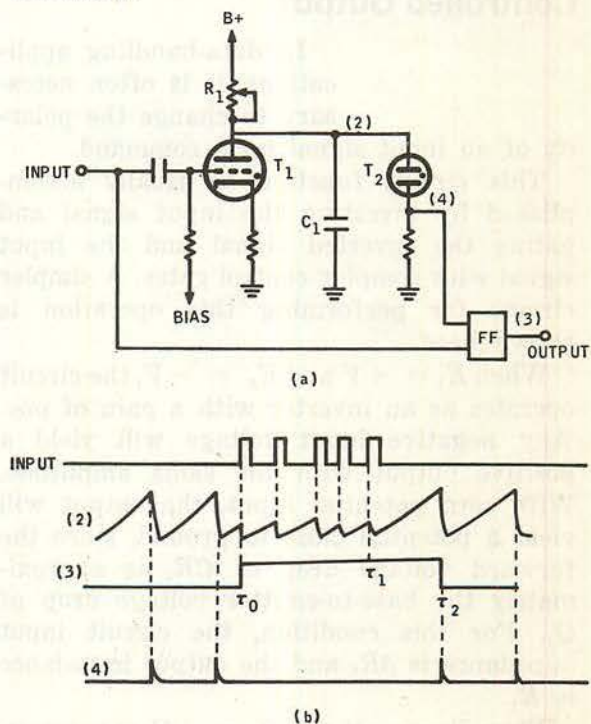


Fig. 1. Flip-flop pulse gate (a) provides gating waveform (b) for random pulse train.

## COMPUTER AND PULSE CIRCUITS

Fig. 1a shows a simple method to accomplish the above. The operation is as follows:  $T_1$ ,  $R_1$  and  $C_1$  comprise a free-running sawtooth generator. The breakdown voltage of  $T_1$  is higher than that of  $T_2$  so that the output at the cathode of  $T_2$  in the quiescent condition (previous to time  $t_0$  in waveform (4) of Fig. 1b) is a series of pulses. When the first input pulse arrives it fires  $T_1$  before its plate voltage reaches the breakdown potential of  $T_2$ . Initially the flip-flop was reset by the pulses at point (4), so that the initial input pulse sets the flip-flop at time  $t_0$ . At time  $t_1$  the last pulse ends and permits  $C_1$  to charge to the breakdown potential of  $T_2$ . The flip-flop is now reset and waveform (3) results, where ( $t_2 = t_1$ ) is the desired fixed period of time. By varying  $R_1$  the designer can compensate for any long-term changes in  $T_2$ .

*Irving Bayer, senior member technical staff, Radio Corp. of America, New York, 13, N. Y.*

### Transistor Stage Yields Polarity-Controlled Output

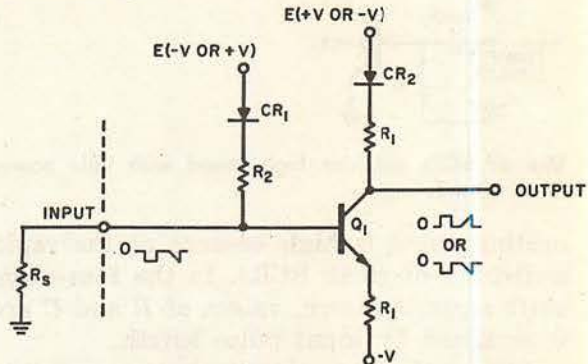
In data-handling applications, it is often necessary to change the polarity of an input signal upon command.

This circuit function is usually accomplished by inverting the input signal and gating the inverted signal and the input signal with complex control gates. A simpler circuit for performing this operation is shown here.

When  $E_1 = +V$  and  $E_2 = -V$ , the circuit operates as an inverter with a gain of one. Any negative input voltage will yield a positive output with the same amplitude. With zero potential input, the output will yield a potential close to ground, since the forward voltage drop of  $CR_2$  is approximately the base-to-emitter voltage drop of  $Q_1$ . For this condition, the circuit input impedance is  $\beta R_1$  and the output impedance is  $R_1$ .

When  $E_1 = -V$  and  $E_2 = +V$ , the circuit acts as a direct path between the input and output. Transistor  $Q_1$  saturates, since the

back-biasing of  $CR_2$  causes the collector load impedance to become very large. The collector is clamped to the emitter and hence follows it. Therefore, the collector voltage will be equal to the input voltage less the base-to-emitter voltage drop of  $Q_1$ . The input impedance to the saturated transistor becomes  $R_1$ .



Reversing supply voltage polarities provides positive and negative outputs.

To keep the output quiescent level at ground,  $R_2$  biases the base to  $+V_{BE}$ . The value of  $R_2$  depends on the value of  $R_1$ , the forward voltage drop of  $CR_1$  and the source impedance  $R_s$ . The input impedance to the circuit in the saturated condition becomes  $R_1$  in parallel with  $R_2$ . The output impedance is  $R_1$  in parallel with  $R_2$  and  $R_s$ .

Control for this circuit can be derived from either a switch or a pnp multivibrator. Inputs can be any unidirectional signal. Refinements of this circuitry technique can adapt the circuit for special applications.

*Frank A. Rappolt, engineer, Airborne Instruments Laboratory, Melville, L. I., N. Y.*

### SCR Charge-Discharge Circuit Samples Slow Rep-Rate Pulses

Amplitudes of pulses with very slow repetition rates—1 sec or more—must often be sampled in low-impedance transistor circuits. If the pulses are supplied by a low-impedance source, the charged-capacitor detector circuit shown in the figure can be used to good advantage. Because silicon controlled rectifiers are used to charge and discharge the capacitor, this unit can be made very large.

At time  $t_0$ , capacitor  $C$  is discharged to ground by the recycling pulse gating 'on'

**SCR 1.** This pulse occurs just before the sampling pulse.

When the current through **SCR 1** drops below the holding current, the SCR will turn itself off. **SCR 2** is then fired by the sampling pulse and the generator charges up the capacitor to the pulse voltage. Here, again, the SCR will turn off, when the current through it drops below the holding current, and the capacitor will then discharge through the load.

The maximum current through the SCR will be determined primarily by the turn-on time of the device, the generator impedance, and the amount of capacity used in the circuit. Current through the SCR is given by:

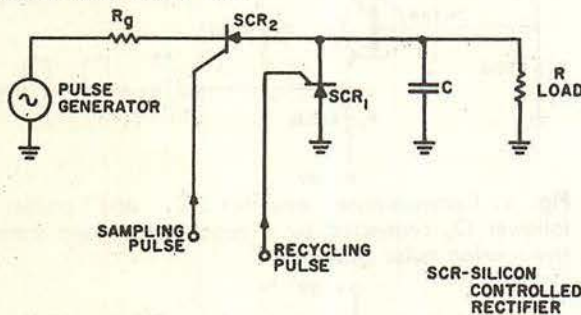
$$i = C \frac{dv}{dt}$$

where  $C$  is the capacitance,  $dv$  the amount of voltage in which the capacitor is to be charged, and  $dt$  is determined by the SCR turn-on time or the  $R_g C$  time constant (whichever is greater).

The turn-off point of the SCR depends on when the current through this device drops below the holding current,  $i_h$ . The current through the capacitance is determined by:

$$i = \frac{E_p}{R_p} e^{-t/R_p C} \text{ (neglecting } R_L)$$

When this is below the holding current the SCR will turn off.



Amplitudes of slow repetition rate pulses are stored on capacitor  $C$  which is charged and discharged through SCRs 1 and 2.

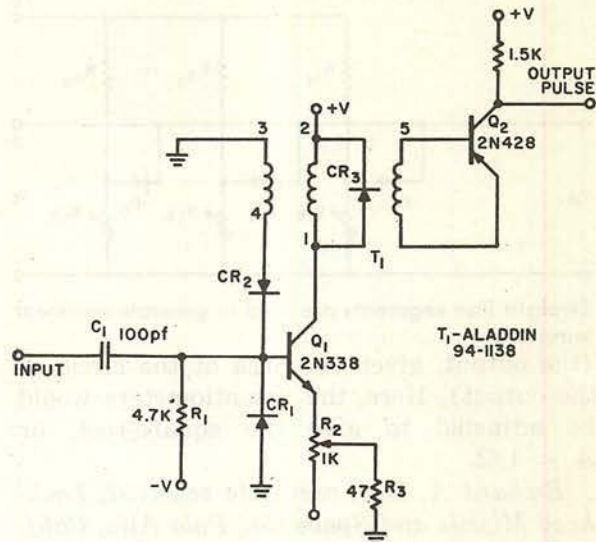
Vito Del Guercio, electrical engineer, International Telephone and Telegraph Laboratories, Nutley, N. J.

## Variable-Width Pulse Generator Provides Fast Rise/Fall Times

Stable, low-impedance, variable-width pulses suitable for shift register clear, shift or read-in pulses can be ob-

tained from the generator shown here. The pulse width is adjustable from 2 through 15  $\mu\text{sec}$ .

The generator is triggered by a positive pulse or transition which saturates  $Q_1$ . Transformer coupling provides a positive regenerative pulse to the base of  $Q_1$ . The amplitude of the feedback is controlled by  $R_2$ . When  $R_2$  is minimal the feedback sustains an output for approximately 15  $\mu\text{sec}$  when



Pulse width of generator output varies less than  $\pm 10$  per cent over temperature range for airborne equipment.

$R_2$  is maximum the output is approximately 2  $\mu\text{sec}$ .

The transformer-coupled output is utilized to cut off a pnp stage and provide a positive output pulse. Diodes  $CR_1$ ,  $CR_2$  and  $CR_3$  are utilized to prevent negative transitions from causing false triggering. Rise and fall times are from 0.1 to 0.2  $\mu\text{sec}$ .

David W. Gray, Electronic Communications, Inc., St. Petersburg, Fla.

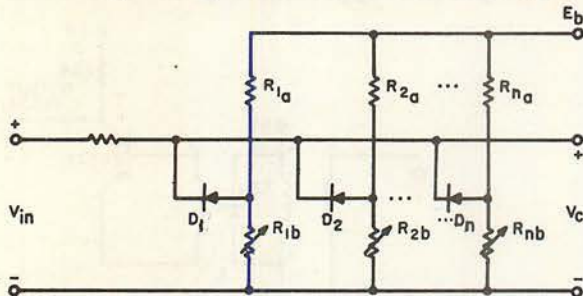
## Root Taker Using Biased Diode Networks

Often, a given quantity must be raised to a fractional or a decimal power. This circuit performs such an operation by taking an analog voltage input  $V_{in}$  and producing an output  $(V_{in})^A$ , where  $A$  is any decimal number less than one.

Output voltage  $V_o$  is a nonlinear function of the input. It is adjusted by means of

## COMPUTER AND PULSE CIRCUITS

the variable potentiometers  $R_{1b}$  through  $R_{nb}$ . The required nonlinear characteristic is generated by straight-line segments approximating the desired fractional power curve. An application for the device would be, for instance, solving for the diameter of a circle



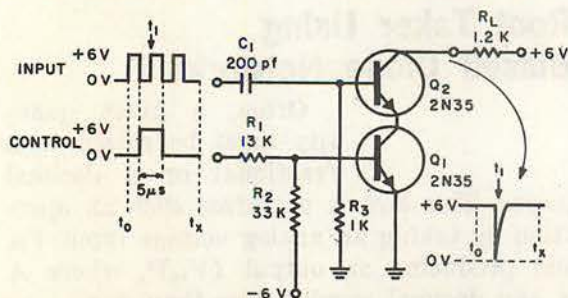
**Straight line segments** are used to generate nonlinear waveform.

(the output, given the area of the circle as the output). Here, the potentiometers would be adjusted to give the square-root, or  $A = 1/2$ .

*Richard A. Dye, associate scientist, Lockheed Missile and Space Co., Palo Alto, Calif.*

## Gate Circuit Inhibits Pulses on Command

We required a gate circuit for our logic system that would pass or inhibit positive-going pulses on command. The input (signal to be gated) was a Gv square-wave train of pulses that could be at any frequency from dc to 200 Kc. The control (gating signal) was to have two levels; +Gv open, and 0v closed. The circuit decided upon is shown in the diagram. When  $Q_1$  is saturated by a control signal greater



**Simple gate** is opened by saturation of  $Q_1$  by pulse larger than 4 v.

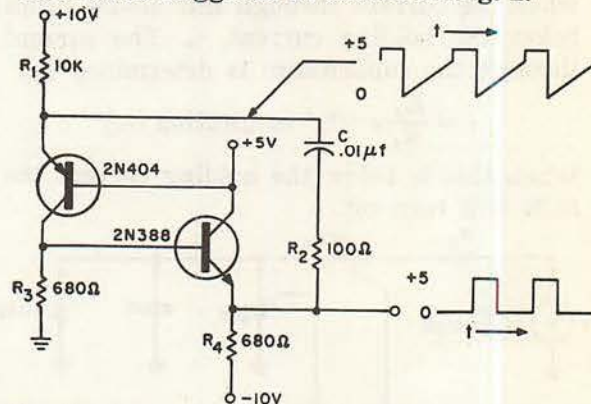
than +4 v, the gate is open and an input pulse will, after being differentiated by  $C_1$  and  $R_3$ , saturate  $Q_2$ . It thereby presents the inverted  $Q_2$  base signal at the collector of  $Q_2$ , as shown. In practice,  $R_L$  is usually the load in a flip flop or monistable.

*R. Rehfeldt and V. Gavoiosi, electronic engineers, Computer Systems, Inc., Monmouth Junction, N. J.*

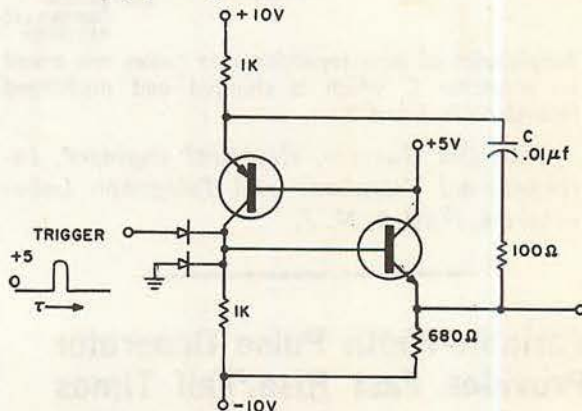
## Two-Transistors, Feedback Produce Free-Running Pulsar

A regenerative loop consisting of a common-base amplifier,  $Q_1$ , driving an emitter follower,  $Q_2$ , produces a simple, free-running pulse generator, Fig. 1. Pulse width is controlled by  $R_2C$  and pulse repetition rate is controlled by  $R_1C$ .

With only a slight modification the circuit can be triggered as shown in Fig. 2.



**Fig. 1.** Common-base amplifier  $Q_1$  and emitter-follower  $Q_2$  connected by a regenerative loop from free-running pulse generator.



**Fig. 2.** With slight modification circuit of Fig. 1 may also be externally triggered.

*Paul Lucas, design engineer, Adage, Inc., Cambridge, Mass.*

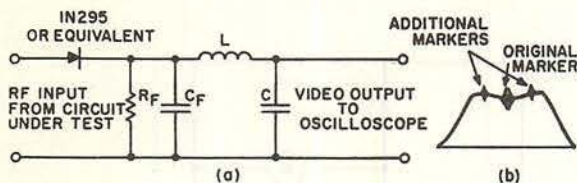
## MEASUREMENT AND TEST CIRCUITS

### Modified Detector Adds Markers For Frequency Response Tests

The frequency response of tuned circuits is usually observed on an oscilloscope by using a swept-frequency generator and an am detector. One or more fixed-frequency sources, called markers, help to identify specific frequency points on the response curve.

By slightly modifying the usual detector circuit, two additional markers can be created for each actual one. These are located symmetrically on either side of the original marker.

The arrangement is useful for the production alignment or the checking of band-pass circuits. Here, the original marker is set to the desired center frequency and the additional markers indicate the desired 1 db or 3 db bandwidth points.



**Fig. 1.** (a) Detector, modified by LC combination at output, produces additional marker pips for frequency response tests of tuned circuits. (b) Typical oscilloscope pattern circuits such as tuned lf or rf amplifiers.

Shown in the figure are the modified detector circuit and a typical frequency response pattern that can be obtained with a single marker source. The detector circuit is conventional except for the series LC combination on the output side.

The central "pip" in the response curve is the usual one caused by the swept-frequency zero-beating the marker generator frequency. Beat frequencies significantly higher than zero are normally bypassed by the detector filter capacitor  $C_F$ . But, at the frequency for which  $L$  is series resonant with  $C$  and  $C_F$ , there is an enhancement of the beat frequency component in the output.

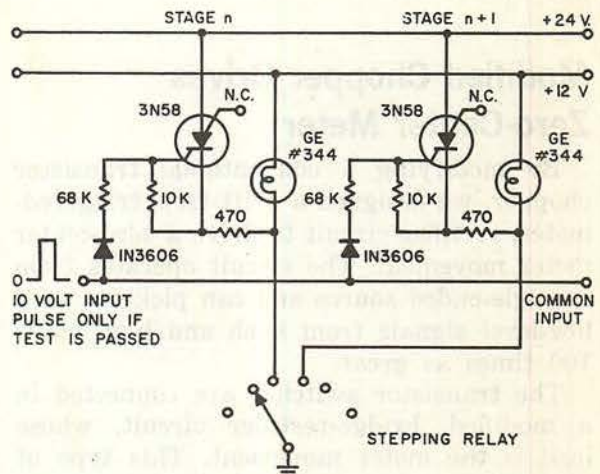
Because of this series resonance, the additional "pips" are created on either side of the zero-beat point. The frequency separation of the side markers from central marker is  $1/2\pi LC_T$ , where  $C_T$  is the series combination of  $C$  and  $C_F$ . For best results, a high impedance oscilloscope input should be used. However, any capacitance associated with the input simply will be added in parallel with  $C$ .

In equipment to be shipped, it has been found useful to connect the modified detector to a test point to aid in-the-field troubleshooting.

*John T. Zimmer, staff engineer, Raytheon Co., Wayland, Mass.*

### Visual Readout for Tester Uses Silicon-Controlled Switch

Stepping relays are frequently used to sequence a series of tests on electronic components such as transistors and diodes. The circuit shown in the diagram will provide a visual indication of which test is being



**Silicon-controlled switches** and lamps indicate those tests in a sequence that have been passed. performed and if the test has been passed.

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The stepping relay position is indicated by a lamp connected from ground to +12 v. If the device passes the test, a 10-v common input pulse turns on only the silicon-controlled switch at the relay location. When the relay sequences to the next location, the grounded terminal of the lamp is returned to +24 v through the silicon-controlled switch and 470-ohm resistor in series. Consequently the lamp remains on at reduced intensity, indicating the test was passed. If the device fails the test, no input pulse occurs and the silicon-controlled switch is not turned on. The lamp will then turn off as the relay sequences to the next position.

If a low-impedance input line is used, the 1N3606 diodes can be eliminated since their purpose is to isolate the line from changes in load.

The lamps are reset by opening the +24-v supply momentarily. If voltage is reapplied too rapidly the lamps may relight. This can be avoided by replacing the type 3N58 silicon-controlled switches with 22-K resistors connected between the anode gate (N.C.) and a 24-v supply which is not interrupted. An alternate solution is to connect a 0.005- $\mu$ f capacitor across the switches.

*Erwin Pacia, General Electric Co., Semiconductor Products Dept., Syracuse, N. Y.*

## Modified Chopper Drives Zero-Center Meter

By modifying a conventional transistor chopper, we designed a drift-free, triggered-meter, rectifier circuit to drive a zero-center meter movement. The circuit operates from a single-ended source and can pick out very low-level signals from hash and hum levels 100 times as great.

The transistor switches are connected in a modified, bridge-rectifier circuit, whose load is the meter movement. This type of circuit has several inherent advantages over other triggered-meter rectifier circuits.

Since the transistors are used only as on-off devices, and no dc amplification is re-

quired at the output, there is essentially no dc drift. Zero adjustment is not needed.

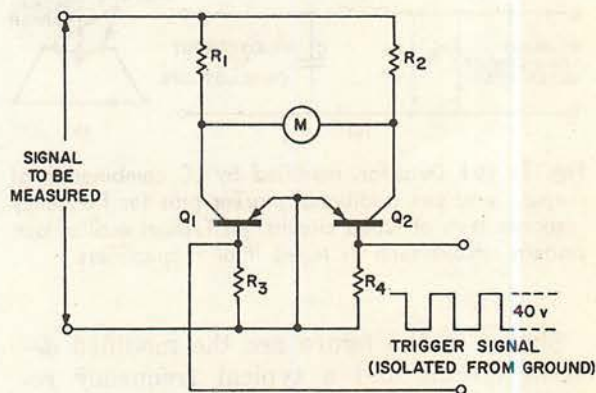
Also, since it is a bridge circuit it operates at high efficiency from a single-ended signal source. This eliminates the need for transformers or phase inverters. The circuit can operate directly from a signal source of at least 5 v rms. And, it can easily be isolated from ground.

The circuit is particularly adaptable to meter amplifier circuitry using current feedback for linearization, since the ac return is completely floating. Designed with the components listed, the largest detectable error was 0.3 per cent of full scale.

The trigger signal need not be a perfect square wave. It should be at least 40 v peak-to-peak and must be isolated from the system ground. In this circuit, the trigger was derived from a 35 v rms transformer winding with a 10-K series resistor and two 20-v Zener diodes back-to-back.

Input impedance of the circuit is approximately 20 K. Input voltage should be approximately 4.4 v rms (in phase with the trigger signal) for full scale deflection.

A balanced dc output voltage for driving recorders or external control circuits is available across the meter terminals.



**Transistor chopper** connected in modified bridge rectifier circuit, drives zero-center meter with essentially no dc drift. Circuit values are:

$R_1, R_2$ —33 K, 1/2 w, 5%

$R_3, R_4$ —27 K, 1/2 w, 10%

$Q_1, Q_2$ —2N220 transistors

$M$ —100-0-100  $\mu$ a, 1,000  $\Omega$ , movement

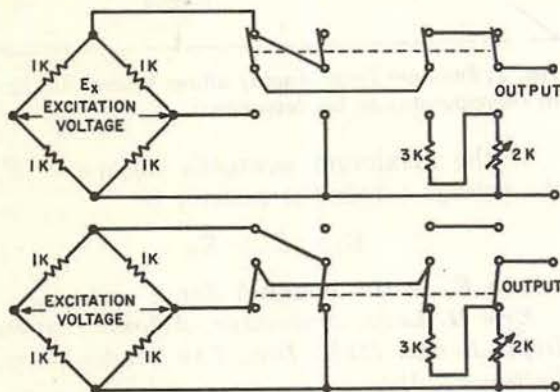
*Don Gephart, Staff Engineer, Ohio Semiconductors, Div. of Tecumseh Products Co., Columbus, Ohio.*



## Technique For Simulating Strain-Gage-Transducer Signal

It is generally agreed that shunt-resistance signal simulation is not suitable for the semiconductor strain-gage transducer. This is due to the relatively large change in bridge resistance with applied input and the high temperature sensitivity of the semiconductors. However an alternate method could be used. The components needed are shown in the diagram.

When a simulation signal is required, the output terminals of the transducer are shorted out, and one of the output connections is transferred to one of the input terminals. The voltage across the output leads will be close to half of the excitation voltage,



Attenuation section of strain-gage signal simulator could be incorporated in common signal conditioner.

dependent on the matching of bridge resistors.

The ratio between this voltage and the rated output voltage is slightly more than 2 to 1. To bring the simulated signal down to a voltage suitable for recording or transmission, an attenuator, or voltage divider is used. Using a 3-K and 2-K resistance in series will provide a voltage across the 2-K resistance of about  $\frac{2}{5} \times \frac{E_x}{2}$ . With 25-v excitation this will produce a signal fairly close to that of rated output. The described resistance combination will also provide an input impedance to the signal conditioner or recorder, similar to that of the transducer proper.

Any malfunction of the strain-gage bridge will show up as a drastic change in the simulated signal. The latter is in a fixed ratio relationship with the rated output and also directly proportional to the excitation voltage.

The temperature effect on the simulated signal is negligible, amounting to less than 0.2 per cent of rated output over a temperature change of 200 F.

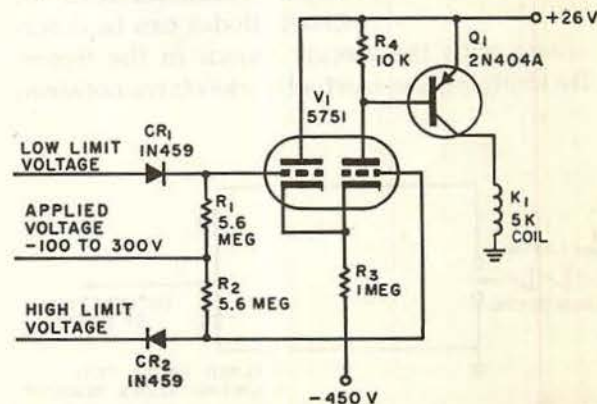
The difference in simulated signal with no pressure or rated pressure applied to the transducer, is about 0.5 per cent of rated output.

This form of simulation also is applicable to the standard wire-type strain-gage transducer. For a 500-ohm bridge with a 10-v excitation and 30 mv rated output the attenuation would be about 200 to 1, which could be accomplished with a 100-K and a 500-ohm resistor in series. Again the impedance presented to the recording or readout device basically would be unchanged. In a telemetry system this method will have the advantage of the elimination of the calibration resistor. The attenuator will be common for all similar transducers. Shorting the output terminals and switching over the output lead easily can be done on a stepping switch, which also will introduce the attenuator into the output circuit when signal simulation is required.

*Sigmund Meieran, engineer, The Boeing Co., Seattle, Wash.*

## Voltage Band Comparator Uses Tube-Transistor Circuit

We require a simple circuit that would energize a relay as long as an applied voltage remained within a high and low limit. The voltage could vary several hundred



Tube-transistor circuit opens relay when applied voltage is outside of preselected limits.

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volts, but a maximum of  $1 \mu\text{a}$  could be drawn from the source. The circuit was required to respond within about one volt of the limits, which could be anywhere in the range of applied voltage.

The circuit designed to meet these requirements is shown in the diagram. As long as applied voltage is within limits, neither of the diodes  $CR_1$  or  $CR_2$  conducts, and both grids see the same potential. Current is drawn through the left section of the tube, turning transistor  $Q_1$  on, which in turn keeps relay  $K_1$  energized.

If the applied voltage drops below the low limit, diode  $CR_1$  conducts, and a voltage develops across  $R_1$ . If the applied voltage rises above the high limit, diode  $CR_2$  conducts, and a voltage develops across  $R_2$ . In both cases the voltage drop appears as a potential difference between the two grids, shutting off the left section. Thus, outside the limits,  $Q_1$  is turned off, and relay  $K_1$  is de-energized.

*G. Richwell, staff engineer, Reflectone Electronics, Inc., Stamford, Conn.*

## Test Set Displays Zener Diode Characteristics

Several important functional characteristics of Zener diodes can be determined with the circuit shown in the figure. By applying the sawtooth waveform obtained

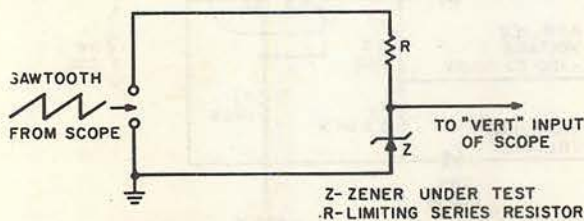


Fig. 1. Sawtooth wave form from scope is applied to Zener diode circuit.

from the scope, the resultant display of the Zener diode ramp allows:

1. The Zener voltage to be measured within the accuracy limits of the scope.
2. The Zener voltage change over the applied current range to be determined.
3. Some measure of the transient response characteristic to be obtained if time-base of the scope is varied.
4. The characteristics of the "knee" to be observed.

The value of the current-limiting resistor is determined from the manufacturers ratings of maximum current or power and the maximum voltage applied to the circuit.



Fig. 2. Resultant Zener display allows several functional characteristics to be determined.

If the maximum sawtooth voltage is  $E_p$ , the voltage across the resistor is:

$$E_R = E_p - E_Z$$

where  $E_Z$  is the nominal Zener voltage.

*Eric H. Levy, supervisor, Avionic Service Dept., Bendix Radio Div., The Bendix Corp., Baltimore, Md.*

## Automatic Continuity Detector Performs Double Test Function

This simple and reliable circuit will check the continuity of a conductor and simultaneously test that conductor against all other conductors in the system under high-voltage conditions.

The automatic continuity tester, of which this circuit is a part, can test 500 circuits at the rate of 10 circuits per second with an adjustable high-potential voltage from 100 to 1000 v dc. The components utilized in the detector consist entirely of resistors and a Western Electric type 280R differential relay.

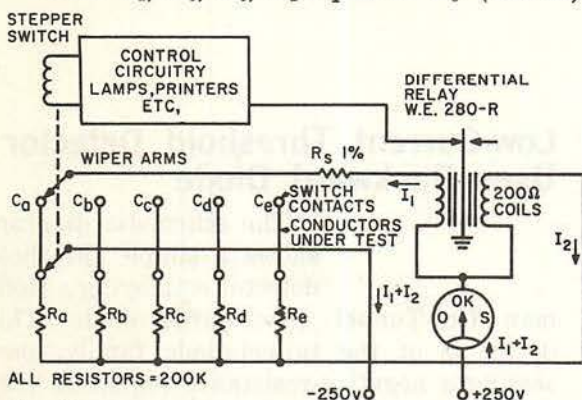
A relay of this type is constructed with a coil consisting of at least two electrically identical windings and a magnetically biased armature for sensing the direction of current through the windings. As shown in the schematic diagram, the continuity testing function consists of a summation of currents  $I_1 \pm I_2$  through the two windings of the relay. When  $I_1 = I_2$  the relay remains inactive, but when the balance is upset by either the opening of  $C_a$  or shorting of  $C_a$  to any other conductor, the relay operates.

This statement can be verified by starting at the +250-v point and tracing the circuit through both sides of the relay to the -250-v point.

The hi-pot function, performed each time a conductor is checked for continuity, is achieved as follows:

While  $C_a$  is being tested, a potential of -250 v is applied through the stepper switch arm; at the same time, +250 v is applied to all other conductors through their associated resistors,  $R_b, R_c$ , etc. Hence, the difference of potential existing between the conductor under test and all other conductors is 500 v.

With  $R_a, R_b, R_c, R_d$  equal to  $R_s$  (200 K)



**Simultaneous continuity** and high-voltage tests can be performed by means of a differential relay.

the circuit can detect 300-f K shorts between conductors. This sensitivity is made possible by the mechanical adjustment capabilities of the differential relay, which permit reliable and consistent operation down to 0.5 ma. Since these relays are factory-adjusted, only a slight modification is necessary and consists of manipulating the pole pieces until a current of 0.0005 amp operates and holds the armature against the contact associated with the energized winding.

One pole piece then is adjusted to keep the armature on one side, as indicated on the schematic, while maintaining a 0.0006-amp operating sensitivity. This adjustment in-

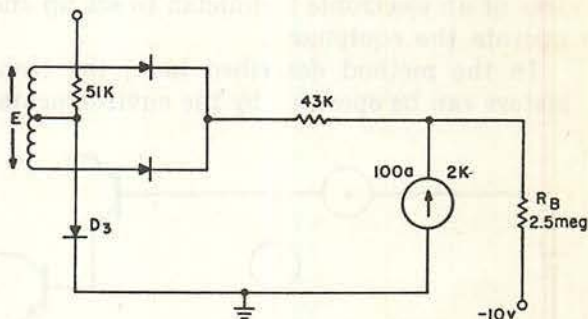
sures that the relay will remain balanced or inactive when no current or equal currents flow through the two windings.

To obtain the maximum amount of information from a reject circuit, a milliammeter was inserted in the total current line. Full scale was calibrated to twice  $I_1 + I_2$  so that a good circuit was indicated on the meter as half-scale reading. When an "open" reject (less current) was encountered, the meter read less than mid-scale and when a "short" reject was encountered the meter read more than mid-scale. With the meter labeled "open," "good" and "short", valuable troubleshooting information is gained.

*Frank L. Egenstafer, project engineer, Jerrold Electronic Corp., Hatboro, Pa.*

## Biased Diode Reduces Non-Linearity of AC Meters

Ac metering circuits are non-linear because of the non-linear impedance of rectifier diodes. The effect of the non-linearity can be reduced by making the excitation voltage very large compared with the diode voltage drop of approximately 0.5 v. However with transistorized circuitry, large voltages are troublesome.



**Biased diode  $D_3$**  in ac metering circuit overcomes the effect of 0.5 v diode voltage drop; circuit operates with greater linearity.

An alternate approach is to add the dc biased diode,  $D_3$ , and bleeder resistor,  $R_B$  as shown in the figure. Sufficient dc bias current is passed through  $D_3$  to exceed the maximum (peak) current required by the

## MEASUREMENT AND TEST CIRCUITS

meter. The best linearity, it has been found, is achieved with the bias current through  $D_3$  approximately twice the peak current.

The circuit values indicated in the schematic yielded 1 per cent linearity with a  $100 \mu\text{a}$ , 2,000-ohm meter movement and an applied voltage,  $E$ , of 10 v rms. To achieve similar results without  $D_3$ , required voltages greater than 50 v.

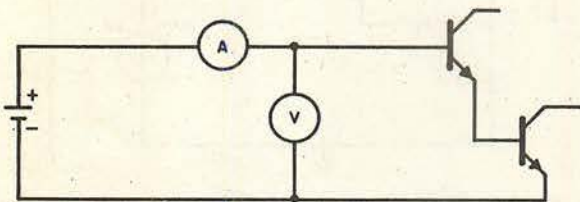
*Carl L. Bose, senior engineer, Nortronics Div. of Northrop Corp., Hawthorne, Calif.*

## Burned Out Transistors Save Time and Money in Heat Tests

In design of circuits using power transistors, heat-dissipation tests frequently are run with the transistors mounted on heat sinks. To be valid, these tests should be run using mockup heat sinks and equipment as close to the final package design as practical. The same type of power transistor should be used in the mockup and the final package.

With some types of silicon power transistors costing \$100 or more a piece, it is expensive to risk these valuable components in these tests. Also, the control of dissipation in multiple transistor circuits requires the services of an electronic technician to set up and operate the equipment.

In the method described here, the transistors can be operated by the environmental



Simple series circuit provides controlled dissipation for heat tests.

test technicians because a simple, stable series circuit is used.

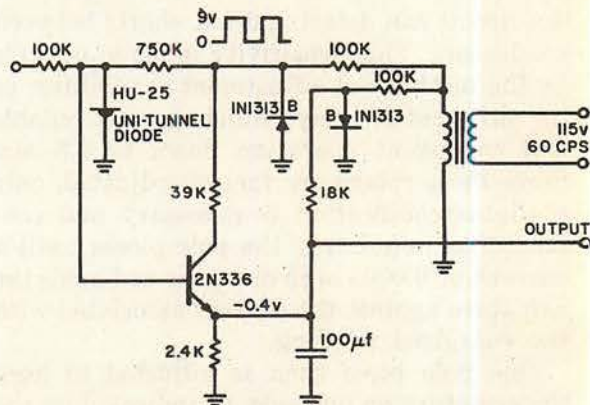
We have found that burned-out (shorted collector-to-emitter) transistors of the same case type as those to be used in the equip-

ment make good resistors for these heat tests. (Burned-out transistors are usually in good supply around development labs.) The burned-out transistors are mounted on the heat sinks and a low voltage high-current source is connected base-to-emitter or collector-to-emitter. The base-to-emitter resistance usually is higher. (Typical resistance for a 2N1016 was 1.8 ohms for a current of 10 amp.) By monitoring current and voltage, the wattage desired can be dissipated in the exact mechanical configuration of the final equipment. In most burned-out transistors, the base diode is still intact so the current must be passed in the forward direction of the base diode.

*Frederick W. Paget, advanced development engineer, Sylvania Electric Products, Inc., Sylvania Electronic Systems, Needham, Mass.*

## Low-Current Threshold Detector Uses Backward Diode

The schematic diagram shows a simple threshold detector employing a Hoffman Uni-Tunnel (backward) diode. This device is of the tunnel-diode family, possessing a negative-resistance region at very low current. Peak current for this diode is at about  $20 \mu\text{a}$ .



Threshold detector is sensitive to inputs of less than  $7 \mu\text{a}$ .

The dc input signal is applied to the HU-25, together with a square-wave current obtained from one of the 1N1313 regulators. Below the trip point the diode acts essentially as a very low impedance, and the square-wave voltage across it is on the order of 10 mv or less. As the dc input current at which this ac voltage will suddenly jump to about 0.4-v peak. In the circuit shown, this occurs for an input current of slightly less than 7  $\mu$ a. Input power is less than 5  $\mu$ watt.

The 2N336 is supplied with a 9-v square wave supply to the collector through the 39 K resistor and an emitter bias of about 0.4 v. Under these conditions the collector voltage is a square wave of about 7-v peak. When the HU-25 switches the 0.4-v signal on the base is sufficient to saturate the transistor and the output drops to zero.

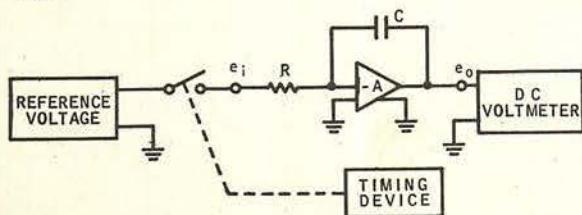
*Richard F. Shea, consulting engineer-electronics, General Electric Co., Schenectady, N. Y.*

## Comparator Circuit Simplifies Integrator Time-Constant Check

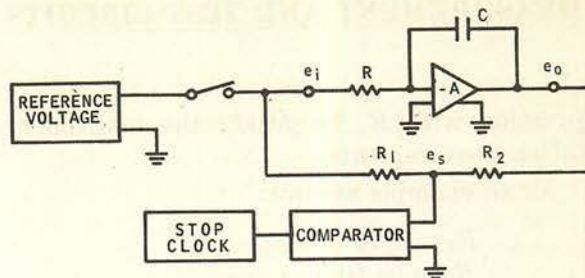
A conventional method for checking the time-constant accuracy of electronic integrators is shown in Fig. 1. This procedure is costly and elaborate in that it involves an accurately controlled reference voltage, a precision timing mechanism and a digital or balancing-type dc voltmeter. By this method an output voltage ( $e_o$ ) measurement is obtained after a known input voltage ( $e_i$ ) has been applied to the integrator for a controlled period of time ( $t$ ). The time constant ( $RC$ ) then is determined from the integration equation:

$$\frac{e_o}{e_i} = - \frac{t}{RC}$$

The method shown in Fig. 2 provides a simpler and less costly approach to the problem.



**Fig. 1.** Conventional measuring technique requires high-accuracy instrumentation.



**Fig. 2.** Stop-clock-comparator gives voltage ratio without determining actual voltage.

Precision resistors  $R_1$  and  $R_2$  are chosen to provide a summing voltage ( $e_s$ ) equal to zero when the output voltage is some desired multiple of the input voltage. The summing point is connected to the input of the dc voltage comparator which, in turn, operates to stop an electric stop clock (or electronic counter) when the summing voltage is zero.

Application of the input voltage will start the clock. When  $e_o/e_i = R/R_1$ , the summing voltage will be zero and the clock will stop. Thus, the elapsed time  $t$  is found, the voltage ratio  $e_o/e_i$  is known (without knowing the actual voltages) and the time constant may be determined from the integration equation as before.

*Richard F. Cutler, project engineer, Sperry Utah Co., Salt Lake City, Utah.*

## Reducing Effect of Intermittent Instrumentation Loads

Five identical sensor elements are used in a control system. However, the summing network equivalent impedances are different, necessitating the addition of resistor  $R_e$  to provide a constant 10-K load to the sensor secondary, as in Fig. 1a. When selected on this basis, the intermittent connection of the instrumentation load reduces the equivalent impedance to  $10 \cdot 105/115 = 9.13$  K. This change in impedance results in a 1-v drop in the sensor output voltage. This creates difficulties in calibration and acceptance.

The problem was solved by using the circuit in Fig. 1b. Here,  $R_1$  and  $R_2$  are selected so that the sum of their values compensates  $R_e$  to the desired 10 K equivalent. Resistor  $R_1$  is made larger than  $R_2$  so that the effect of connecting  $R_e$  is minimized. The final ratio of  $R_1$  to  $R_2$  must be compromised to provide sufficient voltage at their

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junction with  $R_g$  to satisfy the instrumentation requirements.

As an example assume:

$$R_L = 18 \text{ K}$$

$$R_e \text{ to be } 10 \text{ K}$$

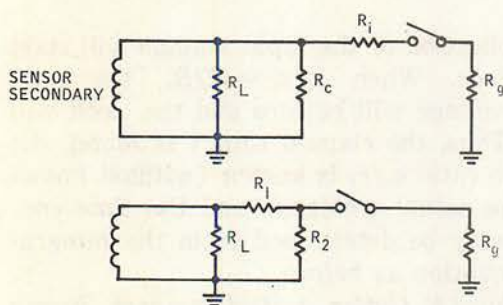
then

$$R_1 + R_c = 22.5 \text{ K} \left( 10 = \frac{18R_c}{18 + R_c} \right)$$

let

$$R_1 = 16 \text{ K}$$

$$R_2 = 6.5 \text{ K}$$



$R_g$  = INSTRUMENTATION LOAD  
 $R_i$  = ISOLATION RESISTOR  
 $R_L$  = EQUIV. LOAD  
 $R_c$  = COMPENSATION RESISTOR

Fig. 1. Modification of sensor circuit reduces effect of loading.

with  $R_g$  connected

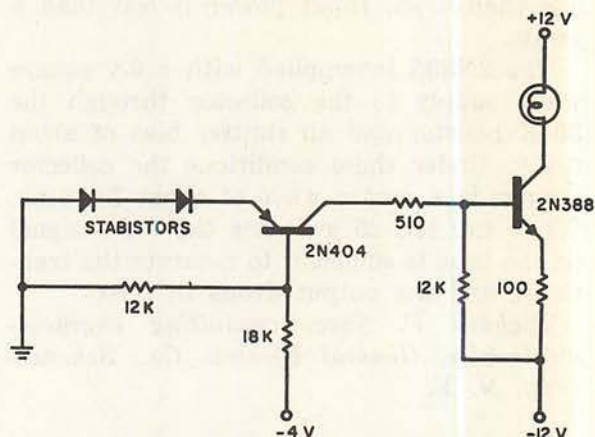
$$R_c' = 16 + \frac{6.5(30)}{36.5} = 21.35$$

$$\text{Required: } \frac{18(21.35)}{39.35} = 9.75 \text{ K}$$

*R. L. Stoval, project engineer, The Bendix Corp., North Hollywood, Calif.*

## DC Presence Indicator Checks Three Voltages

The circuit shown here will indicate presence of all three voltages in a typical pnp digital system with negative collector and clamp supplies, and a positive bias supply. An npn system could use the complementary version of the circuit. Fail-



All three voltages must be present in modified AND gate to have bulb light.

ure of any one of the voltages will extinguish the "dc-presence" lamp.

The circuit is a modification of the typical transistor AND circuit. The conventional circuit will not indicate properly because of voltage incompatibility. The pnp-npn AND circuit shown in the diagram uses the three voltages as inputs.

The pnp-npn circuit detects in a true AND function. Absence of any one voltage will extinguish the lamp. The stabistors provide a tight control over the error level of the clamp voltage. Resistor  $R_4$  limits the initial current surge present during turn-on of a cold bulb.

*Daniel Chin, development engineer, Computer Control Co., Inc., Framingham, Mass.*

### Band Switcher Uses Light-Sensitive Resistors

We have devised a band-switching circuit using light-variable resistors that has been successful in a number of multirange, low-power oscillating devices. The circuitry is simple and rugged. And, it eliminates a costly rotary switch that has low rf leakage, because our switch does not carry any rf at all.

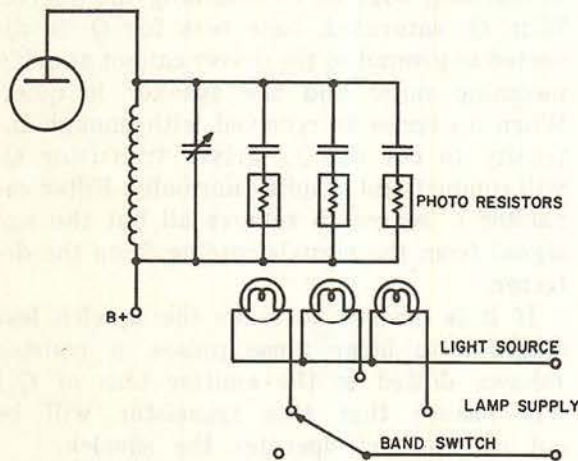


Fig. 1. Bandswitching is accomplished by shining light on photosensitive resistors and shorting out sections of the oscillator coil.

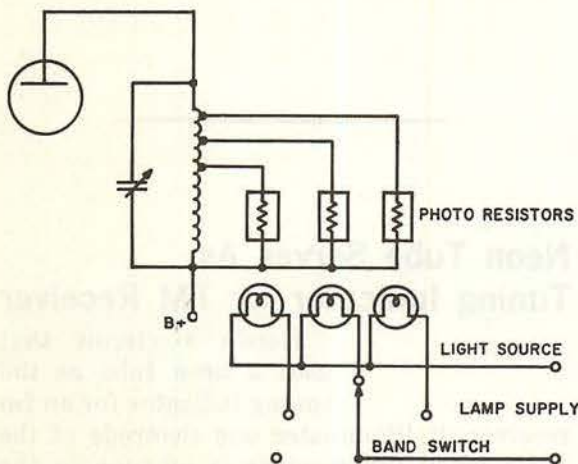


Fig. 2. Alternate bandswitching configuration also is feasible.

Light-variable resistors, connected across successive portions of an rf inductor, Fig. 1, are used for the switching. Illuminating any of the photoresistors with an essentially saturating light source effectively shorts out the portion of the coil bridged by the resistor. This changes the tuning characteristics of the LC circuit.

This scheme could be the solution to a multitude of problems associated with receiver and oscillator design, and in remote-control and telemetering applications.

An alternate configuration is shown in Fig. 2.

*R. M. Zilberstein, project engineer, Andersen Laboratories, Inc., West Hartford, Conn.*

### Forward Biased Diode Gives Protection for Crystal Filters

Electrical characteristics of crystal filters may be permanently damaged if large input voltages occur, even for short intervals. In some receivers, for example, the amplifiers before the crystal filter are controlled by a relatively slow-acting agc circuit, and it is possible for very large signals to be momentarily impressed upon the filter input. The simple circuit shown in Fig. 1 effectively prevents large signals from reaching the filter.

Resistors  $R_2$  and  $R_3$  are for dc path and termination purposes, respectively. A path is provided through  $R_1$  for a constant current to bias  $CR_1$  in the forward direction. The maximum peak-to-peak voltage that may exist across the filter input is determined primarily by the dc current through  $R_1$ , multiplied by the parallel combination of the crystal input  $Z$  and  $R_2$ . For normal signal amplitudes  $CR_1$  is always conducting and transfers all of the signal to the filter. When a large input signal exists,  $C$  acquires a charge as shown and biases  $CR_1$  in the reverse direction so that it conducts for only a portion of each cycle, limiting the crystal

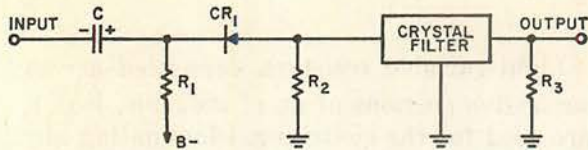


Fig. 1. Crystal-protection circuit shunts voltage peaks through  $R_1$ .

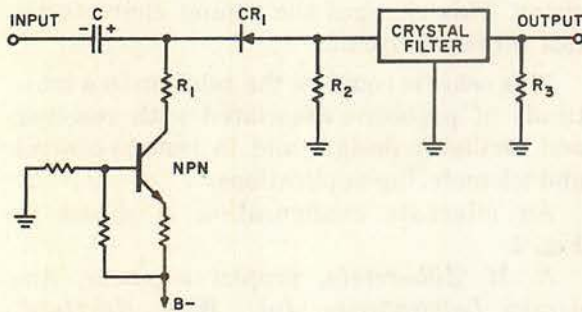


Fig. 2. Use of transistor with  $R_1$  maintains constant current.

filter input. The polarity acquired by  $C$  forces a larger current through  $R_1$ , which should be reasonably constant for good protection. The  $B-$  voltage may be increased to provide a more constant current or  $R_1$  may be replaced in part by a transistor, as shown in Fig. 2.

These circuits also may be used for amplitude limiting.

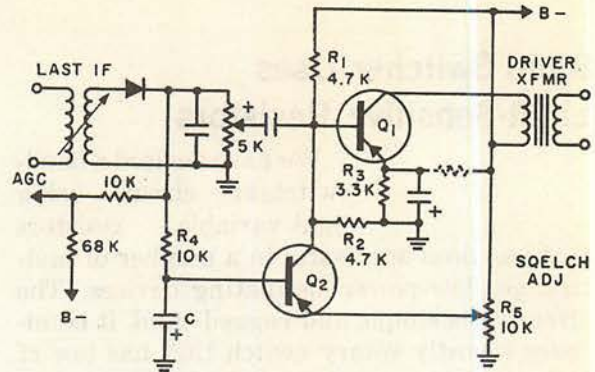
*M. F. Feller, engineer, General Dynamics Corp., San Diego, Calif.*

## Computer Circuit Provides Simple Transistor Squelch

Adapting transistor-computer circuits to radio work can provide simple control circuits capable of handling complex jobs. A good illustration is the transistorized squelch circuit shown in the diagram.

This simple, but positively operating circuit calls for minor component value changes in the audio circuit and only four additional components,  $R_4$ ,  $C$ ,  $R_5$  and the blocking transistor,  $Q_2$ . In a short-wave transistor radio, the circuit will make the set function as a monitor receiver; or, inserted into a inexpensive citizens band transceiver, the circuit will up-grade its performance.

Without an input signal, normal IF amplifier forward bias flows in the age bus. A



Switching circuit is adapted to audio squelch system.

portion of this bias voltage is applied to the base of  $Q_2$ , biasing this transistor into full conduction, with  $R_5$  determining the degree. With  $Q_2$  saturated, base bias for  $Q_1$  is diverted to ground so the driver cannot amplify incoming noise and the speaker is quiet. When a carrier is received with enough intensity to cut off  $Q_2$ , driver transistor  $Q_1$  will conduct and amplify normally. Filter capacitor  $C$  serves to remove all but the age signal from the signals coming from the detector.

If it is desired to make the squelch less sensitive to large noise pulses, a resistor (shown dotted to the emitter bias of  $Q_1$ ) will ensure that this transistor will be cut off until rf operates the squelch.

Component values given are merely representative and should be arrived at by cut-and-try methods in each case.

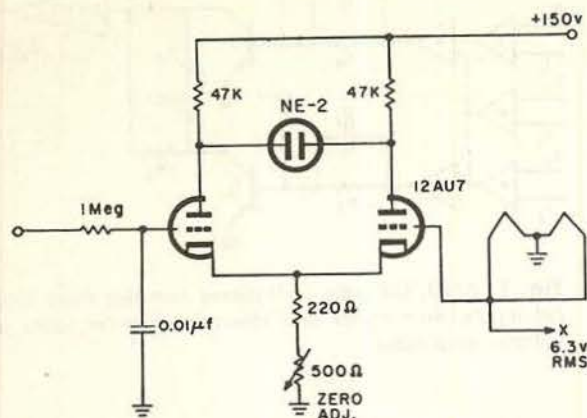
*Leonard E. Geisler, senior applications engineer, Apollo Industries, Ltd., Tokyo, Japan.*

## Neon Tube Serves As Tuning Indicator for FM Receiver

Here's a circuit that uses a neon tube as the tuning indicator for an fm receiver. It illuminates one electrode of the NE-2 when the receiver is off-tune in the high direction, and the other electrode when off-tune in the low.



On-tune (zero volts input), the 60 cps part of the plate voltage keeps both electrodes



Neon-tube fm tuning indicator can be added to circuit of fm receiver.

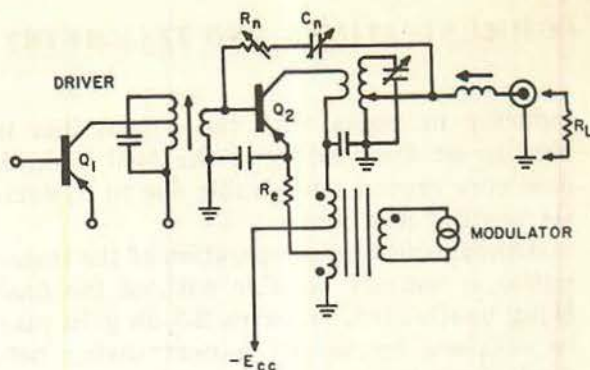
fired, so the tuning transition is smooth. A  $\pm 1$  v swing from the discriminator is ample for clear indication. This compares favorably with the performance of the GAL7 indicator tube.

M. W. Egerton, Jr., engineer, Towson Laboratories, Towson, Md.

## Linear Modulation Of Transistor Power Amplifiers

Separate modulation of the collectors of both the driver and the final of am transistor power amplifiers has been recommended as the only way to obtain 100 per cent modulation without excessive distortion.

The approach described here yields highly satisfactory results with only the final stage modulated. The basis of the system is simultaneous modulation of both the collector and emitter by application of audio signals that are 180 deg out of phase. The base drive to the final is not varied. As the result, demodulated output of a transmitter using this system has a characteristic distortion-free, "punchy" quality, which greatly extends the range of operation by comparison with simple collector modulation. The circuit of a typical class C final is shown in the diagram.



High level modulation of transmitter final is obtained by applying modulation to both emitter and collector.

When modulation is applied in series with the collector supply of a class-C transistor final, the height of the collector-current pulses varies within the transistor limits. If a lower amplitude of modulation, shifted by 180 deg, is simultaneously fed in series with the emitter return, the transistor operating point will be moved along the  $h_{FE}$  curve and the power content of the collector current pulses will be greatly increased on modulating wave crests.

Since driver loading by the final decreases during troughs of the modulating waveform, the drive tends to rise just enough to prevent downward carrier modulation on large "negative" modulation peaks.

Oscilloscope inspection of the driver waveform shows no appreciable variation at any normal level of modulation.

It was found, pragmatically, that over-coupling between driver and final must be avoided, or the final will depart from true class-C operation with consequent inefficiency and distortion.

The value of  $R_e$  is arrived at by experiment. The emitter resistor is varied while the final modulated output waveform is observed on an oscilloscope. When a perfect trapezoid is obtained at maximum modulated rf output, the value of  $R_e$  may be permanently set, using a fixed 10 per cent tolerance resistor.

Although transistor parameter spreads vary considerably, this system is extremely tolerant, hence economically feasible for use on the production line for applications with transistorized radio-telephone equipments.

In practice, we found it necessary, due to the very low output impedance of transistors operated at low values of  $E_{cc}$ , to link-couple the transistor to the tank coil. We thus were able to preserve a good operating  $Q$  of between 30 to 45. A brass-slug tuned

inductor in series with the output line is used to set fine loading of the final tank. A dust core proved undesirable due to hysteresis heating and losses.

Although servicable operation of the transmitter is entirely possible without the final being neutralized, an extra 2-3-db gain may be obtained by use of a neutralizing network. Such a network also tends to improve over-all performance.

Neutralization must be adjusted while the final is modulated 100 per cent by a 1-Kc sine wave and output is monitored by a cathode-ray oscilloscope connected directly across the output terminals with the dummy load. A perfectly clean trapezoid is indication of correct operation of the final.

Design of a transmitter final, using this modulation system, closely follows vacuum-tube practice except for impedance differences. The modulation transformer impedances are determined in the usual vacuum-tube fashion.

It is possible to use this same system with grounded-base finals if the designer allows for varying loading on the driver due to the modulation's effect on the final transistors' emitter.

*Leonard E. Geisler, senior applications engineer, Apollo Industries, Ltd., Meguro, Tokyo.*

### AND/OR Gate Multiplexer Uses Voltage-Amplitude Coding

The circuit in Fig. 1 codes the intelligence from three logical signals for transmission through a long, single conductor to a remote station, where the signals are decoded and used as required. The coding is done in terms of voltage amplitude.

Fig. 2 shows the output voltage vs control-signal timing.

If  $Q_1$  is true at time  $P_1$ , transistor  $T_1$  saturates, and the output voltage  $V_1$  is calculated by:

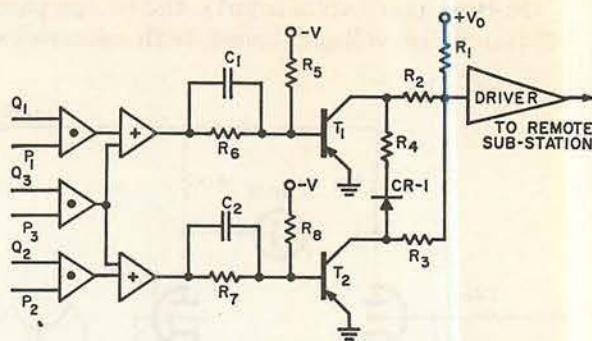


Fig. 1. AND/OR gate multiplexer samples three logical inputs, then codes and transmits them in terms of voltage amplitude.

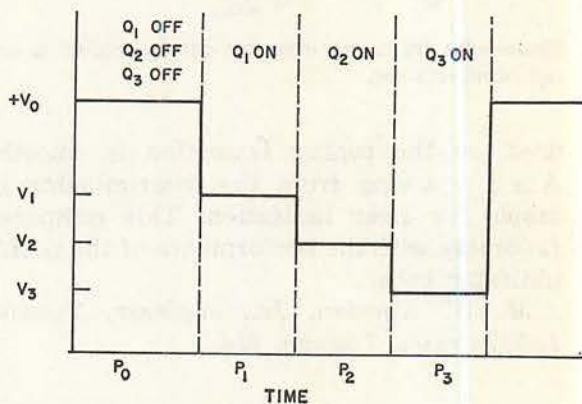


Fig. 2. Output voltage vs logical input for sampling times  $P_1$ ,  $P_2$  and  $P_3$ .

$$V_1 = V_0 \left[ \frac{R_2(R_3 + R_4)}{R_1R_2 + R_1R_3 + R_1R_4 + R_2R_3 + R_2R_4} \right] \quad (1)$$

Similarly, if  $Q_2$  is true at time  $P_2$ , transistor  $T_2$  saturates and  $V_2$  is:

$$V_2 = V_0 \left[ \frac{R_3}{R_1 + R_3} \right] \quad (2)$$

If  $Q_3$  is true at time  $P_3$ , both  $T_1$  and  $T_2$  saturate and  $V_3$  is:

$$V_3 = V_0 \left[ \frac{R_2R_3}{R_1(R_2 + R_3) + R_2R_3} \right] \quad (3)$$

Germanium diode  $CR-1$  and resistor  $R_4$  conduct only when  $T_1$  is saturated and  $T_2$  is cut off. Their purpose is to reduce the voltage of the first step at  $P_1$ , so that changes between voltage steps are equal.

*Jack McGruder, electrical engineer, Hughes Aircraft Co., Fullerton, Calif.*

## Reducing Power Dissipation In Emitter-Follower Circuits

The emitter-follower circuit shown in Fig. 1a is used to send digital information over a transmission line into a load represented by  $R_L$ . In this circuit it is desirable to have  $i_e$  as large as possible (and, therefore, have  $R_1$  as small as possible) in order to (1) reduce the rise time—this time

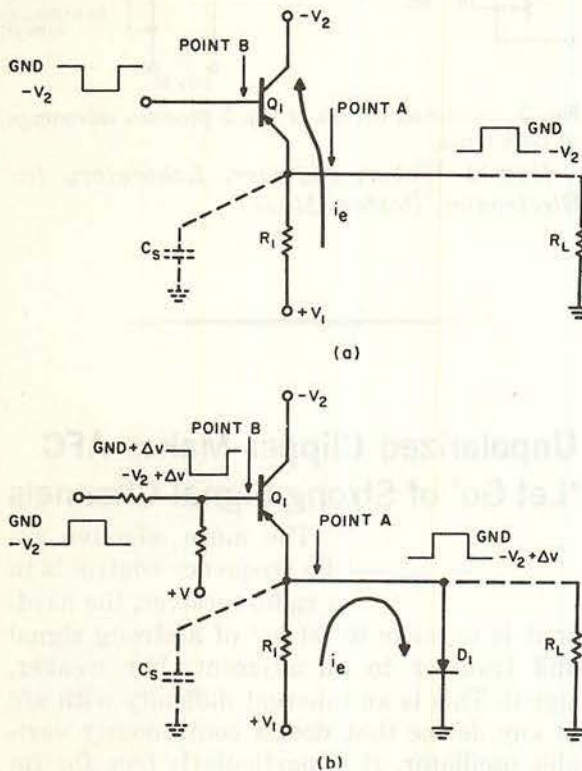


Fig. 1. Basic emitter follower (a) is modified by adding diode (b) to reduce current through transistor.

is a function of  $R_1$  and the stray capacitance  $C_s$ , (2) provide for impedance matching between the load and source, and (3) reduce any noise which could feed back from the line through  $Q_1$ . When the input is at the  $-V_2$  potential, the power dissipation in  $Q_1$  is small because the voltage drop across  $Q_1$  is negligible; but when the input is at ground potential the power dissipation equals  $i_e V_2$ . Thus the maximum power dissipation rating of  $Q_1$  can be the limiting factor for  $i_e$ .

To increase  $i_e$  and still not exceed the maximum power-dissipation rating of  $Q_1$  the circuit shown in Fig. 1b is recommended. Here a biasing network inserted at point B, and a clamping diode inserted at point A is used to modify the original circuit. When the input signal goes to ground, point B is

biased slightly positive, the emitter-to-base junction of  $Q_1$  is then back-biased because point A is clamped to ground through  $D_1$ , and  $Q_1$  cannot conduct. Thus the previous power-dissipation problem is eliminated because the current through  $Q_1$  is zero, and a transistor having a much smaller power dissipation rating can be used. The current,  $i_e$ , which previously went through  $Q_1$  to the collector now goes through  $D_1$  to ground.

Norton Markin, engineer, Sherman Oaks, Calif.

## Current Overload Protectors Use Simplified Designs

Many an engineer's face has turned as red as the anode of the power tube he was working with, when he glanced at the plate-current meter and observed that it was indicating much greater current than normal.

Although most modern tubes will not be severely damaged by a momentary overload, the problem is a constant threat to the engineer of high power equipment using expensive tubes and components.

Many commercial communications and broadcasting transmitters and other industrial equipment include automatic overload protection. These overload circuits are frequently quite complex.

In the simple protective device shown in Fig. 1, a warning light is turned on if excess

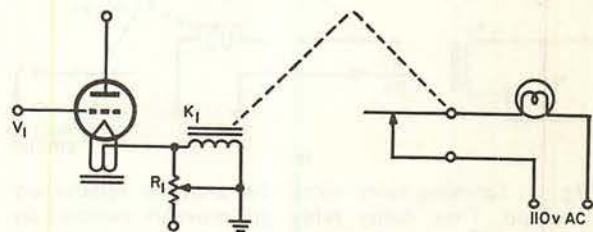


Fig. 1. Basic circuit provides indication of tube overload.

current is drawn. The circuit requires only the addition of a paralleled relay and potentiometer ( $K_1$  and  $R_1$ ) in series with the filament or cathode return of the power tube. The potentiometer's value must be such that when paralleled with  $K_1$ , the voltage drop of the combination is equal to the pull-in voltage of the relay at the maximum current of the

circuit. This can be computed by:

$$R_1 = \frac{E_{K1}}{I_{max} - \left(\frac{E_{K1}}{R_{K1}}\right)}$$

where:  $E_{K1}$  = operating voltage of relay  $K_1$ ,  
 $R_{K1}$  = dc resistance of  $K_1$ ,  
 $I_{max}$  = maximum circuit current in amps.

For example, if a 24-v, 200-ohm relay is used,  $R_1$  is 300 ohms to limit the maximum current to 0.2 amp. Since the pull-in voltage of a relay is lower than the operating voltage,  $R_1$  is made adjustable and can be set to adjust the sensitivity of the relay. If the pull-in voltage of the relay is known, the pull-in voltage may be substituted for  $E_{K1}$  in the formula. The resistance of a relay and, therefore, its sensitivity change significantly with heat. Pull-in current should be set after the relay has reached operating temperature. Wattage rating of the resistor may be computed from:

$$P = E_{K1} \left( I_{max} - \frac{E_{K1}}{R_{K1}} \right)$$

More sophisticated control circuits can be derived from this basic circuit configuration. Fig. 2 demonstrates two possibilities. In Fig.

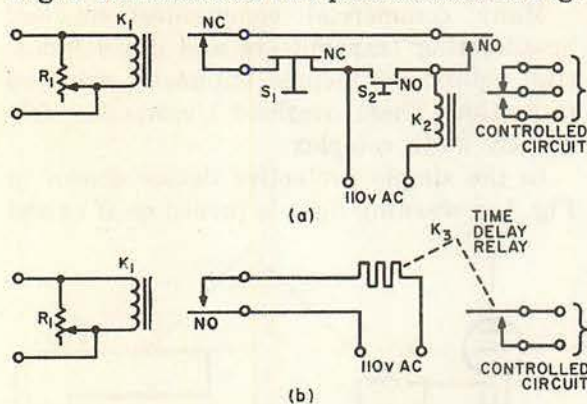


Fig. 2. Latching relay circuit (a) provides release on overload. Time delay relay (b) prevents release on momentary overloads.

2a, when an overload occurs, latching relay  $K_2$  opens due to the breaking of the latch contact by the normally closed contacts of  $K_1$ . In the circuit shown, pushbutton  $S_2$  latches and  $S_1$  releases the circuit.

Fig. 2b demonstrates a method for overcoming the releasing of  $K_2$  on transients or momentary overloads, as would be the case with Fig. 2a. A short-cycle thermal relay is employed. A delay of 3 to 10 sec normally

would be adequate. The delay should equal the longest anticipated normal momentary overload, such as is encountered when returning a transmitter tank circuit. A further sophistication may be achieved by consolidating the circuits of Fig. 2 into the circuit shown in Fig. 3.

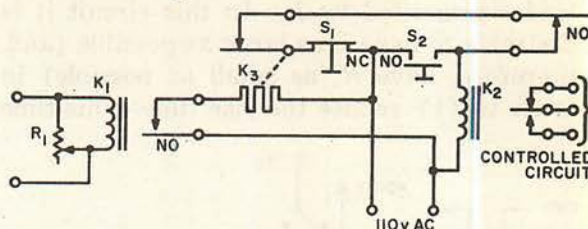


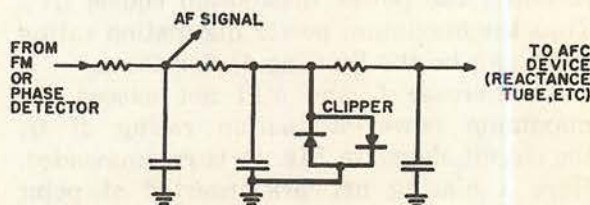
Fig. 3. Combined circuits of Fig. 2 provides advantage of both types.

Harold Weber, engineer, Laboratory for Electronics, Boston, Mass.

## Unpolarized Clipper Makes AFC 'Let Go' of Strong Signal Channels

The more effective audio frequency control is in a radio receiver, the harder it is to make it 'let go' of a strong signal and transfer to an adjacent, but weaker, signal. This is an inherent difficulty with afc in any device that uses a continuously variable oscillator. It is particularly true for fm receivers that have broadband IF and derive the afc bias from the fm detector. With full afc action it may be impossible to tune in weaker channels without first disabling the afc.

Of several possible methods for disabling afc, adding an unpolarized dc clipper, as shown, proved to be the simplest. It can be added to any afc without disturbing the original circuit and without adding tubes or tuned circuits.



Clipper added to circuit prevents development of large afc bias voltages, which can swamp out weak signals.

The clipper can consist of two very low voltage Zener diodes or, each "diode" can consist of 7 to 9 small selenium plates in series. (The latter arrangement uses the forward knee of the rectifiers.)

At or near center tuning the full gain of the afc circuit is available for holding on to weak signals. When tuning away from strong signals, the clippers prevent large afc bias from being developed. They permit the signal to be released so that weak adjacent channels can be received.

In the Craftsmen C500 receiver in which the clipper was installed, it was found that if it limited maximum afc bias to 1.5-2.5 v, the results were excellent. (Without the clipper, strong signals produced as much as 20-25 v maximum bias, completely swamping out nearby weaker channels.)

*Louis W. Reinken, Reinken Rectifier Engineering, Plainfield, N. J.*

The voltage drop across  $R_1$  is also maximum under this condition and is used to bias  $Q_2$  on. Current through  $Q_2$  is determined by the value set on the variable resistor  $R_2$ . If  $R_2$  is set so that the current flow in  $Q_2$  causes the voltage drop across  $R_3$  (which is also the emitter resistor of  $Q_3$ ) to be greater than the voltage from base-to-ground minus  $V_{be}$  of  $Q_3$ , then  $Q_3$  is turned off. Under these conditions, there is no output from  $Q_3$  and the receiver is quiet.

Now, assume that a signal is being picked up by the receiver. Under this condition, when the agc is acting, the current through  $Q_1$  is reduced by an amount depending on the signal strength. When this occurs, the voltage drop across  $R_1$  is reduced, thus reducing the collector current through  $Q_2$ . This produces a lower voltage drop across  $R_3$ . When this voltage becomes less than the voltage from base-to-ground minus  $V_{be}$ ,  $Q_3$  begins to turn on; this results in an output to the audio amplifier.

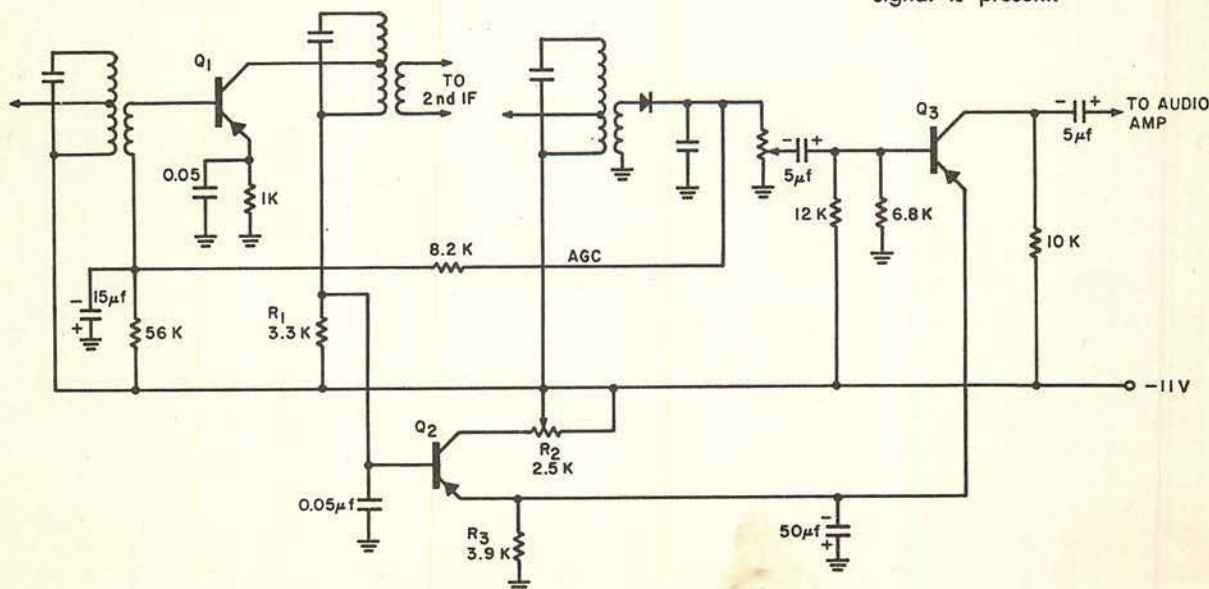
This circuit has been incorporated into citizens-band receivers with good results. It was found to be capable of squelching out up to a 300- $\mu$ v signal into the receiver and still maintain good control down to something less than 1  $\mu$ v.

It should be noted that between full on and full off conditions of  $Q_3$ , small amounts of collector current may result in some audio distortion depending on the volume-control setting. This distortion should not be ob-

## Transistor Squelch Circuit Uses Minimum of Components

A simple and inexpensive squelch circuit is designed for use with transistorized communications receivers is shown in the illustration. With no signal coming into the receiver, an agc-controlled IF amplifier,  $Q_1$ , is operating at its maximum collector current and gain.

**Squelch-control** transistor,  $Q_2$ , cuts off audio when no input signal is present.



## COMMUNICATIONS AND TELEMETRY

jectional and under ordinary operating conditions (where the signal received is many times greater than that required to just trigger the squelch), this distortion is not present.

When the squelch pot  $R_2$  is set to just squelch out any signal being received, approximately 3-db increase in signal level will completely override the squelch action. The amount of increase is dependent, of course, on the level of the original signal, the gain and sensitivity of the receiver and the amount of agc of the receiver.

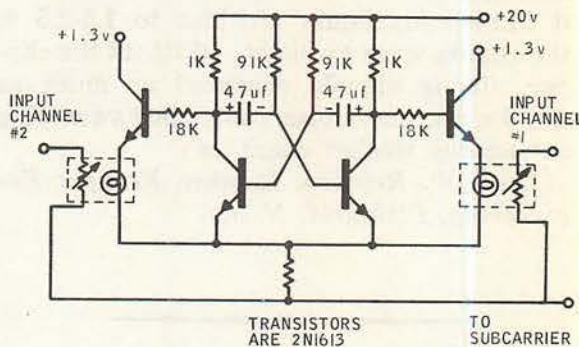
The IF transistor was set to idle approximately 0.75 ma under no-signal conditions. The squelch transistor may be any small-signal npn unit, such as the 2N1304; the audio transistor may be any small-signal pnp alloy, such as the 2N1274.

*Richard E. Morgan, Transistor Products Div., Texas Instruments Inc., Dallas, Tex.*

### Photoconductor Commutator Has Simplicity and Isolation

We needed an electronic, two-channel, low-rate commutator to be used with an fm-fm telemetry system. Such a

commutator was devised using the Raytheon CK1114 Raysistor. This is a photoconductive cell plus a grain-of-wheat lamp in a TO-5 case. By switching the lamp full on and off, the resistance of the photoconductor may be switched from 0.5 ohm to 300 megohms. Connecting two CK1114s to the input of a subcarrier oscillator and alternately switching them, we had a two-channel commutator with 300 megohms isolation between input channels to the telemetry system.



**Electrical isolation** in telemetry circuit is obtained by using light-controlled photoconductor.

The circuit is an astable multivibrator driving two transistor switches, which switch the lamps in the Raysistors alternately. Since the photoconductors are electrically independent of the lamps, the signal channels are electrically isolated from the switching circuit. Dc input signals may be of either polarity. The passband is flat from dc to 1 mc.

*C. G. Blanc, instrumentation engineer, R. C. Crawford, electrical technician, U.S.N.O.Y.S., China Lake, Calif.*

# SWITCHING AND RELAY CIRCUITS

## Flip-Flop Relay Driver Eliminates Emitter Follower

The conventional method of driving a solenoid or relay from a control flip-flop is to drive the transistor switch with an emitter follower. The follower, in turn, is

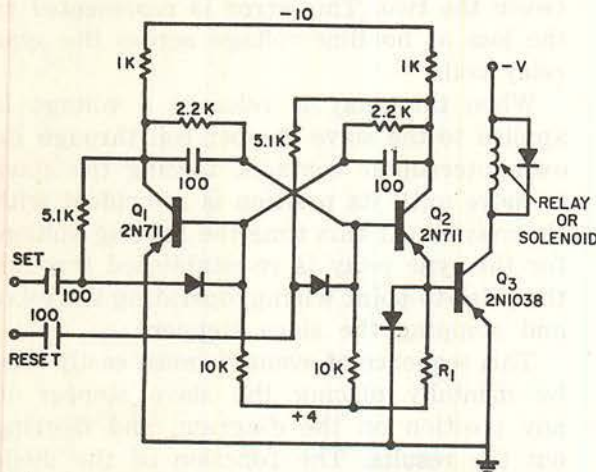


Fig. 1. Emitter follower is eliminated by putting transistor switch  $Q_3$  in the emitter circuit of driver.

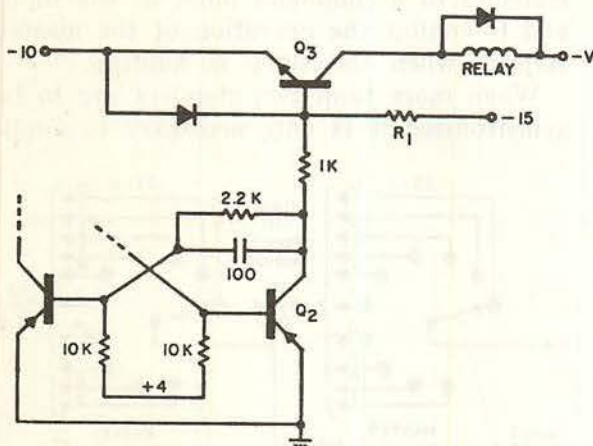


Fig. 2. Alternate switch driven method places switching transistor in collector circuit of flip-flop transistor.

driven by the flip-flop.

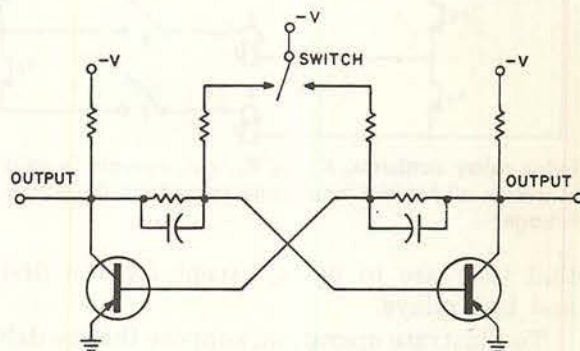
By putting the switch directly in the emitter circuit of one of the flip-flop transistors, the emitter follower can be eliminated. In Fig. 1,  $Q_2$  draws virtually all of its emitter current through the base of  $Q_3$ . Resistor  $R_1$  supplies  $I_{co}$  to the base of  $Q_3$ , and diode  $CR_1$  clamps the emitter of  $Q_2$  when  $Q_1$  is conducting.

An alternative method is shown in Fig. 2, using an npn transistor in series with the collector of  $Q_2$ . This, however, is slightly less efficient than the first circuit, because  $R_1$  must supply  $I_{co}$  and base current for  $Q_1$  when  $Q_2$  is cutoff.

*Phillip Joujon-Roche, engineer, Aeronautics, Newport Beach, Calif.*

## Multi-Buffered Switch Eliminates Contact Bounce

In circuits using toggle or push-button switches to generate digital logic levels or trigger signals, contact bounce may cause objectional noise voltages. However, this noise can be eliminated by letting the switch



Problem of contact bounce in switch-generated trigger signals is eliminated by using the switch to flip a bistable multi, then using the multi's outputs.

trigger an ordinary resistance-coupled bistable multivibrator as shown in the figure. The switch is a double-throw type. As it is thrown from one contact to the other, the complementary outputs of the multi provide fast, simultaneous switching, free of contact noise.

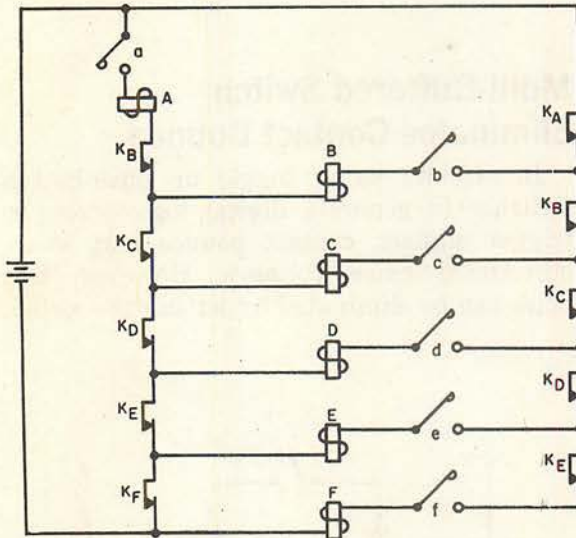
*Stewart T. Coffin, Head of Engineering, Dynamic Controls Co., Cambridge, Mass.*

## Relay Bridging Avoided Through Isolation Scheme

This circuit will prevent bridging or erroneous closing of relay contacts in a multiplexer, even when the drive switches have considerable chatter and could accidentally make contact. The circuit applies to any number of relays. Only two extra contacts per relay are required.

When any switch energizes a specific relay, no other coil can be energized until the contacts of the first relay change state.

In Fig. 1, the relay coils are designated *A, B, C, etc.*, and the corresponding switches that control them are labelled *a, b, c, etc.* The additional, normally closed contacts that provide circuit isolation are  $K_a, K_b, K_c, \dots$ ; note



Extra relay contacts,  $K_a, K_b, K_c, \dots$ , operate in pairs to isolate all but the functioning relay from the supply voltage.

that they are in pairs, except for the first and last relays.

To illustrate operation, suppose that switch *d* is closed. *D* is then energized and  $K_D$  (both poles) opens. The subsequent closing of any combination of drive switches *a, b, c, \dots* etc. cannot affect any other relay. Should the relays be of the make-before-break type, the shorting time is so much shorter than the closing delay that bridging still cannot occur.

The scheme may be applied to similar situations in solid-state logic gating.

*Patrick F. Howden, project engineer, Thompson-Ramo-Wooldridge Computers Co., Canoga Park, Calif.*

## Stepping Switch Provides Fool-Proof Synchronization

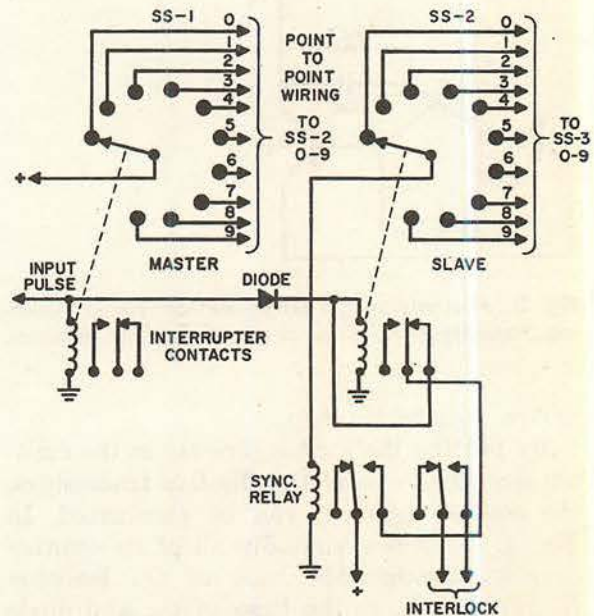
In the circuit configuration shown here loss of synchronization is virtually impossible. There is no way for the master and slave steppers to get out of step except by component failure.

The action of the sync relay is to detect, through the continuity of the point-to-point wiring, from the master to the slave steppers, an error in relative position between the two. This error is represented as the loss of holding voltage across the sync relay coil.

When the relay is released a voltage is applied to the slave stepper coil through its own interrupter contacts, forcing the slave to move until its position is coincident with the master. At this time the holding voltage for the sync relay is re-established through the point-to-point wiring, operating the relay and stopping the slave stepper.

This sequence of events is most easily seen by mentally placing the slave stepper in any position on the diagram, and figuring out the results. The function of the diode between the two stepper coils is to permit simultaneous operation of the steppers in response to a command pulse at the input and to inhibit the operation of the master stepper when the slave is hunting.

When more than two steppers are to be synchronized it is only necessary to dupli-



Loss of synchronization of stepping switches energizes slave stepper until proper position is found.



cate relay point-to-point wiring and supply a sync relay for each additional stepper. The contacts on the sync relay labeled "interlock" may be utilized to disable other circuits when the slave stepper is hunting. The only requirement for the sync relay is that it must stay closed between steps and must release fast enough to stop the slave units in the correct position.

*Frank L. Egenstafer, project engineer, Jerrold Electronic, Hatboro, Pa.*

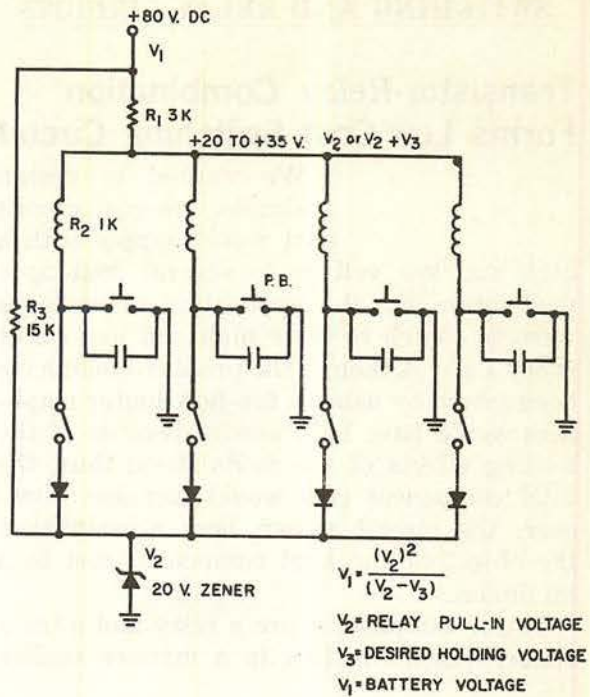


Fig. 1. Interlocks relay control requires only a single conductor for each relay.

## 'Constant-Current' Supply Interlocks Relay Network

Interlock circuits become complex when a large number of relays are to be remote-controlled by push-buttons, or where latching of a new relay must unlatch any previously energized relay.

The circuit of Fig. 1 permits these functions with only a single form A contact on each relay for the latching function. Additionally, the remote push-buttons require only a single wire plus common for each relay to be controlled.

In Fig. 1, a quasi-constant current source is obtained by starting with a battery voltage of at least four times the desired pull-in voltage for the relays, and inserting a resistor in series.

The low side of each relay coil goes to ground through a Zener diode rated at the pull-in voltage. This removes voltage from any previously latched coils when a new one is engaged. If reed type, or other fast relays are used, the capacitors shown across the push buttons are not required. With relatively slow drop-out on the relays, a previously engaged coil may not drop out if the button is tapped only momentarily. A firm touch on the button, shunt capacitors, or faster relays will cure the problem.

The power waste in the large series resistor usually is not serious since only one relay

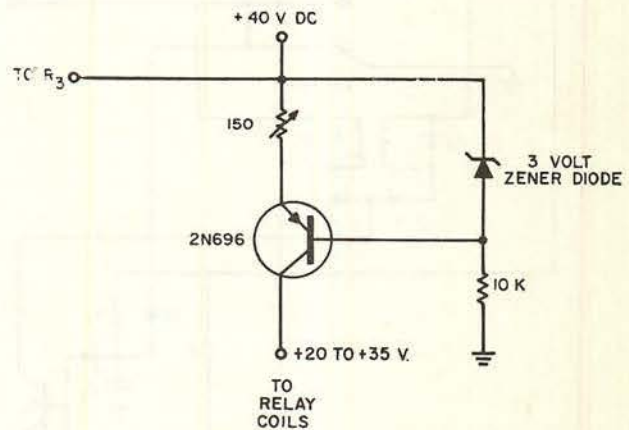


Fig. 2. Transistor regulator reduces power drain on constant-current source.

is energized at a time and the power involved is rather small.

Power loss can be reduced by using a more efficient constant-current source. This could be a fast barretter, a barretter and choke coil in series, or a transistor circuit, as in Fig. 2. The series diodes in the low side of each relay coil prevents the grounding of the Zener diode.

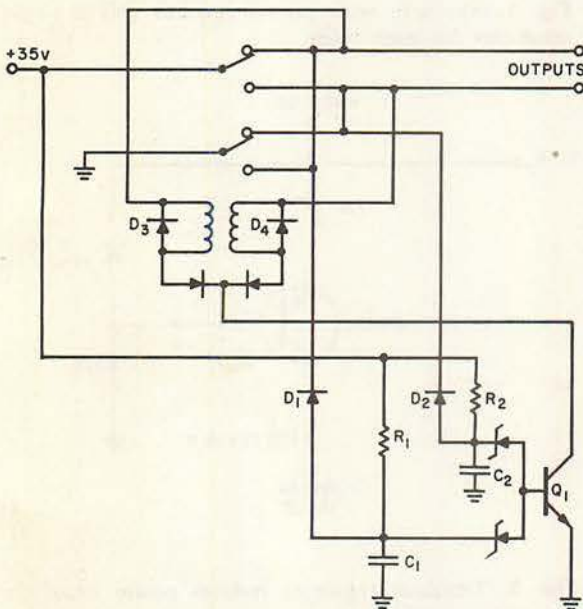
*Daniel Cronin, executive vice president Bell Sound Studios, New York, N. Y.*

## SWITCHING AND RELAY CIRCUITS

### Transistor-Relay Combination Forms Low-Cost Switching Circuit

We wanted to design a simple, low-cost circuit that would supply both a high and low voltage to several dual-input modulators. For this application, the voltages were to switch to their high and low states every 4 sec. Although the problem could have been solved by using a flip-flop, buffer amplifiers would have been needed because of the loading effects of the modulators; thus, the total component cost would increase. However, the circuit shown here accomplished the objective and kept component cost to a minimum.

Major components are a relay and a transistor, which function in a manner similar



Alternate charging of  $C_1$  and  $C_2$  provide flip-flop action.

to a multivibrator due to the R-C networks at the base of the transistor. The junction of  $R_1C_1$  (and  $R_2C_2$ ) is alternately connected to ground through the relay contacts. If the junction of  $R_1C_1$  is disconnected from ground,  $C_1$  will begin to charge to 35 v through resistor  $R_1$  when power is applied to the circuit. When the charge on  $C_1$  is +15 v dc, the Zener diode breaks down and transistor  $Q_1$  turns on. When  $Q_1$  is on, the relay is energized, the  $R_1C_1$  junction

becomes grounded,  $C_1$  discharges, and transistor  $Q_1$  turns off. Capacitor  $C_2$  now can begin to charge and the cycle is repeated.

*Michael Cianciola, V. Lemley, engineers, General Precision Inc., San Marcos, Calif.*

### Voltage-Controlled Relay Selector System

There are many applications requiring a relay system to work from a voltage-controlled device. Fig. 1 shows a circuit capable of closing three relays in 1, 2, 3 order as the input voltage is raised beyond 10, 12, and 15 v respectively. (The voltage levels are arbitrary so long as sufficient collector voltage is available to actuate the relays.)

The transistor base resistors ( $R_B$ ) are, in effect, limiting resistors that absorb any input voltage in excess of that needed to turn on the relays. Their values determine the turn-on sensitivity of the relay circuit. The following formulas can be used to calculate the sensitivity  $\Delta V$ , that is, the input voltage in excess of the Zener voltage required for relay turn-on:

$$V_{IN} = V_Z + \Delta V$$

$$V_{IN} \approx V_Z + R_B$$

$$R_B \approx \Delta V B / I_C$$

where

$V_{IN}$  = the minimum input voltage required for relay closing,

$V_Z$  = breakdown voltage of Zener diode,

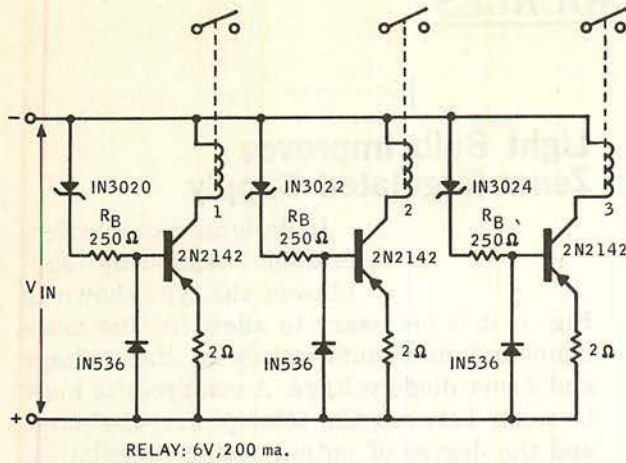
$I_C$  = collector current required for relay closing,

$B$  = dc current gain of the transistor, and

$R_B$  = base resistance.

The 2-ohm resistor and the silicon rectifier in the transistor emitter and base circuits form a clamp that limits the current into the relays when the input voltage rises to the firing levels of succeeding relays.

The characteristics of the silicon rectifier



As  $V_{in}$  is increased beyond 10, 12 and 15 v, relays 1, 2 and 3 are actuated in sequences.

(1N536) are such that the unit does not conduct until the voltage reaches a level of about 0.7 to 0.8 v. Typically, the base-emitter voltage of the transistor in the forward-biased condition is about 0.3 v. To cause the rectifier to conduct, the voltage drop across the 2-ohm resistor must be at least

0.4 v, corresponding to an emitter current of about 200 ma.

As the input voltage is raised enough to turn on the last relay, the current through the earlier relays normally would increase, resulting in excessive relay current through these stages. This increase, however, is held to a minimum due to conduction of the rectifier which clamps the emitter current to a predetermined level.

As the number of relays in such a system increases, the power dissipation of the transistors, which are controlled by the lower voltage Zeners, increases because of the higher collector-emitter voltages, and heat sinking must be provided.

The circuit shown has the advantage of rapid turn-off when the input voltage falls below the Zener control voltage since all base drive is then eliminated. This provides positive turn-off as the input voltage drops below the initial turn-on level.

*J. D. McCall, engineer, Motorola Semiconductor Products, Inc., Phoenix, Ariz.*

# POWER SOURCES

## Currector and Zener Diode Reduce Ripple In Power Supply

The constant current characteristic of a currector—a relatively new solid-state device—can be combined with the

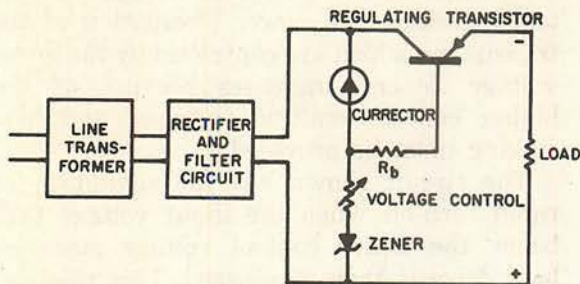


Fig. 1. Series connected currector-Zener reduces ripple in power supply.

constant-voltage characteristic of a Zener diode to give a simple power supply with very low ripple.

The ripple voltage appearing at the input to the base resistor is attenuated by the factor  $\frac{R_z + R}{R_z + R + R_c}$

where:

$R_z$  = dynamic resistance of the Zener, which is small.

$R$  = voltage control resistor, which may be kept small.

$R_c$  = dynamic resistance of the currector, which is very large.

Resistor  $R_b$  protects the transistor from excessive base current in case of a short cir-

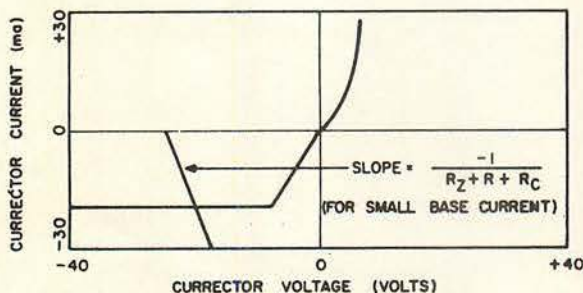


Fig. 2. Typical characteristics of currector.

cuit. This arrangement provides a simple, voltage controlable power supply with good regulation and low ripple.

Edward P. Mitchell, member of technical staff, Hughes Aircraft Co., Fullerton, Calif.

## Light Bulb Improves Zener-Regulated Supply

In designing simple Zener-diode regulating supplies of the type shown in Fig. 1, it is necessary to allow for the minimum and maximum values of line voltage and Zener diode voltage. A compromise must be made between the total power dissipated and the degree of output voltage regulation.

The voltage regulation of the power supply shown in Fig. 1 can be improved by increasing the secondary voltage of the transformer. But this results in higher power

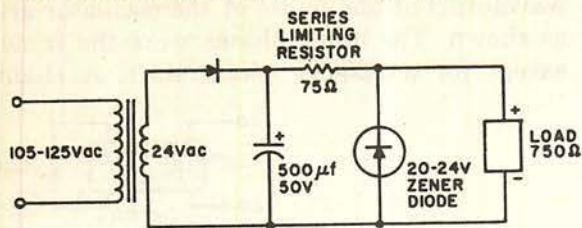
	75-ohm resistor	No. 1447 lamp
Minimum Zener Current	19 ma	20 ma
Maximum Zener Current	138 ma	57 ma
Minimum Zener Power	0.38 w	0.40 w
Maximum Zener Power	3.30 w	1.37 w
Maximum Lamp/Resistor Power	2.35 w	0.97 w
Maximum Total Power	5.65 w	2.34 w

dissipation in the series limiting resistor and requires higher voltage ratings for the capacitor and rectifier.

A significant improvement in over-all circuit performance can be achieved with no increase in cost by substituting a properly rated incandescent lamp for the series limiting resistor. The increase in the effective resistance of the lamp with applied voltage stabilizes the current through the Zener diode. For the case shown, the type 1447 lamp proved an ideal choice since it has a resistance of about 75 ohms under the minimum voltage conditions (minimum line voltage and maximum Zener voltage) and is within its nominal 18-v rating under maximum voltage conditions (maximum line voltage and minimum Zener voltage).

A comparison of the two cases is shown in the table. It is seen that the minimum Zener current is equal in both cases, as required. However, the total range of Zener current is three times larger with the resistor than with the lamp. The voltage regulation will, accordingly, be about three times better with the lamp than with the resistor.

With the lamp the total Zener power dissipation is low enough to permit a 3.5-w unit to be used conservatively. With the re-



**Circuit performance** of this simple Zener-diode regulated power supply can be improved by substituting incandescent lamp for the series limiting resistor.

resistor, a 10-w unit probably would be required. Since the average operating lamp voltage is approximately 2/3 its rated value a longer than usual lamp life can be expected.

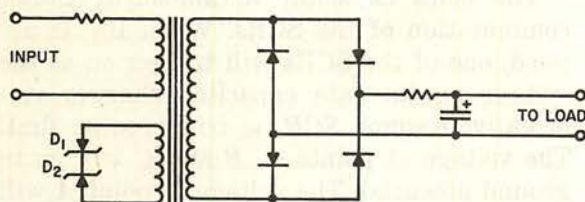
In addition to its function as a series regulating element the lamp also may serve as a pilot lamp or as a trouble-shooting aid.

*T. P. Sylvan, application engineer, General Electric Co., Syracuse, N. Y.*

## Regulated Power Supply Uses Low-Cost Diodes

A simple circuit was required to provide a regulated, temperature-stable, high-voltage dc supply for a fixed load. Methods using vacuum tubes, voltage-regulator tubes or high-voltage Zener-diode strings are elaborate and expensive.

The circuit shown in the figure uses inexpensive, low-voltage Zener diodes with



**Back-to-back** low voltage Zener diodes provide line regulation.

about 5 to 7-v breakdown voltages for 10-w dynamic impedance and low temperature coefficient. Zener diodes  $D_1$ ,  $D_2$  are placed back to back to operate on both halves of the input voltage.

The Zener voltages are multiplied by the

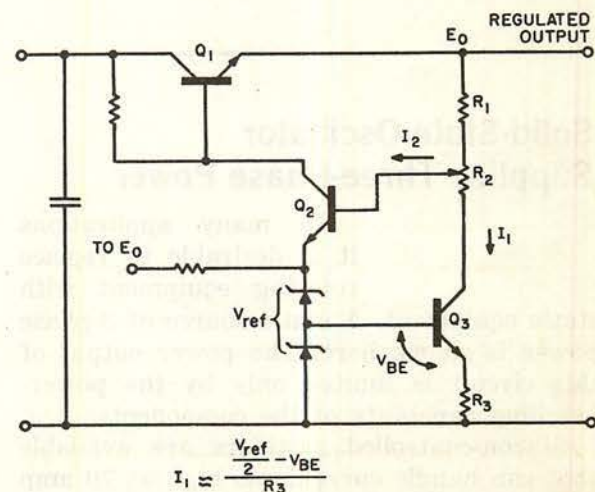
turns ratio between the primary and low voltage winding. This effectively places a high voltage, double-ending Zener diode in parallel with the primary winding, thus regulating the input voltage to the transformer. The output on the secondary will be a clipped sine wave, which will ease filtering problems. If ultra-low temperature variation is desired, the negative temperature coefficient of the Zener diode in the forward direction can be cancelled out by picking a Zener diode with a positive temperature coefficient in the reverse direction. To insure a minimum of tilt in the output, a transformer with good low-frequency response should be used.

*Joseph La Fiandra, project engineer, EDO Corp., Yonkers, N. Y.*

## Modified Regulator Is Made More Sensitive to Output Changes

In a conventional series regulator circuit, Fig. 1, a change in output voltage,  $\Delta E_o$ , is seen at the base of  $Q_2$  as  $\Delta E_o/n$ , where  $n$  is the voltage-division ratio determined by  $R_1 - R_2$  and  $R_3$ .

If  $n$  were to approach unity, the regulator would be much more responsive to  $\Delta E_o$ .



**Fig. 1.** In conventional series regulator, change in output voltage,  $\Delta E_o$ , is seen at base of  $Q_2$  as  $\Delta E_o/n$ , where  $n$  is voltage division ratio of  $R_1 - R_2$  and  $R_3$ .

## POWER SOURCES

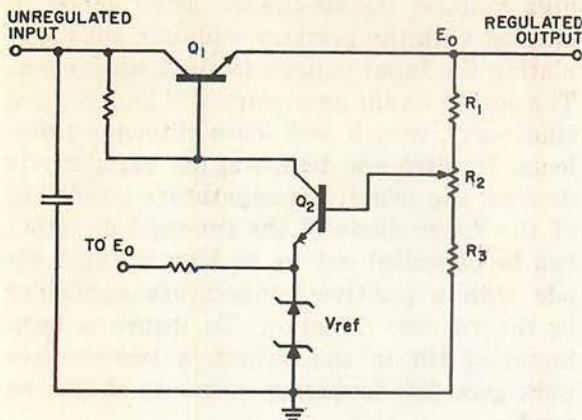


Fig. 2. Modified regulator allows  $n$  to approach unity so that regulator is more sensitive to changes in output voltage.

This can be done with the circuit shown in Fig. 2. The method is applicable to both vacuum tube and transistor series regulators.

In this circuit  $Q_3$  is a constant current source so that:

$$I_1 \gg I_2 \text{ and } I_1 \cong \frac{V_{ref}}{2R_3}$$

Since  $I_1$  is independent of  $E_o$ , a change in  $E_o$  or  $\Delta E_o$ , is seen at the base of  $Q_2$ . Thus, this circuit avoids the voltage division that is inherent in the series regulator of Fig. 1. This can also be accomplished by replacing  $R^1$  of Fig. 1 by a Zener diode. However, this would lead to temperature drift problems that are several orders of magnitude greater than the temperature drift associated with the circuit of Fig. 2.

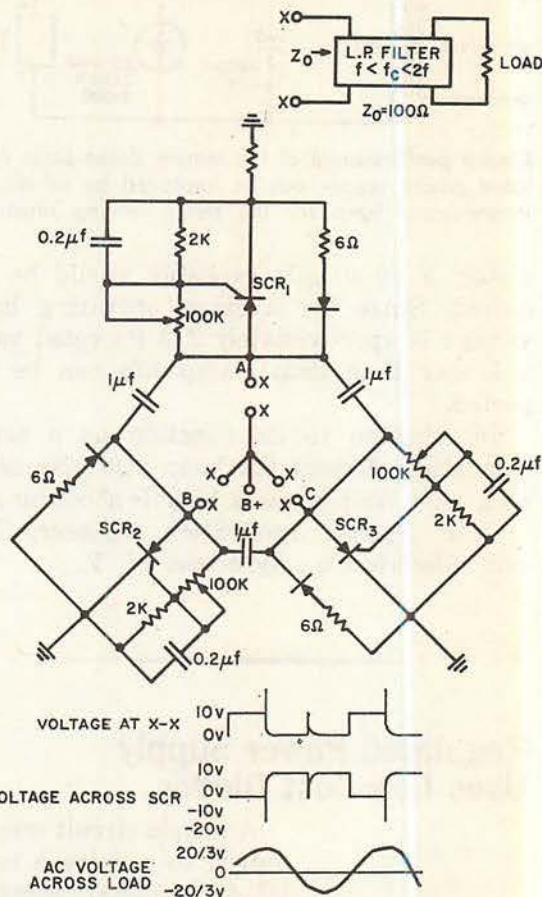
Marvin Shapiro, electrical engineer, Vector Manufacturing Co., Southampton, Pa.

## Solid-State Oscillator Supplies Three-Phase Power

In many applications it is desirable to replace rotating equipment with static equipment. A static source of 3-phase power is shown here. The power output of this circuit is limited only by the power-handling capability of the components.

Silicon-controlled rectifiers are available that can handle currents as high as 70 amp at 300 piv. Hence, it would appear that the upper limit on power-handling capacity of this circuit is 21 kw.

A one-watt oscillator was designed to test the technique. The filter and load at X-X were replaced with a 100-ohm resistor. The waveforms of one phase of the oscillator are as shown. The other phases were the same, except for a 120-deg phase shift. A slight



$$\text{FUNDAMENTAL: } \frac{20f}{\pi} \sin \frac{\pi}{3f} \cos 2\pi ft \cong \frac{20}{3} \cos 2\pi ft, f \gg 6\text{CPS}$$

Basic configuration of 3-phase power source with waveforms for one phase.

potentiometer adjustment was required to balance the circuit.

The delta capacitor arrangement causes commutation of the SCRs. When  $B+$  is applied, one of the SCRs will trigger on as the voltage on its gate capacitor charges sufficiently. Assume  $SCR_1$  is triggered on first. The voltage at points A, B and C will go to ground potential. The voltage at point A will remain at ground potential and point B and C will increase to  $B+$  potential. At this time one of the remaining SCRs—say  $SCR_2$ —will trigger on. If  $SCR_2$  triggers on, point B will go to ground potential. This will cause a negative potential to appear across  $SCR_1$ , turning it off. Just before  $SCR_2$  triggers on, B and C are at the same potential. When point B goes to ground, the charge on the capacitor

between *A* and *C* will redistribute between this capacitor and the capacitor between points *B* and *C*. Hence, just after *SCR*<sub>2</sub> triggers on, point *C* will be at the highest potential; therefore, *SCR*<sub>3</sub> will be the next to trigger on. After *SCR*<sub>3</sub> triggers on, which triggers *SCR*<sub>2</sub> off, *SCR*<sub>1</sub> will trigger on again. In this way each SCR will have a duty cycle of 1/3 and three-phase power will be generated. The filter before the load is a low-pass filter with a characteristic impedance of 100 ohms which passes only the fundamental and dc components of the voltage at X-X.

If the pots are adjusted accurately, the voltages across the three loads will be sinusoidal and 120 deg out of phase with respect to each other.

*William B. McCartney, Jr., engineer, Westinghouse Electric Corp., Baltimore, Md.*

## “Junk-Box” Current Limiter Protects Breadboard Equipment

One of the most discouraging aspects of electronics laboratory work is an accidental short circuit, thermal runaway or other mishap that causes damage or destruction of valuable components in a breadboard or other developmental circuit. Therefore, a current-limiting device that can be inserted between the output of any dc power source and a circuit under test often is desirable.

The circuit shown here is a simple current limiter, which can be used with any existing dc power source. Since it uses only four components, it can be assembled quickly in temporary form from junk-box parts.

Transistor *T*<sub>1</sub> is a germanium pnp unit and *D*<sub>1</sub> is a silicon diode. Approximate design equations are as follows.

$$I_{cf} = \frac{V_{D1} - V_{be}}{R_E}$$

$$R_B = \frac{V_{s(min)} H_{FE(min)}}{I_{cf}}$$

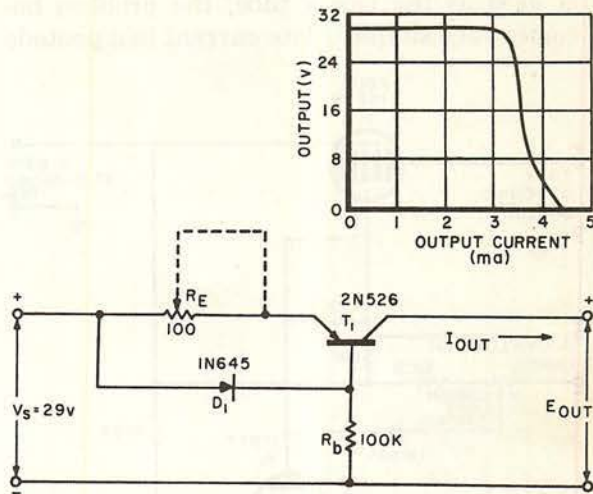
$$I_{C(max)} \geq I_{cf}$$

$$P_{C(max)} \geq V_{s(max)} I_{cf}$$

$$V_{CEO} \geq V_{s(max)}$$

where:

- $I_{cf}$  = output cutoff current.
- $V_{D1}$  = forward voltage drop of *D*<sub>1</sub>.
- $V_{be}$  = forward base-emitter drop of *T*<sub>1</sub>.
- $V_{s(min)}$  = minimum supply voltage.
- $V_{s(max)}$  = maximum supply voltage.



**Limiter circuit** and output characteristics using components and values as shown.

If a potentiometer is used for *R*<sub>E</sub>, a continuously variable cutoff current will be available. By connecting an ammeter across the output and applying an input voltage, *R*<sub>E</sub> can be calibrated directly in  $\mu$ a, ma, or amperes.

The lower limit on cutoff current is the *I*<sub>CBO</sub> of the transistor used. The output impedance of the circuit before cutoff is equal to *R*<sub>E</sub> + *R*<sub>sat</sub> where *R*<sub>sat</sub> is the saturation impedance of *T*<sub>1</sub>.

This circuit also makes a handy current source for one-shot timing applications and other uses.

*Donald A. Boelter, associate engineer, Martin-Marietta Corp., Baltimore 20, Md.*

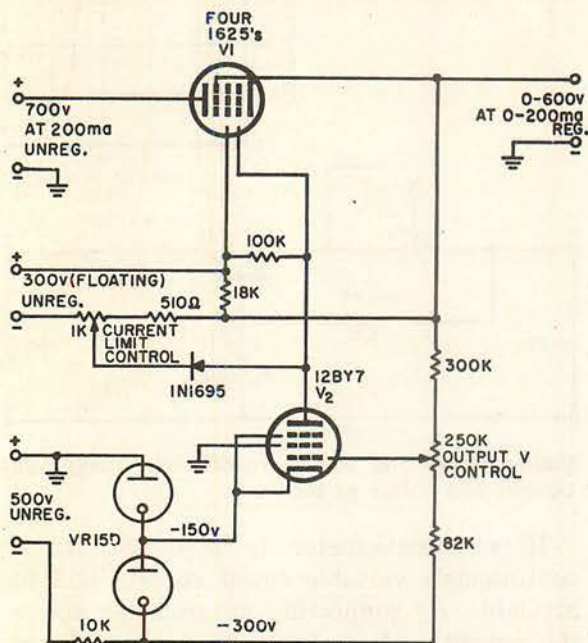
## Pentode Replaces Triode For Current-Limiting in Tube Supply

Current-limiting is a rather common feature of transistorized laboratory power supplies. But it is rather difficult to achieve in a series-regulated vacuum tube

## POWER SOURCES

supply. This is because it is difficult to sense load current, necessary to bring about current limiting, in this type of supply.

But if a pentode instead of the usual triode is used as the series tube, the problem becomes very simple. Plate current in a pentode



**Current-limiting** is introduced in vacuum tube supply by using a pentode instead of the usual triode series tube. The control grid of the pentode is clamped with a diode so that its bias is held above a minimum value.

depends primarily upon control grid voltage. Even if the plate voltage should increase greatly, the plate current rises very little. If the control grid is clamped with a diode so grid bias cannot be reduced beyond a set value, the tube automatically will go into current limiting.

Such a supply was built using transmitting pentodes for the series tubes to permit high plate dissipation. Low resistances were used in series with the control grid and the screen grid leads of each tube for parasitic suppression. They also were placed in the cathode of each tube for current equalization.

In the circuit shown in the figure, as load current increases, the output voltage drops slightly.  $V_2$  senses this drop and counteracts it by raising the voltage applied to the grid of  $V_1$ . This is the normal operation of a voltage regulator.

However, when load current reaches the current limit value, the grid of  $V_1$  is stopped from going higher by the conduction of the

silicon diode. This clamps the grid-to-cathode voltage of  $V_1$  to a preset bias, and current limiting begins.

*Herbert Zimmerman, development engineer, Wilcox Electric Co., Kansas City, 27, Mo.*

## Standby Batteries Protect Supply Against AC Power Loss

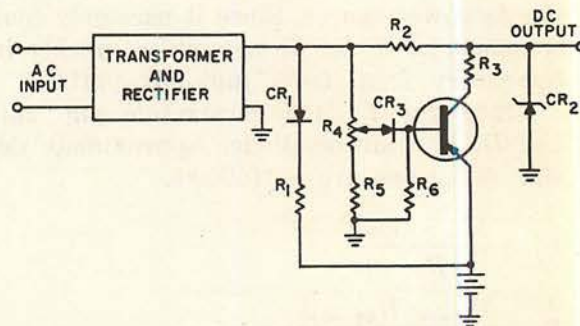
We had to design a power supply that could "ride out" a loss of ac power.

The simplified circuit shown in the figure served us perfectly.

Zener diode  $CR_2$  and resistor  $R_2$  form a simple shunt regulator. With line voltage applied, the rectifier supplies regulator current and holds transistor  $Q_1$  cut-off through the base-biasing network of  $R_4$ ,  $R_5$ ,  $R_6$ , and  $CR_3$ . Decreasing line voltage drops the base potential and the transistor begins to conduct. Thus, the batteries, through  $R_3$ , furnish the regulator current which would normally be lost on reduced input voltage.

When a total loss of ac voltage occurs, the transistor saturates and the batteries carry the entire load.  $CR_1$  and  $R_1$  form a charging network that keeps the batteries charged as long as line voltage is available.

In our system the dc voltage output varies less than 0.2 per cent over the range of 0-130 v rms input.



**When a total loss** of ac input voltage occurs, the transistor saturates and the standby batteries carry the entire load.

*G. Douglas McKinley, development engineer, Forney Engineering Co., Dallas, Tex.*

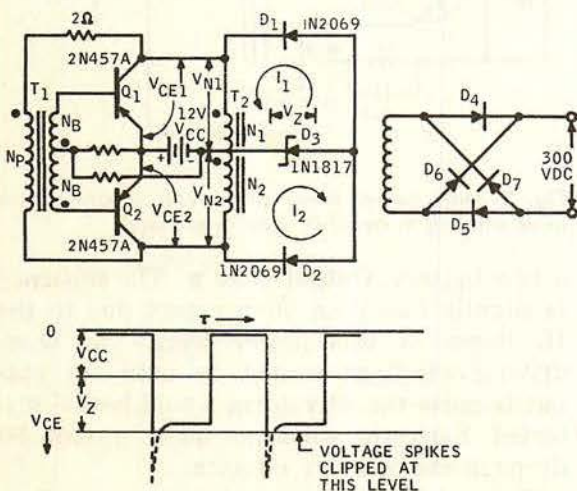


## Transient Clipper For DC Converters

In a dc converter, as shown, each transistor is ideally subjected to twice the supply voltage  $V_{CC}$  when in the OFF condition. For example, if  $Q_1$  is conducting, the induced voltage across  $N_2$  will be equal to  $V_{CC}$  and will add to the supply voltage so that  $V_{CE2} = -2V_{CC}$ .

However, due to leakage inductance in the power transformer, this situation is not always realized. When the transistor switches off, the sudden change in current through any leakage inductance in the collector circuit will result in a high voltage spike appearing from collector to emitter on the OFF transistor. This spike may be several times the supply voltage and may exceed the voltage breakdown rating of the transistors.

The method suggested here suppresses these transients. Assume  $Q_1$  is conducting and  $Q_2$  is off. Voltage  $V_{CE2}$  will be equal to the supply voltage plus any voltage that is induced in  $N_2$ . Zener diode  $D_3$  is chosen to have a breakdown slightly above the supply voltage. When  $V_{N2}$  tends to exceed  $V_Z$ , the Zener diode breaks down causing a current  $I_2$  to flow as shown. This results in  $V_{N2}$  being clamped at approximately  $V_Z$ , thereby maintaining  $V_{CE}$  at a level within the transistor rating. Transistor  $Q_1$  is protected in a like manner against voltage spikes in  $N_1$  through current path  $I_1$ . Diodes  $D_1$  and  $D_2$  prevent a reverse flow of currents  $I_1$  and  $I_2$ , which would otherwise



Single Zener clipping diode removes waveform spikes.

short the windings  $N_1$  and  $N_2$ , and the applied voltage  $V_{CC}$  alternately appears across them.

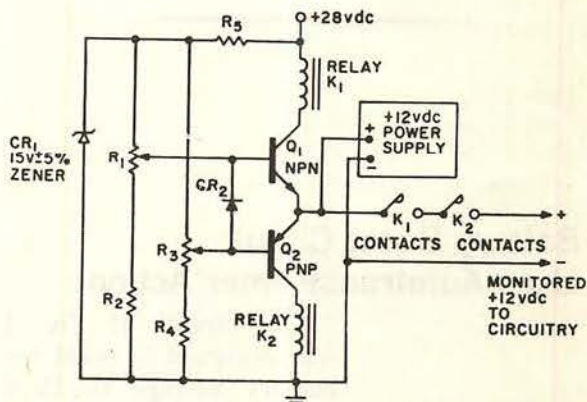
This system offers an advantage of lower cost over systems where two Zener diodes are used. Another advantage is better control over clipping level. Since Zener tolerance is based on a percentage of voltage rating, closer clipping can be achieved here as tolerance is a percentage of  $V_{CC}$  and not  $2V_{CC}$ .

A small capacitor may be placed across  $D_3$  to help clip the leading edge of very fast rising voltage transients. It is generally not required that diodes  $D_1$  and  $D_2$  have fast recovery times since the transient voltage in this type of circuit lasts for only a small percentage of the period of oscillation. Typical circuit components are shown in Fig. 2a.

*Paul Vergez, Transistor Products Div., Texas Instruments Inc., Dallas, Tex.*

## Voltage, Current Limiter Protects Circuitry From Shorts and Overs

Laboratory breadboards can be protected from shorts and over-voltages by connecting the circuit shown in the figure across the output of the power source. The circuit is quite useful when transistorized circuitry, easily damaged by high voltages or currents, is being tested. Because it is designed to have adjustable limit settings,



Circuit connected across power supply outputs removes power to test circuitry if shorts or over-voltages occur.

## POWER SOURCES

the circuit can be used for different applications.

In normal operation, transistors  $Q_1$  and  $Q_2$  are conducting and relays  $K_1$  and  $K_2$  are energized. The relay contacts are closed and the load will receive +12 v dc. Tolerances around +12 v are set by potentiometers  $R_1$  and  $R_3$ .  $R_1$  is set for the high voltage limit and  $R_3$  for the low voltage (short circuit) limit.

If the power supply should suddenly produce an over-voltage, transistor  $Q_1$  will be turned off, de-energizing relay  $K_1$  and opening the  $K_1$  contacts. If the load should suddenly short, transistor  $Q_2$  will be turned off, de-energizing relay  $K_2$  and opening the  $K_2$  contacts.

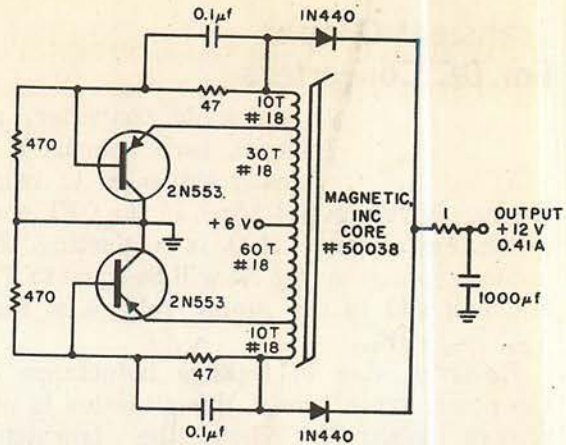
Resistors  $R_2$  and  $R_4$  prevent overdriving  $Q_1$  and  $Q_2$ ;  $CR_2$  prevents reverse-biasing the transistors more than about 1 v. Zener diode  $CR_1$  provides a stable reference voltage.

For fast operation, relays  $K_1$  and  $K_2$  should be mercury-wetted contact relays similar to the C. P. Clare HGS series. These relays permit 2 msec drop-out times that are compatible with transistor thermal time-constants. With the Clare relays and military components, the MTBF of the circuit is about 12,000 hours.

*Cecil R. Frost, senior project engineer, Canoga Electronics Corp., Van Nuys, Calif.*

### Battery Boost Circuit Uses Autotransformer Action

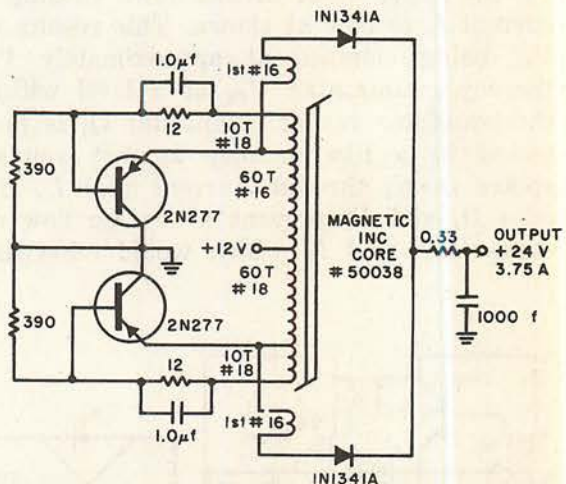
The circuit of Fig. 1 was designed to boost 6-v battery voltage to 12 v at about 5-w output. Since no secondary winding is used and the collectors are grounded, the circuit is very simple and can be



**Fig. 1.** High efficiency is obtained in battery boost circuit by permitting battery to supply half of the voltage directly.

constructed in a very small space. An efficiency of 90 per cent is obtained because the dc-to-dc converter is essentially in series with the battery. Battery voltage appears at the output even when the converter is disabled.

The circuit has been used in a 6-v automobile to power a 12-v radio. The circuit of Fig. 2 provides higher power to operate a 24-v image-orthicon television camera on



**Fig. 2.** High power boost circuit uses separate base drive winding to avoid IR drop in primary.

a 12-v battery. Output is 90 w. The efficiency is slightly less than 90 per cent due to the IR losses at this power level. The base-driving windings cannot be used for output because the waveform would be too distorted. Separate windings make up for IR drops in the primary circuits.

*Howard F. Stearns, project engineer, General Electric Co., Syracuse, N. Y.*

## Inexpensive DC-to-DC Converter Operates Without Rectifier Diodes

Most dc-to-dc converters use two transistors, a transformer and rectifier diodes. The converter circuit shown in Fig. 1 uses a single transistor, which serves as both oscillator and rectifier.

The load and its shunting capacitor bias the transistor off. The transistor therefore is turned on for only a small angle in each cycle. A conversion efficiency of 70 per cent has been attained for a 5-to-1 (3 v-to-15-v) step-up at an operating frequency of 100 kc.

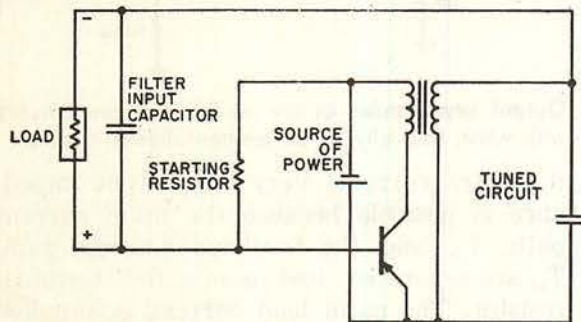


Fig. 1. Transistor acts as oscillator and rectifier in dc-to-dc converter.

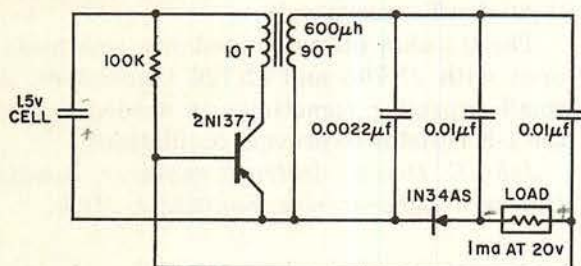


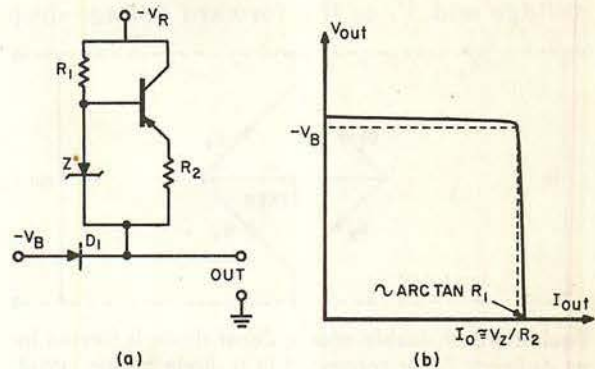
Fig. 2. Base-to-emitter diode provides full-wave doubling for higher step-up ratios.

For higher step-up ratios, or where the load voltage would exceed the base-to-emitter avalanche potential in the circuit of Fig. 1, the modified circuit of Fig. 2 is useful. Here, the base-emitter diode serves in a full-wave doubler. This circuit has been used to supply 20 v at 1 ma when driven by a pen-light cell.

W. R. Kundert, development engineer, General Radio Co., Concord, Mass.

## Simple Current-Limited Voltage Source

During the experimental stages of a circuit design it sometimes is convenient to use individual current-limited voltage sources for some critical stages—for instance a transistor stage containing only a transformer in its collector circuit.



Current-limited voltage source (a) provides output characteristic at (b).

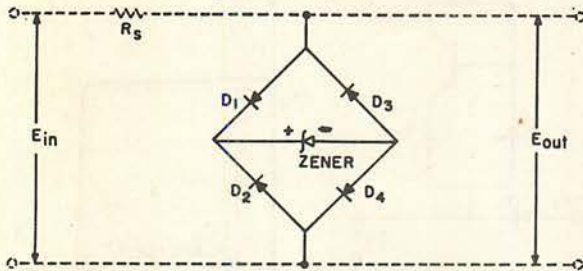
The circuit consists of a constant-current generator (transistor, Zener diode and resistors  $R_1$  and  $R_2$ ) and a catching diode biased by the voltage  $-V_B$ .

If the current required by the load is less than that supplied by the constant-current generator diode  $D$  conducts. Hence the output voltage is slightly less than  $-V_B$  and the output impedance is equal to the differential resistance of the diode  $D$ . However, if the current required by the load equals or exceeds the current supplied by the constant-current generator, the diode  $D$  is cut off and the output impedance of this device increases rapidly to that of the constant-current generator.

Zvi Netter, research engineer, Ministry of Defense, Hakiryia, Tel Aviv, Israel.

## Zener, Diode Bridge Form Double-Ended Clipper

A symmetrical double-anode Zener diode equivalent can be constructed very simply by using an ordinary Zener and a diode bridge circuit. The output voltage is equal to  $\pm (V_Z + 2V_f)$  where  $V_Z$  is the Zener voltage and  $V_f$  is the forward voltage drop



Equivalent of double-anode, Zener diode is formed by an ordinary Zener connected in a diode bridge circuit.

of the diodes. The output waveform is almost perfectly symmetrical since both positive- and negative-going voltages are clipped by the same Zener. If extreme symmetry is required,  $D_1$  and  $D_2$  and  $D_3$  and  $D_4$  can be matched diode pairs.

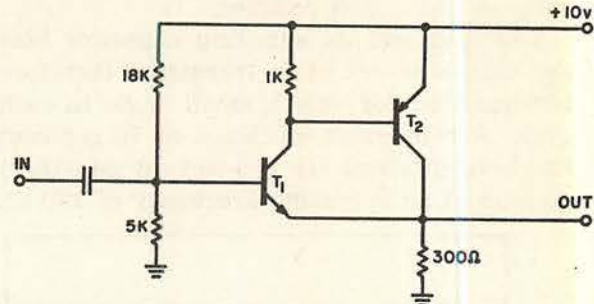
*Donald A. Boelter, associate engineer, Martin-Marietta Corp., Baltimore, Md.*

## Modified Emitter Follower Has Very Low Output Impedance

Low output impedances often are obtained from a transistor amplifier by using an emitter-follower output stage. For very low impedances, two emitter followers in cascode may be used. But the output impedance of any emitter follower is limited by the properties of the transistors. For example, with the much-used 2N706, the output impedance will not go below about 3 ohms with double or even triple emitter followers.

With the circuit shown, however, we were able to overcome this limitation and operate with a measured output impedance of less than 0.1 ohm.

Transistor  $T_1$  operates as an ordinary emitter follower;  $T_2$  "helps"  $T_1$  by supply-



Output impedances as low as 0.1 ohm are possible with what, basically, is an emitter-follower circuit.

ing extra current. Very low output impedance is possible because the main current path,  $T_2$ , and the feedback sensing path,  $T_1$ , are separated, just as in a four-terminal resistor. The main load current is supplied by the collector of  $T_2$ .  $T_1$  senses the difference between input and output voltage and regulates  $T_2$  accordingly.

The 0.1-ohm output impedance was measured with 2N706 and 2N726 transistors. A small capacitor sometimes is needed across the 1-K resistor to prevent oscillations.

*John K. Dixon, electrical engineer, Bendix Research Laboratories, Southfield, Mich.*

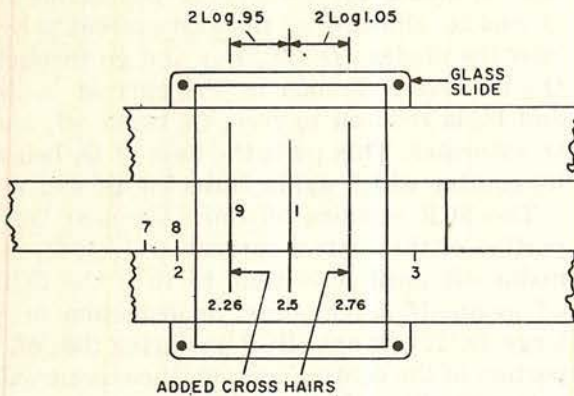
## Component Tolerance Calculator Can Be Built Into Your Slide Rule

When calculating the worst-case conditions of a circuit it is often necessary to multiply or divide parameters with their tolerances and to obtain the extreme values of the result. But, by adding two cross hairs to the glass slider of the slide rule, the extremes may be read at the same time as the nominal value.

The extra lines are placed according to the principle that moving along a log scale a fixed distance is the same as multiplying or dividing by a constant factor.

For 5 per cent components one cross hair is located at twice the distance from the index to 1.05 and the other is located at twice the distance from the index to 0.95.

For 10 per cent components the same slider may be used on the *A* and *B* scales.



**Added cross hairs** drawn on glass slide are placed to indicate extreme values when divided numbers have  $\pm$  tolerances. Illustration shows settings for  $2 \pm 5\%$  /  $8 \pm 5\%$ .

A slider scale calibrated at log 1.02, 1.04, 1.06, etc., would be more useful. The answer tolerance would be read at the line indicating the sum of the component tolerances.

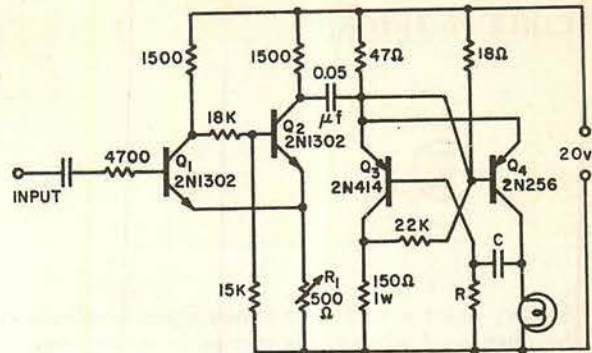
To use this device the calculation is performed with the nominal values. Then, with the slider hair line on the answer, the extreme values appear under the added cross hairs.

*Bruce Ross, associate research engineer, The Boeing Co., Seattle, Wash.*

## Schmitt Circuit Monitor Triggers on Overloads

A simple overload alarm was needed to give a visual signal when the output of an amplifier exceeded a certain limit. The circuit shown was designed to work in the range of from 1 to 6 v rms.

Transistors  $Q_1$  and  $Q_2$  form a conventional Schmitt trigger with  $Q_2$  conducting and  $Q_1$  cut off. The emitter of  $Q_1$  is at a potential determined by the current flowing in the common emitter resistor  $R_1$ . When



**Overload alarm** with 10-mv sensitivity uses Schmitt trigger circuit driving multivibrator.

the input voltage does not exceed this level, the alarm presents to the source a very high impedance (that of the reverse-biased base-emitter diode of  $Q_1$ ). When the peak of the ac signal exceeds the emitter bias of  $Q_1$ , the circuit is triggered, providing a positive pulse at the collector of  $Q_2$ . This pulse is coupled to the one-shot multivibrator formed by  $Q_3$  and  $Q_4$ . The alarm lamp is the collector load of  $Q_4$  which normally is cut off. If the period of the one shot (determined by  $R$  and  $C$ ) is chosen close to the period between successive peaks of the input waveform, the lamp will remain lit as long as the limit is exceeded and stay out at all other times. These sensitivity is about 10 mv.

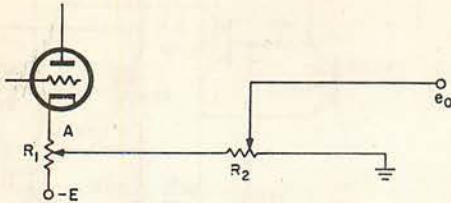
*Bill Gutman, project engineer, Kearfott Div., General Precision, Inc., Clifton, N. J.*

## Amplitude Control in DC-Coupled Circuit Holds DC Level Constant

Usually if a potentiometer is used to pass on an amplitude variation in a dc-coupled amplifier, the average dc level will also change. To prevent this the arrangement shown in the figure has proved to be quite effective.

Point *A* is varied until it is at 0 v dc. Then any variation in  $R_2$  will only affect the amplitude of the ac signal and not the dc level.  $R_2$  can be much larger than  $R_1$  so that the full amplitude at the cathode can

## CIRCUIT TRICKS



**Setting point A** to 0 v dc allows signal amplitude to be attenuated without any change in its dc level.

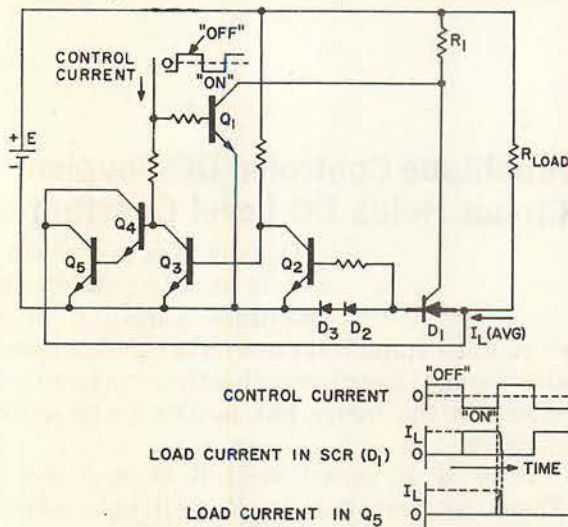
be utilized. However, the designer must choose between the increased output impedance and the larger useful amplitude.

*Irving Bayer, senior member, technical staff, Radio Corp. of America, New York, N. Y.*

## Shorting Transistor Reduces SCR Turn-Off Time

Silicon-controlled rectifiers have not been used extensively in dc circuits because of the difficulty in turning them off. But an SCR can be turned off efficiently by shorting it with a transistor for the brief period required to turn it off.

In the circuit shown in the figure, control current is fed into the bases of transistors  $Q_1$  and  $Q_4$ . When the "on" portion of the control current flows,  $Q_1$  is off and allows gate current through  $R_1$  to the SCR,  $D_1$ . Transistors  $Q_4$  and  $Q_5$  are also off, so that the entire



**Silicon-controlled** rectifier is turned off rapidly by shorting it with a transistor,  $Q_5$ , during the brief turn-off transition.

load current passes through  $D_1$ ,  $D_2$ , and  $D_3$ . The voltage drop across  $D_2$  and  $D_3$  is used to saturate  $Q_2$ . This blocks any base current to  $Q_3$ .

When the "off" portion of the control current flows, it saturates  $Q_1$ , which cuts off gate current to the SCR. The control current also saturates the Darlington connection of  $Q_4$  and  $Q_5$ , allowing all the load current to bypass the diodes ( $D_1$ ,  $D_2$ ,  $D_3$ ) and go through  $Q_5$ . However, as soon as the current in  $D_2$  and  $D_3$  is reduced to zero,  $Q_2$  turns off, and  $Q_3$  saturates. This pulls the base of  $Q_4$  below its emitter which again turns off  $Q_4$  and  $Q_5$ .

The SCR remains off until the next "on" portion of the control current arrives.  $Q_5$  remains off until it is time to turn the SCR off again. If a temporary malfunction or a large  $dv/dt$  turns the SCR on during the "off" portion of the control current, the circuit will automatically turn the SCR off.

A typical turn-on time for a high current SCR is  $0.5 \mu\text{sec}$ , while a typical turn-off time is  $5.0 \mu\text{sec}$ . Transistor  $Q_5$  handles only a small fraction of the total load current while the SCR does most of the work. Thus, high switching rates can be realized without dissipating a great deal of power in  $Q_5$ . Since the SCR is either off or on, it also dissipates very little power.

It might be noted that insulation hardware for  $Q_5$  and  $D_1$  is not necessary if the circuit is grounded to the chassis at the anode of  $D_1$ .

*D. K. Phillips, Member of the Technical Staff, Hughes Aircraft Co., Culver City, Calif.*

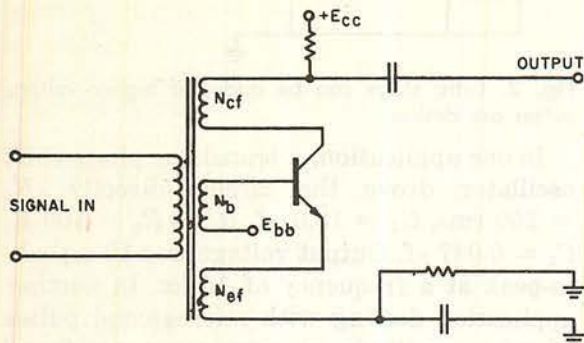
## Positive, Negative Feedback Combine to Reduce Noise

Negative feedback does not reduce collector noise because both signal and noise are decreased proportionately. Positive emitter feedback may be helpful but results in signal instability.

The circuit in Fig. 1 combines positive emitter feedback with negative collector feedback in equal proportions. Consequently, the signal amplification is unchanged, but the collector noise is reduced by

$$\beta \left( \frac{N_{cf}}{N_b} \right)$$

where  $\beta$  = forward current transfer ratio,  
 $N_{cf}$  = number of turns on collector feedback



**Positive emitter feedback** and negative collector feedback combined reduces noise figure while retaining good signal amplification.

winding, and  $N_b$  = number of turns on the base winding.  $N_{ef}$  in Fig. 1 represents the number of turns on the emitter feedback winding.

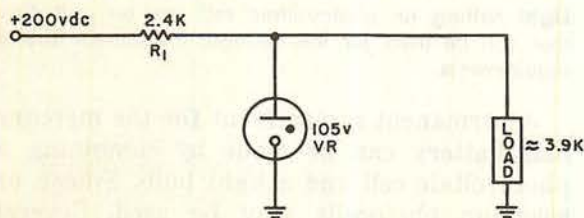
In this circuit, there is no need to isolate the dc component of the feedback currents because their effects in the transformer cancel.

*Kermit Norris, technician, General Dynamics, Pomona, Calif.*

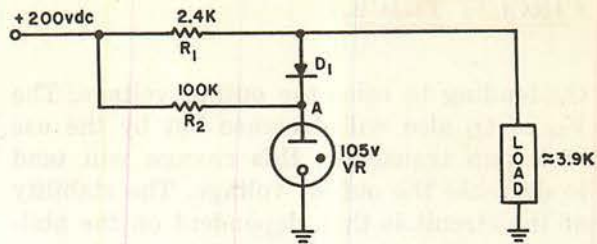
## VR Tube, Removed From Load, Is Fired By Source

Occasionally, a voltage regulator tube will not be able to fire because there is insufficient potential across its terminals. Such a situation is present, for example, in the circuit of Fig. 1.

A solution to the problem is shown in Fig. 2. A silicon diode  $D_1$  disconnects  $R_1$



**Fig. 1.** VR tube will not fire because circuit does not put sufficient potential across its terminals.



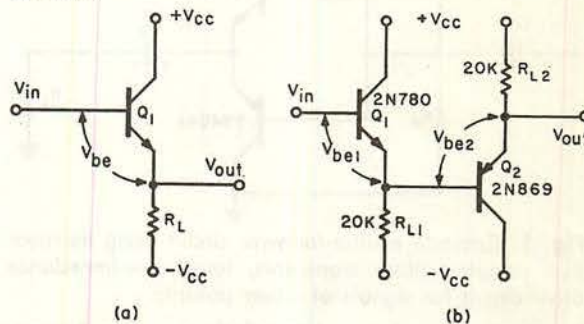
**Fig. 2.** Added diode  $D_1$  disconnects VR tube from load, fires it directly from source.

and the load from point A until the VR is fired by the potential applied through  $R_2$ . The circuit then operates in the normal manner except for about a 0.5-v increase in the regulated voltage because of the drop across  $D_1$ .

*Matt Cousins, electrical engineer, Airtronics Inc., Washington, D. C.*

## Temperature-Stabilizing Emitter Followers

There are many applications in instrumentation systems for emitter followers. The conventional emitter follower in Fig. 1a has two problem areas when used in dc-circuit applications. These are: an inherent drift with temperature produced by variations in the base-to-emitter voltage ( $V_{be}$ ), and a dc offset equal to the base-to-emitter voltage. The temperature stabilized emitter follower of Fig. 1b provides a simple but effective method of reducing both effects.



**Fig. 1.** Basic emitter follower (a) is temperature-stabilized by addition of opposite-polarity stage (b).

The principle of operation of the temperature-stabilized emitter follower is based on the cancellation of the base-to-emitter voltage ( $V_{be}$ ) of the first stage by an equal, but opposite polarity, base-to-emitter voltage in the second stage. An increase in temperature will produce a decrease in  $V_{be}$  of

## CIRCUIT TRICKS

$Q_1$ , tending to raise the output voltage. The  $V_{be}$  of  $Q_2$  also will decrease but by the use of a pnp transistor, this change will tend to decrease the output voltage. The stability of the circuit is then dependent on the ability of the base-to-emitter voltage of the two transistors to track over an extended temperature range.

A series of tests has been conducted using 2N780 transistors as  $Q_1$  and 2N869 transistors as  $Q_2$ . The maximum drift obtained over the temperature range of 20 F to + 200 F was 30 mv, with the average drift about 25 mv. The transistors used in this test were randomly selected and no attempt was made to match transistor characteristic.

*M. H. Schmidt, instrumentation engineer, McDonnell Aircraft Corp., Florissant, Mo.*

## Dual-Polarity Signal Drive Uses Cascode Emitter Follower

To provide a low-output impedance drive circuit for signals of either polarity, we connected complementary transistors, as shown in Fig. 1. This circuit has a low current drain and can use inexpensive transistors. The pnp and npn transistors

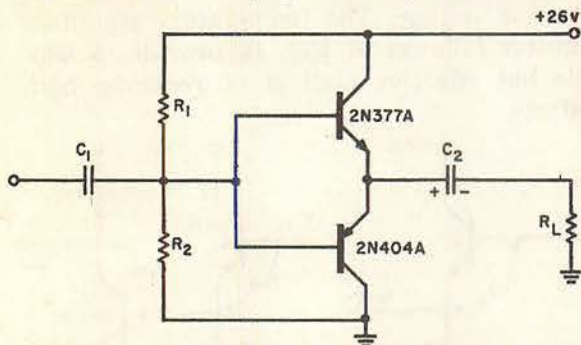


Fig. 1. Cascode emitter-follower circuit using inexpensive complementary transistors, forms low-impedance drive circuit for signals of either polarity.

form a cascode emitter-follower configuration in which they cut each other off, drawing a negligible amount of quiescent current.

A signal of either polarity, swinging around the bias determined by voltage dividers  $R_1$  and  $R_2$ , causes the respective transistor to conduct. This shuts off the other transistor even more, and all the current flows to the load  $R_L$  through  $C_2$ .

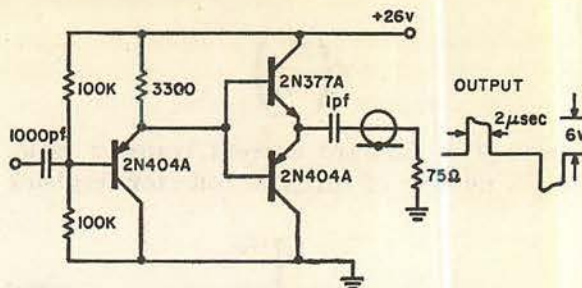


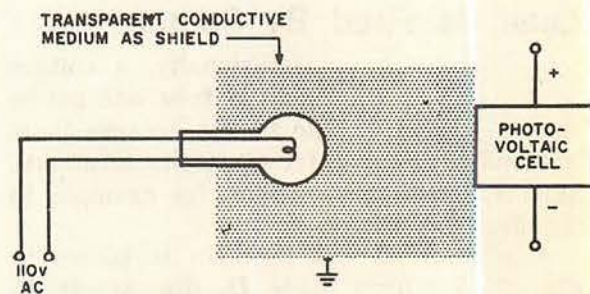
Fig. 2. Extra stage can be added if higher voltage pulses are desired.

In one application, a transistor phase-shift oscillator drove the circuit directly:  $R_L = 200$  rms,  $C_2 = 10.0$   $\mu$ f,  $R_1 = R_2 = 100$  K,  $C_1 = 0.047$   $\mu$ f. Output voltage was 10 v peak-to-peak at a frequency of 10 kc. In another application dealing with microsecond pulses of  $\pm 6$  v amplitude, an extra stage was found desirable, Fig. 2.

*Gunnar Richwell, staff engineer, Reflectone Electronics Inc., Stamford, Conn.*

## Lighted Photocell Replaces Mercury Bias Battery

Requirements in electronics equipment for low-voltage, low-current biasing sources are met, when convenient, with mercury batteries. Their great disadvantage is that they must be periodically replaced. The alternative of a transformer-rectifier-Zener diode combination is relatively bulky and expensive.



Light falling on photovoltaic cell sets up potentials that can be used for low-voltage, low-current source requirements.

A permanent replacement for the mercury bias battery can be made by combining a photovoltaic cell and a light bulb. Silicon or selenium photocells may be used. Several cells may be connected in series for increased voltage. Combination light-photovoltaic cell

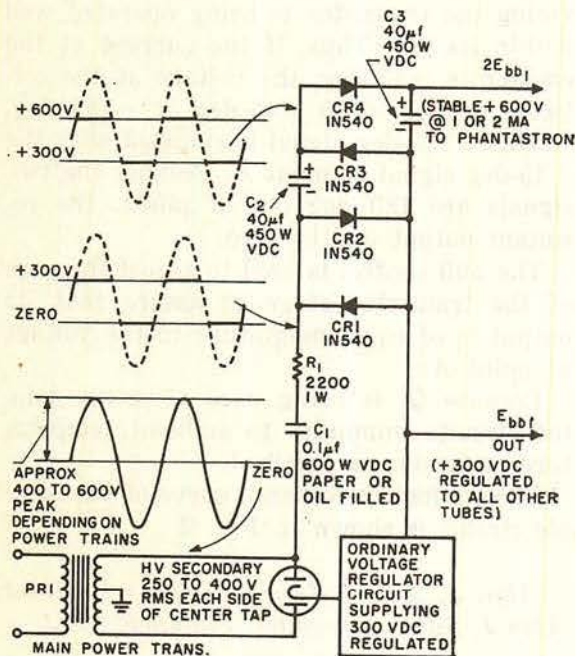


units can be made for this purpose, analogous to the light-photoresistor combinations that are now commercially available.

*Dr. F. W. Cope, research scientist, Aviation Medical Acceleration Laboratory, Naval Air Development Center, Johnsville, Pa.*

## Regulator-Doubler Eliminates Need for Second Power Supply

Design of a vacuum-tube circuit included one phantastron-type stage to generate a timing sawtooth having a peak-to-peak amplitude of 500 v. This stage required stable B+ voltage of +600 v at a current of approximately 1 ma. The remainder of the tubes in this chassis required only +300 v, which was being supplied by a regulated power supply circuit of ordinary design. The accompanying schematic shows a "regulated voltage-doubling circuit" used to supply the required 1 or 2 ma at +600 v to



**Regulating doubler** provides high voltage at low current eliminating need for second power supply.

the phantastron only. This eliminated the need for an additional regulated power supply in the design.

Diodes  $CR_1$ ,  $CR_2$ ,  $CR_3$ ,  $CR_4$  and capacitors  $C_2$  and  $C_3$  need withstand only 300 v.  $C_1$  must withstand the peak value of the ac

voltage across half of the secondary winding.  $R_1$  was included to limit the surge current during the turn-on transient. A much lower resistance value—perhaps 47 ohms—would probably be satisfactory for most applications.

A bleeder resistor (now shown) of about 1 megohm may be desirable for safety reasons in some applications. If used, it may be connected in parallel with  $C_3$ .

This circuit is quite efficient because it does not employ a power-dissipating principle to accomplish its voltage-regulating function. It does not, therefore, contribute to the chassis heat-dissipation problem.

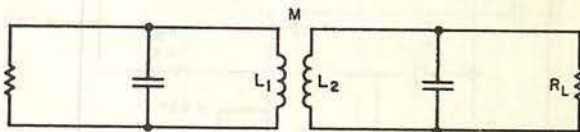
*James W. Carroll, staff member, Sandia Corp., Albuquerque, N. M.*

## Low Impedance Line Driver Uses Standard Coils

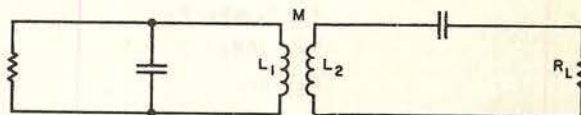
Frequently, a terminated cable must be driven from a wideband if source.

The optimum matched condition for this calls for an equal-Q, transitionally-coupled stage.

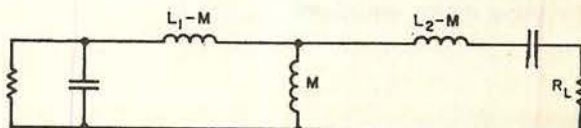
To achieve equal-Q loading under conditions of low load impedance, it is usually



**Fig. 1.** If shunt capacity is required in a transformer secondary to achieve equal-Q loading with a low load impedance, negative values of  $M$  may be required in the Tee-transform of the circuit.



**Fig. 2.** With a series-tuned circuit in the secondary,  $L_2$  will be much greater than  $M$ .



**Fig. 3.** The result of series tuning is that standard, not negative, coils are present in the Tee-transform circuit.

## CIRCUIT TRICKS

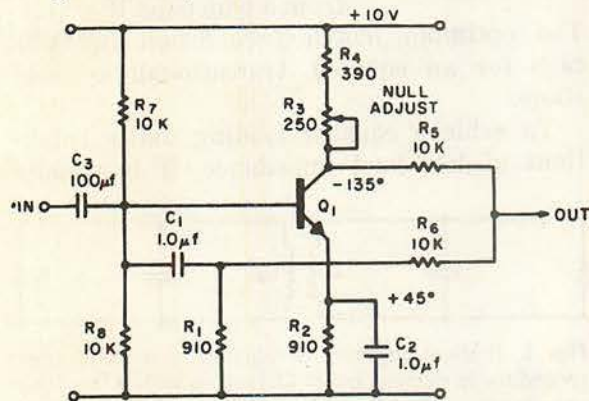
necessary to load the transformer secondary with shunt capacity as in Fig. 1. This reduces the value of the secondary inductance  $L_2$ . For values of  $L_2$  less than  $M$ , a negative value of  $M$  is required in the Tee-transform of the circuit.

However, if a series-tuned circuit of the same  $Q$  is used in the secondary, Fig. 2, values of  $L_2$  much larger than  $M$  are obtained. This allows standard coils to be used in the Tee-transform of the transformer, as in Fig. 3.

*Martin E. Doyle, design group supervisor, Raytheon Co., Airborne Operation, Sudbury, Mass.*

## Novel Notch Filter Is Easy to Tune for Null

Unlike a bridged-T or parallel-T circuit, the 185-cps notch filter shown in Fig. 1 is simple to tune for a minimum null,



### DESIGN EQUATIONS

$$R_1 = \frac{1}{\omega C_1} \quad (\omega = \text{CUTOFF FREQUENCY})$$

$$R_2 = \frac{1}{\omega C_2}$$

$$R_4 \approx \frac{R_2}{2}$$

$$R_3 \approx \frac{R_2}{4}$$

$$R_5 = R_6 \approx R_7 = R_8$$

$$R_5 \approx 10R_2$$

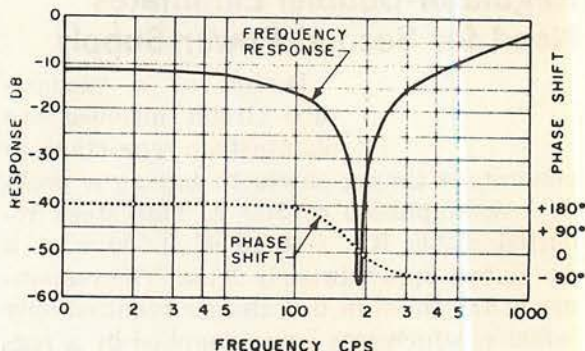
$$C_3 > 10C_1$$

**Fig. 1.** Circuit gives component values for 185-cps notch filter. Other notch frequencies can be obtained by using design equations.

and does not require close tolerance components.

The  $X_c$  of  $C_1$  is equal to  $R_1$  at the rejection frequency, providing a 45-deg voltage lead at point A.

The  $X_c$  of  $C_2$  equals  $R_2$  at the rejection frequency, providing a 45-deg current lead at the emitter of  $Q_1$ . The voltage at the collector of  $Q_1$  will always be 180 deg out



**Fig. 2.** Response and phase shift for 185-cps notch filter.

of phase with the current at the emitter, providing the transistor is being operated well within its  $f_{hfe}$ . Thus, if the current at the emitter is +45 deg, the voltage at the collector will be  $-180 + 45$  deg or  $-135$  deg.

This  $-135$ -deg signal is summed with the +45-deg signal at point A. Because the two signals are 180 deg out of phase, the resultant output will be zero.

The null control is used to adjust the gain of the transistor stage to assure that its output is of equal magnitude to the voltage at point A.

Because  $Q_1$  is being used at unity gain, the circuit's immunity to ambient temperature variations is excellent.

The frequency response curve of the sample circuit is shown in Fig. 2.

*Alan J. Adler, circuit design consultant, Alan J. Adler Associates, Plainfield, N. J.*

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